Reply to Anonymous Referee #2

General
The paper deals with an important topic of atmospheric research: The retrieval of CCN from multiwavelength backscatter and extinction lidar observations. New aspects are integrated (e.g., using the increase in backscatter and extinction coefficient with relative humidity, humidogram approach). This is an excellent idea!

However, the paper has to my opinion almost no structure. Although one gets an idea how the method may work, a well-elaborated and well-structured description of the methodology is completely missing. A huge amount of information on microphysical and chemical particle properties, simulated related optical effects, dependence of optical effects from increasing humidity (growth factors), etc. and respective experimental data from field observations in the North China Plain (NCP) are just accumulated in different sections, but the reader must already be an expert in this field to get an idea how all this may fit together.

So, the manuscript is far from being acceptable. To be short: to my opinion it cannot be published in the present version and must be rejected. In the following, I will give more detail so that the authors may get an idea how to change the structure of the manuscript and then resubmit it.

A manuscript with clear goals, clear structure, an easy-to-follow methodology, plus uncertainty analysis, and also some convincing but simple case studies are required.

Response:
Thanks for your suggestions. The structure of the paper has been rearranged and some additional explanations have been added according to your valuable suggestions. The retrieval algorithm is now presented at the beginning of Sect. 3 step by step. We also give explanations to the data we used in this study before we introduce the data. All of the comments and concerns raised by the referee have been explicitly replied point by point and incorporated into the revision.

An important issue is also: Please do not consider NCP aerosol only. It would be nice to have a general methodology that can be applied to anthropogenic haze and smoke, to dust aerosol, and may be to aerosols dominated by marine sea salt. All the required kappa values and growths factors are available in the literature. You do not need to focus on NCP aerosol!

Response:
Thanks for the valuable suggestions. We hope to propose a complete methodology as well. This paper is a very preliminary job. The main goal of our paper is introducing the idea of using backscatter and extinction humidograms to retrieve CCN and showing the significance of the information contained in the humidogram parameters. In this paper, we only use dataset measured in the NCP as an example to theoretically evaluate the feasibility of the method, because one of the biggest challenges to consider other types of aerosols is the acquisition of the size-resolved hygroscopicity data. Hygroscopicity (specially referred to here as $\kappa$) cannot be regarded as a size-independent parameter in most cases. The backscatter and extinction humidogram are influenced by hygroscopicity of all particles but the calculation of CCN number concentration is only controlled by hygroscopicity of small particles. Optical-equivalent bulk $\kappa$ is different from critical activation $\kappa_c$ and the relationship between them is found to be complex (Tao et al., 2018). Besides, the mixing state of particles is also an important parameter in simulating particle optical properties. The purpose of using these data is to make the simulation closer to real situation in the atmosphere.
So we only focus on the aerosol in the NCP, and we believe that researchers who concern about other types of aerosols can repeat theoretical simulations with their own datasets. Also, we are trying to complete the algorithm as much as possible in future work.

Details

P3, L8-9: . . . The new method to retrieve CCN . . . is proposed based on kappa Koehler theory. . . . There are many examples of such ‘isolated’ phrases, not further explained. So, often the reader is confronted with a lot of information and then with the question: What do they want to say? How will that be used? Only experts know what the message behind probably is.

Response:

Thanks for pointing the problem out. We revised the sentence: 

'It in this paper, a new method to retrieve CCN number concentrations for 3β+2α MWRL systems is proposed. Theoretical simulations are carried out to seek the relationship between CCN number concentrations and lidar-derived optical properties. The simulation implement κ-Köhler theory (Petters and Kreidenweis, 2007) to describe particle hygroscopic growth and activation process. Mie theory (Bohren and Huffman, 2007) is utilized to calculate particle backscatter and extinction coefficients from in situ measured aerosol microphysical and chemical properties. '

Section 2: As a motivation it is mentioned: Section 2 introduces the measured and simulated data sets. Ok. But why do you introduce these data, why do you need these data, what is the goal, do you need them as input? All this is not explained. Nothing is clear. As a reader one wants to know the motivation for every section, before the content of the section is presented.

Response:

An introduction of the motivation for Sect. 2 has been added to the beginning of the section:

'Since it is not easy to accumulate large datasets of simultaneous measurements of lidars and aircrafts, ground-measured aerosol microphysical and chemical data are used to simulate lidar-derived backscatter and extinction coefficients and corresponding CCN number concentrations. The simulations are based on κ-Köhler theory and Mie theory. The required datasets include: particle number size distribution (PNSD), black carbon (BC) mass concentrations (mBC), mixing state of BC containing particles, and size-resolved hygroscopicity. The simulation results are used to establish and validate the new retrieval method.'

And after reading of section 2 and all the subsequent sections it becomes more or less clear: This method obviously only holds for North China Plain (NCP) pollution aerosol. But is that then a useful method, for all the lidar scientists around the globe?

As a reader I expect a well elaborated algorithm applicable to all relevant aerosol types: What about pure marine conditions, what about desert dust scenarios, what about forest fire smoke in the free troposphere? How does the method work in these cases? All this is not considered in this paper. Only NCP aerosol.

Response:

We agree that other aerosol types should be considered if the algorithm need to be applied globally. However, the main purpose of our paper is to introduce the idea of using humidograms to estimate CCN to lidar and other related researchers. Elaborating an algorithm is a long process and needs the contribution of the whole community. We sincerely hope to share the idea with an example of NCP
to other researchers through the paper and improve the algorithm together in the future.

The BC mixing state is introduced. . . . size resolved chemical composition all come from campaign C2. . . . and after transforming the ambient wet aerodynamic diameters into dry volume-equivalent diameters, size resolved kappa distribution were derived from measured size resolved chemical composition. Twenty five typical size-resolved kappa distributions in the NCP are computed and later used. . . . in the simulations. Who can follow? Why do you present all this? The methodology is still not presented yet! The paper is to more than 50% just an accumulation of information, like in a laboratory book . . . . Section 2.2.

Response:
The derivation of the parameter of BC mixing state and size-resolved $\kappa$ distributions are detailed described in the papers of Ma et al. (2012) and Liu et al. (2014) respectively. The use of these data can improve the simulation. The mixing state of BC influence particle optical properties, and the $\kappa$ distribution, as is addressed in the previous response, is needed in the simulations of humidogram and CCN activation. These valuable parameters are important in the method. All the data used in this paper will be put in a repository and available to everyone if the paper is published.

P4, Eq3 is introduced, taken from another paper, D is introduced as particle/droplet radius (but it is obviously the droplet radius). The equation contains: $\text{RH} = 1 + \text{SS}$ with SS in %, so what is the unit of RH?

Response:
Thanks for your suggestion. We have changed ‘particle/droplet’ to ‘particle or droplet’. As for the doubt about the unit of RH, we check the equation carefully and believe there is no problem about the equation. Besides, there is no indication that the unit of SS is ‘%’ in the manuscript.

P4, L29: Then Mie theory is used with all the parameters introduced before including the confusing 25 kappa distributions. It is impossible to check the simulations in detail. We are forced to read another paper (Zhao et al, 2017). So, as a reader I am totally confused by the accumulation of all the information from field campaigns, simulations, partly explained in another paper. All particles are spherical which may make sense for North China pollution close to cloud base but what about aerosol mixtures with a lot of mineral dust, practically 75% of the aerosol in China) probably contains dust, what do we do in these cases?

Response:
The simulations are now introduced in detail in the Supplement (Please see Sect. S3 of the Supplement). Assumptions, equations, and values of key parameters are presented.

We agree that mineral dust is an important component of aerosols in China. NCP is also influenced by dust transported from North East China, especially in spring. However, limited by the knowledge and data, dust is not considered in the current algorithm. When dust is the dominant component (easily identified from polarization measurement), the algorithm is not applicable at present. Considering the mixture of anthropogenic aerosols and mineral dust is a challenge, especially for dust coated by anthropogenic components (e.g. sulfate or organic compounds). The optical properties, hygroscopicity, and size-resolved number fraction of dust aerosols coated by anthropogenic components still have lots of uncertainties. More measurements are needed to deal with these cases.
P5. In Section 3, among the discussion of another set of new aspects (useful or not) the authors ‘jump’ to a new topic: Size-resolved enhancement contributions of backscatter and extinction are calculated to discuss hygroscopicity sensitive size of optical enhancement factor measurement. Ok?! . . . strong oscillations are found in size enhancement contributions of backscatter coefficients. OK! But what is the message behind all this? Where is the methodological concept? Where is all the mentioned information used?

Response:
In this part, we want to discuss the number and hygroscopic information of particles that can be gained from lidar measurements. Lidar can be used to retrieve CCN number concentration only if we can get particle number and hygroscopic information of CCN-related sizes. Size-resolved enhancement contributions of backscatter and extinction are discussed because we want to know hygroscopicity information of which size we can get from the humidograms of backscatter and extinction. The result shows that the humidograms of different parameters are sensitive to the hygroscopicity of different sizes. The oscillation in backscatter means the hygroscopic information in backscatter enhancement is complex and different from that in extinction enhancement. That explains why we use humidogram parameters (κ₉) of all the 3β+2α to indicate particle hygroscopicity. Size-dependent hygroscopicity is important to estimate CCN rather than a bulk hygroscopicity information, especially for different supersaturation conditions. One humidogram may indicate the bulk hygroscopicity, but it is the hygroscopicity of small particles that influences CCN number concentrations most. Spectrally dependent κₑ can provide some information about the hygroscopicity of small particles. We have removed the ‘oscillation’ sentence and add the explanation:
‘Figure 3b also shows that different κₑ is sensitive to the hygroscopicity of different size. Size-dependent hygroscopicity is important to estimate CCN rather than a bulk hygroscopicity information, especially for different supersaturation conditions. One humidogram may indicate the bulk hygroscopicity, but it is the hygroscopicity of small particles that influences CCN number concentrations most. Using κₑ of all the 3β+2α can provide some information about the hygroscopicity of small particles.’

This part has been moved to Discussion (Section 4.1) with some extra explanation in the revised version.

P6: Now equations describing light scattering enhancement factors are introduced, no word about aerosol types and related differences in the enhancement factors. So, here it became finally clear to me the authors only develop their method for North China Plain pollution aerosol.

In conclusion, the authors accumulate and accumulate information . . . from field campaigns, from papers, from own simulations, but leave the reader alone. . . with the question: Why do you present all this? Where is the flow chart with all input parameters needed to compute CCN from backscatter and extinction coefficients at several wavelengths, including uncertainty bars? We are already at the end of page 6, and no methodological concept is presented yet. Section 5 (Summary) comes close (given on page 11).

Response:
Thanks for your suggestion to change the structure. The algorithm is now presented at the beginning of Sect. 3 and is described step by step as you suggested. We not only want to show the algorithm
to researchers but also hope to introduce how we develop the algorithm and the scientific support
behind the method.

Now the methodology section starts, Sect. 3.3.

P7 L6: The equation provides the basic relationship between lidar information (backscatter and
extinction coefficient) and N-CCN.

P7 L4: you write backscatter/extinction coefficient, but I believe you want to write backscatter and
extinction ..., and not to use the ratio (backscatter/extinction). All this is confusing!

Response:

Thanks for the suggestion. We now use ‘backscatter and extinction’ or ‘backscatter or extinction’
according to the meaning in the manuscript.

P7, Eq.7 and Eq.8, again new parameters are introduced, new discussion and uncertainty sources,
but no clear flow chart what to do with all this information in detail (step by step).

P8, L4-6: Here the entire method is summarized within three lines! We need to study Figure 3 that
shows a flow chart. This is a SKTECH! . . . and helps to understand the method. But a clear set of
equations with all input parameters needed in the first step and all the output parameters, which are
again input for the next step and so on, is missing. All this is needed for five optical properties (3
beta and 2 ext). All this is not presented. What about uncertainties in the retrieval? How can we get
a convincing opinion on the potential (and especially the limits) if we have only Fig 3 and then the
correlation plots in Figure 4. Figures 6 and Figure 7 are useful. But we need to see the overall
concept (equations, including uncertainty computation approaches.) And we need it for other
aerosol types (dust, haze, marine..), not only for NCP aerosol which is of course an important aerosol
mixture.

Response:

Thank you for your advice. We have already expressed the retrieval step more clearly according to
your suggestion.

P8, L4-6 describes the last step of the algorithm, and we have added a word ‘Finally’ to avoid
misunderstandings.

We have tried to make a flow chart to contain all the details, but it would make the figure really
complicated. So we remain the flow chart unchanged, because it is concise and easy for the readers
to understand. For more detailed information, the algorithm is now described step by step in Sect.
3.1, and we believe it is now clear to the readers. The idea of our method is more valuable than the
details in the algorithm, and all the steps is adjustable if others want to use the idea to retrieve CCN
from lidars.

The uncertainties of the retrieval shown in Fig. 4 indicate the uncertainties from the concept of
method. It shows whether humidogram parameters, Ångström exponent, and lidar ratios can
describe the variation of the defined optical-related activation ratio. Uncertainties can also arise
from the assumption of the aerosol model, the κ-Köhler theory, and the Mie theory. All the
assumptions and theories are not exactly what the real world is. These uncertainties are evaluated
by lots of closure studies. In practical application, uncertainties also come from lidar and other
corresponding measurements. These uncertainties could be analyzed by Monte-Carlo method if the
uncertainties of all the measured value is known.

As for the limitations, we have already addressed in the summary in the public version of the
manuscript (the second last paragraph):

'It should be noted that the theoretical analyses in this paper are based on datasets of continental aerosols, and the implement of Mie theory also limits the scope of the results. The results can be applied in the North China Plain but are not fit for sea salts and mineral dust. Studies with datasets of other aerosol types should be carried out in the future. Although the applicability of this new method is limited by large uncertainties in RH profiles, comparison between real measured MWRL data and airborne in situ measurement should also be conducted.'

Reference


Method to retrieve cloud condensation nuclei number concentrations using lidar measurements

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Abstract. Determination of cloud condensation nuclei (CCN) number concentrations at cloud base is important to constrain aerosol-cloud interactions. A new method to retrieve CCN number concentrations using backscatter and extinction profiles from multiwavelength Raman lidars is proposed. The method implements hygroscopic enhancements of backscatter/extinction backscatter and extinction with relative humidity to derive dry backscatter/extinction backscatter and extinction. Humidogram parameters, Ångström exponents, and lidar extinction-to-backscatter ratios are then linked to the ratio of CCN number concentration to dry backscatter/extinction backscatter and extinction coefficient ($AR_{\xi}$). This linkage is established based on the datasets simulated by Mie theory and $\kappa$-Köhler theory with in situ measured particle size distributions and chemical compositions. CCN number concentration can thus be calculated with $AR_{\xi}$ and dry backscatter/extinction backscatter and extinction. An independent theoretical simulated datasets is used to validate this new method and results show that the retrieved CCN number concentrations at supersaturations of 0.07%, 0.10%, and 0.20% are in good agreement with theoretical calculated values. Sensitivity tests indicate that retrieval error in CCN arise mostly from uncertainties in extinction coefficients and RH profiles. The proposed method improves CCN retrieval from lidar measurements and has great potential in deriving scarce long-term CCN data at cloud base which benefits aerosol-cloud interaction studies.

1 Introduction

Anthropogenic activities have caused a huge increase in atmospheric aerosols, and some of the aerosol particles affect the climate by serving as cloud condensation nuclei (CCN). CCN in clouds can modify cloud forming processes and cloud microphysical properties (Rosenfeld et al., 2014). Although numerous impacts of aerosol-cloud interactions on radiative forcing (McCoy et al., 2017;Zhou et al., 2017), precipitation (Xu et al., 2017;Fan et al., 2018), cloud electrification (Wang et al., 2018), and severe weathers or hazards (Fu et al., 2017) have been discovered, constraining the relationships between
aerosols and clouds is still a big challenge (Seinfeld et al., 2016). Lacking the knowledge of aerosol-cloud interactions limits our ability to estimate climate forcing caused by aerosols (Boucher et al., 2013).

Aerosol CCN supersaturation activation spectrum is one of the most critical parameters to quantify aerosol-cloud interactions (Schmala et al., 2018). Despite that a large amount of CCN number concentrations near ground have been measured worldwide (Tao et al., 2017), ground-measured CCN may not represent CCN at cloud base that alter clouds directly. Obtaining CCN near cloud base becomes a crucial issue. Cloud base CCN can be measured in situ on aircraft platforms, but airborne measurements have the limitations of huge costs and discontinuity. Satellites are difficult to observe CCN at cloud base, because clouds obscuring aerosol signals beneath them. Rosenfeld et al. (2016) have proposed an alternative approach for satellites to retrieve CCN concentrations using clouds as CCN chambers, however, employing CCN concentrations derived with this strategy limits our exploration of the relationship between CCN concentrations and cloud droplet concentrations in the natural environment. So far, CCN concentrations at cloud base are scarce for aerosol-cloud interaction studies.

Ground-based lidars can continuously provide optical properties of aerosol particles from ground up to cloud base (Mattis et al., 2016; Barreto et al., 2019), suggesting great potential in deriving CCN concentrations near cloud base. Ghan and Collins (2004) propose a simple method to infer CCN profiles with the combination of surface in situ CCN and aerosol optical measurements. The method is only applicable when boundary layer is well mixed from surface to cloud base (Ghan et al., 2006). Multiwavelength Raman lidars (MWRLs) are increasingly used to detect aerosol vertical distributions in recent years. The principle of MWRLs allows independent retrieval of particle backscatter ($\beta$) and extinction coefficients ($\alpha$), which provides more information about particle microphysical properties (Müller et al., 2016). The $\beta+2\alpha$ MWRL systems (backscatter coefficients at 355, 532, and 1064 nm and extinction coefficients at 355 and 532 nm) have been widely recommended to derive particle microphysical properties (Burton et al., 2016). Existing approaches to retrieve CCN using MWRLs are based on microphysical inversion techniques (Mamouri and Ansmann, 2016). Retrieved optical-equivalent particle size distributions together with assumed activation critical diameters are utilized to calculate CCN concentrations (Lv et al., 2018).

There are three major challenges in CCN concentration retrieval with lidars. The first is the conversion of lidar-derived optical properties into particle number concentrations. High uncertainties of retrieved particle number concentrations could be an important source of CCN retrieval error. The second one is the determination of particle hygroscopicity in order to evaluate the ability of particles to participate as CCN. Particle hygroscopicity, which is highly related to chemical composition and aging/coating effect, is found to cause nonnegligible variations in cloud droplet activation (Hudson, 2007; Zhang et al., 2017). The last is the influence of high relative humidity (RH) near clouds. Aerosol particles are likely to be humidified in the ambient environment, and the consequent changes in optical properties make CCN retrieval more complicated. Most studies working on CCN retrieval with MWRLs mainly focus on deriving particle number concentrations, but seldom commence to solve the issue of hygroscopicity.

In recent years, several aerosol hygroscopic studies based on lidar measurements have been carried out (Fernández et al., 2017; Lv et al., 2017; Bedoya-Velásquez et al., 2018). Backscatter and extinction enhancement factors can be derived with lidar
measurements and RH profiles. The enhancement factor, which is associated with both particle size and hygroscopicity (Kuang et al., 2017), is defined as:

\[ f_{\xi}(\text{RH}, \lambda) = \frac{\xi(\text{RH}, \lambda)}{\xi(\text{RH}_{\text{ref}}, \lambda)}, \]  

where \( f_{\xi} \) is the enhancement factor of the optical property \( \xi \) (backscatter or extinction) at a specific light wavelength \( \lambda \) and \( \text{RH} \), and \( \text{RH}_{\text{ref}} \) is the reference RH value. Many studies manifest that lidar-derived enhancement factors are in good agreement with in situ measurements (Wulfmeyer and Feingold, 2000; Pahlow et al., 2006; Fernández et al., 2015; Rosati et al., 2016). Feingold and Morley (2003) demonstrate that the extent of backscatter and extinction enhancements hints at the ability of particles to serve as CCN. Tao et al. (2018) use in situ measured light scattering enhancement factors to predict \( N_{\text{CCN}} \) at 0.07% supersaturation, and the result shows strong consistency with CCN counter.

In this paper, a new method to retrieve CCN number concentrations for 3β+2α MWRL systems (backscatter coefficients at 355, 532, and 1064 nm and extinction coefficients at 355 and 532 nm) is proposed based on \( \kappa \)-Köhler theory (Petters and Kreidenweis, 2007) and Mie theory (Bohren and Huffman, 2007). Enhancements of backscatter and extinction with RH are first implemented in CCN retrieval using MWRLs. In this paper, a new method to retrieve CCN number concentrations for 3β+2α MWRL systems is proposed. Theoretical simulations are carried out to seek the relationship between CCN number concentrations and lidar-derived optical properties. The simulation implements \( \kappa \)-Köhler theory (Petters and Kreidenweis, 2007) to describe particle hygroscopic growth and activation process. Mie theory (Bohren and Huffman, 2007) is utilized to calculate particle backscatter and extinction coefficients from in situ measured aerosol microphysical and chemical properties.

The paper is structured as follows. Section 2 introduces the measured and simulated datasets used in this paper. Section 3 presents the methodology. Firstly, suitable supersaturation conditions for lidar retrieval are discussed in Sect 3.1. Performances of two parameterization scheme for backscatter and extinction humidogram are evaluated in Sect 3.2. In Sect. 3.3, the new CCN retrieval method for MWRLs and the sensitivity tests are respectively described in detail. Sect. 3.1 and Sect. 3.2. Sensitivity tests are carried out in Sect. 3.4. Results and summary discussions are given in Sect. 4 and Sect. 5, respectively. Section 5 summarizes the paper.

2 Data

Since it is not easy to accumulate large datasets of simultaneous measurements of lidars and aircrafts, ground-measured aerosol microphysical and chemical data are used to simulate lidar-derived backscatter and extinction coefficients and corresponding CCN number concentrations. The simulations are based on \( \kappa \)-Köhler theory and Mie theory. The required datasets include: particle number size distribution (PNSD), black carbon (BC) mass concentrations (\( m_{\text{BC}} \)), mixing state of BC containing particles, and size-resolved hygroscopicity. The simulation results are used to establish and validate the new retrieval method.
2.1 Datasets of aerosol microphysical and chemical properties

In situ measured aerosol properties were collected from five field campaigns at three different measurement sites in the North China Plain (NCP). The measurement sites are located at Wuqing (39°23′ N, 117°01′ E, 7.4 m a.s.l) in Tianjin, Xianghe (39°45′ N, 116°58′ E, 36 m a.s.l) and Wangdu (38°40′ N, 115°08′ E, 51 m a.s.l) in Hebei province. The specific locations, topographical information, and pollution status of these measurement sites are shown in Fig. S1 in the Supplement. These three sites all lie inside the polluted NCP region and are highly representative of the polluted background (Xu et al., 2011; Bian et al., 2018; Sun et al., 2018). Time periods, measured parameters, and corresponding instruments of individual campaign are listed in Table 1. During these field campaigns, except measurement for size-resolved chemical compositions, ambient particles were drawn in through a PM10 inlet (16.67 L/min), passed through a silica gel diffusion drier, and then were split into different instruments. All instruments were operated at RH less than 30%.

The particle number size distributions (PNSDs) were measured with the combination of a twin differential mobility particle sizer (TDMPS, IfT, Leipzig, Germany) or a scanning mobility particle size spectrometer (SMPS) and an aerodynamic particle sizer (APS, TSI, Inc., Shoreview, MN USA, Model 3320 or Model 3321). The statistical information about the measured PNSDs is shown in Fig. 1a. The peaks of the PNSDs are at about 100 nm (diameter in log-scale), which shows strong characteristics of continental aerosols.

The black carbon (BC) mass concentrations \(m_{\text{BC}}\) were measured by a multi-angle absorption photometer (MAAP, Thermo, Inc., Waltham, MA USA, Model 5012). As for mixing states of BC, BC and other non-absorbing compositions were found to be both externally mixed and core-shell mixed during the campaigns (Ma et al., 2012). The mass fraction of externally-mixed BC \(r_{\text{ext}}\) is defined to quantify the mixing states of BC:

\[
r_{\text{ext}} = \frac{m_{\text{ext, BC}}}{m_{\text{BC}}},
\]

where \(m_{\text{ext, BC}}\) is the mass concentration of externally mixed BC. According to Ma et al. (2012), \(r_{\text{ext}}\) can be retrieved from hemispheric backscattering fractions (HBFs) measured by an integrating nephelometer (TSI, Inc., Shoreview, MN USA, Model 3563).

Size-resolved chemical compositions all come from campaign C2. The size-resolved aerosol sampling was carried out with a ten-stage Berner low pressure impactor (BLPI). Chemical species including inorganic ions (\(\text{NH}_4^+, \text{Na}^+, \text{K}^+, \text{Mg}^{2+}, \text{Ca}^{2+}, \text{NO}_3^-, \text{SO}_4^{2-}, \text{Cl}^-\)), elemental carbon, organic carbon, water-soluble organic carbon and some other species such as dicarboxylic acids were analyzed from sample substrates. After transforming the ambient wet aerodynamic diameters into dry volume-equivalent diameters, size-resolved \(\kappa\) distributions were derived from measured size-resolved chemical compositions. The chemical compositions are found to be size dependent during the campaign C2, especially the mass fraction of organic matter (Liu et al., 2014). Twenty-five typical size-resolved \(\kappa\) distributions in the NCP are given in Fig. 1b. The measured size-resolved \(\kappa\) distributions vary a lot and cover a wide range of aerosol hygroscopicity (Kuang et al., 2018). More details about the measurements can be found in Liu et al. (2014).
2.2 Datasets of CCN number concentrations and lidar-derived optical properties

In situ measured aerosol properties mentioned above are utilized to calculate CCN number concentrations and particle backscatter and extinction coefficients based on $\kappa$-Köhler theory and Mie theory. For each simultaneously measured PNSD, $m_{BC}$, and $r_{\text{ext}}$ (16183 sets of data), simulations are carried out with every one of the twenty-five size-resolved $\kappa$ distributions. CCN number concentrations can be calculated with PNSD and size-resolved $\kappa$ distributions based on $\kappa$-Köhler equation. Petters and Kreidenweis (2007) introduce the $\kappa$-Köhler equation to describe the relationship between particle/droplet size and critical supersaturation ratio (SS) or RH with a single hygroscopic parameter $\kappa$:

$$\text{RH}(D) = 1 + \text{SS}(D) = \frac{D^3 - D_{\text{dry}}^3}{D^3 - D_{\text{dry}}^3(1-\kappa)} \exp\left(\frac{4\sigma_{s/a}M_w}{RT\rho_wD}\right),$$

(3)

where $D_{\text{dry}}$ is particle dry diameter, $\sigma_{s/a}$ is the surface tension of the solution/air interface, $M_w$ is the molecular weight of water, $R$ is the universal gas constant, $T$ is temperature, and $\rho_w$ is the density of water. For a specific supersaturation, critical activation diameter can be derived with $\kappa$-Köhler equation using size-resolved $\kappa$ distributions. CCN number concentrations thereby can be calculated by integrating number concentrations of particles larger than the critical diameter. Given PNSD at dry condition, SRKD, and $r_{\text{ext}}$, $\kappa$-Köhler equation can be used to estimate CCN number concentrations by calculating critical diameter—CCN number concentrations at the supersaturations of 0.07%, 0.10%, 0.20%, 0.40%, and 0.80% are accordingly simulated. The selected supersaturation ratios are widely used in CCN measurements.

Particle backscatter and extinction can be calculated with PNSD, $m_{BC}$, and $r_{\text{ext}}$ using Mie models. Mie theory can solve light scattering problems of homogeneous and coated spherical particles. Without the consideration of mineral dust, using Mie model is quite reasonable because particles are likely to be spherical near clouds where the RH could be relatively high. When simulating particle backscatter and coefficients, PNSD, $m_{BC}$, $r_{\text{ext}}$, and complex refractive index are essential.

PNSD at different RH can be calculated with $\kappa$-Köhler equation as well. The refractive indices of BC, non-absorbing component, and pure water are set to be 1.8+0.54i (Ma et al., 2012), 1.53+10^{-7}i (Wex et al., 2002), and 1.33+10^{-7}i respectively. More detail about calculations of lidar derived optical properties can be found in (Zhao et al., 2017). Backscatter coefficients (355, 532, and 1064 nm) and extinction coefficients (355 and 532 nm) at dry condition and RH from 60-90% are simulated with an interval of 1%.

The simulations are introduced in detail in Sect. S3 in the Supplement. The new method and all the analyses in this paper are based on the Mie model simulated datasets, and all the simulations mentioned above are implemented.

3 Methodology

3.1 Supersaturations for lidar CCN retrieval

CCN number concentrations are related with supersaturations. Critical diameters of each supersaturation calculated with twenty-five size-resolved $\kappa$ distributions are shown in Fig. 2a. Most of the critical diameters at supersaturation of 0.07% are...
larger than 200 nm, while critical diameters at supersaturation of 0.80% are around 50 nm. Suitable supersaturations for lidar CCN retrieval depend on the ability of lidar optical properties to provide information about number and hygroscopicity of CCN-related sizes.

Size cumulative contributions of particle number of all measured particle size distribution and corresponding calculated backscatter and extinction at dry condition are also displayed in Fig. 2a. As the cumulative contributions of particle number suggest, particles with diameter less than 100 nm dominate particle number concentrations (over 65%). However, most backscatter and extinction come from particles larger than 200 nm (around 90%) and almost 100% come from particles larger than 100 nm. If critical diameter is small, dry backscatter and extinction are insensitive to particles diameters that contribute to most CCN concentrations.

Size-resolved enhancement contributions of backscatter and extinction are calculated to discuss hygroscopicity sensitive size of optical enhancement factor measurement. The enhancement contribution is defined as the difference between optical cross-sections of RH at 90% and 60%, and represents the proportion of each size to the enhancement in backscatter or extinction. As is shown in Fig. 2b, the contributions of the extinction enhancements are concentrated in the diameters within 200 nm to 700 nm, and extinction enhancement at 355 nm is related to smaller particles than that at 532 nm. Strong oscillations are found in size enhancement contributions of backscatter coefficients. Similar to particle number, particles with diameters smaller than 100 nm contributes little to the enhancement of both backscatter and extinction.

Comparing sensitive size of optical properties and critical diameters at different supersaturations, 3β+2α MWRL systems have potential to retrieve CCN number concentrations at supersaturations smaller than 0.20%. It is not recommended to estimate CCN concentrations using lidar data at supersaturations larger than 0.40%.

**3.2 Humidogram parameterization for backscatter and extinction enhancements**

Humidogram parameterization is needed to find a representative parameter for the relationship between enhancement factor and RH. Unlike in situ controlled RH measurements, there is no such a generic reference RH as dry condition for lidar measurements to derive enhancement factor. Inferring backscatter and extinction coefficients at dry condition ($\xi_{\text{dry}}$) is also an important issue in CCN retrieval. Therefore, humidogram parameterization of lidar-derived optical properties should combine $\xi_{\text{dry}}$ and $f(\text{RH}, \lambda)$ together.

Many equations to parameterize enhancement factors have been proposed by previous studies (Titos et al., 2016). Two one-parameter equations are selected to test their performance on estimating $\xi_{\text{dry}}$ and representing particle hygroscopic growth characteristics. The first equation is the most commonly used one initially introduced by Kasten (1969):

$$\xi(\text{RH}, \lambda) = \xi_{\text{dry}}(\lambda) \cdot f(\text{RH}, \lambda) = \xi_{\text{dry}}(\lambda) \cdot (1 - \text{RH})^{-\gamma_f(\lambda)}$$

(4)

where the exponent $\gamma_f$ is the fitting parameter and describes the hygroscopic behavior of the particles; the other equation is proposed based on physical understanding by Brock et al. (2016), which has been reported to have better performance in describing light scattering enhancement factor than Eq. (4) (Shin et al., 2018):
\[ \xi (\text{RH}, \lambda) = \xi_{\text{dry}}(\lambda) \cdot f_\xi (\text{RH}, \lambda) = \xi_{\text{dry}}(\lambda) \cdot \left[ 1 + \kappa_\xi(\lambda) \frac{\text{RH}}{1 - \text{RH}} \right] \]  

where \( \kappa_\xi \) is the fitting parameter and shows significant correlation with bulk hygroscopic parameter \( \kappa \) (Kuang et al., 2017). Here, Eq. (4) and Eq. (5) are denoted as \( \gamma \) equation and \( \kappa \) equation respectively. With given backscatter and extinction at different RH, \( \xi_{\text{dry}} \) and \( \gamma \) or \( \kappa \) can be fitted simultaneously by means of least squares.

Comparisons between the performances of \( \gamma \) equation and \( \kappa \) equation on inferring backscatter and extinction at dry condition are carried out to select a better parameterization. Four RH ranges (60%–90%, 60%–70%, 70%–80%, and 80%–90%) are selected. The fitted \( \xi_{\text{dry}} \) are compared with the \( \xi_{\text{dry}} \) calculated by Mie model. The slopes of linear regressions, determination coefficients (\( R^2 \)), and relative errors are listed in Table 2. Apparently, \( \kappa \) equation has a better performance than \( \gamma \) equation for all RH ranges. Inferring \( \xi_{\text{dry}} \) with \( \gamma \) equation will underestimate about 10%–30%. It is consistent with the finding of Haarig et al. (2017) that \( \gamma \) equation does not hold for RH lower than 40%. The bias of backscatter is found to be larger than the bias of extinction.

The RH range of humidogram equations also influences the fitting results. Table 2 shows the fitted \( \xi_{\text{dry}} \) have larger bias when the value of RH increase. The fitted humidogram parameters \( \gamma \) and \( \kappa \) from different RH ranges are compared to each other, and the results are displayed in Table 3. Parameterization equations are not always perfect for the whole RH ranges, so humidogram parameters fitted with various RH ranges can be different. If \( \gamma \) and \( \kappa \) are used to represent hygroscopic behavior of particles, more careful attention should be paid to the RH range.

Based on the comparisons above, Eq. (5) (\( \kappa \) equation) is selected as our humidogram equation to derive \( \xi_{\text{dry}} \) and \( \kappa \). The RH range for parameter fitting used is fixed to 60%–90% in the following method.

3.3.3.1 Method to retrieve CCN number concentrations using MWRL

3.3.13.1.1 Overview

An optical-related CCN activation ratio, \( AR_\xi \), is introduced to bridge the gap between CCN and lidar-derived optical properties. \( AR_\xi \) is the ratio between CCN number concentration and backscatter/extinction coefficient, which can be expressed as:

\[ AR_\xi (\text{SS}, \lambda) = \frac{N_{\text{CCN} (\text{SS})}}{\xi_{\text{dry}}(\lambda)} = \frac{N_{\text{CCN} (\text{SS})}}{N_{\text{aerosol}}} \cdot \frac{N_{\text{aerosol}}}{\xi_{\text{dry}}(\lambda)}, \]  

where \( N_{\text{CCN}} \) is the CCN number concentration, and \( N_{\text{aerosol}} \) is the total number concentration of aerosol particles. \( AR_\xi \) can be divided into two parts: one is the ratio of CCN to the total particles, which is the origin definition of CCN activation ratio; the other is the ratio of total number concentration to backscatter or extinction at dry condition. Bulk CCN activation ratio is related with particle size distribution and hygroscopicity, and the relationship between particle number concentration and optical properties is mainly controlled by size distribution. Therefore, \( AR_\xi \) could be quantified with size and hygroscopicity information. The key point of our method is to seek parameters that can indicate size and hygroscopicity of particles from lidar...
measurement and use these parameters to estimate $\text{AR}_\xi$. Besides, deriving backscatter and extinction coefficients at dry condition is also important.

The schematic diagram of the whole algorithm method to retrieve CCN number concentration is shown in Fig. 32. Firstly, enhancement of backscatter and extinction coefficients with RH (also called humidogram) is derived from lidar measurements and additional ancillary data (i.e. pressure, temperature, RH profiles). Humidogram parameter which can indicate particle hygroscopicity can be fitted from humidograms with parameterization equation. Particle dry backscatter and extinction can also be inferred from the humidograms. This step is applied to all the $3\beta+2\alpha$ parameters. The approaches to select appropriate hygroscopic layers and fit humidogram parameters, dry backscatter, and dry extinction are described in Sect. 3.1.2.

With the method in Sect. 3.2, $\xi_{\text{dry}}$ and $\kappa_{\text{d}}$ can be derived with backscatter and extinction enhancements. Optical humidogram parameters $\kappa_{\text{d}}$ can be regarded as parameters indicating hygroscopicity. Then, Ångström exponent ($\hat{a}_\xi$) and lidar extinction-to-backscatter ratio (lidar ratio, $s_\alpha$) are calculated from inferred dry backscatter and extinction coefficients. Extinction-related Ångström exponent ($\hat{a}_\omega$) is the most commonly used parameter to reveal information about the predominant size of aerosols. Generally speaking, a smaller $\hat{a}_\omega$ represents there are more large particles. Similarly, backscatter-related Ångström exponent ($\hat{a}_\beta$) are often employed in lidar analysis (Fernández et al., 2015), and particle backscatter coefficients of different wavelengths also have been proved to have a valid Ångström exponent relationship (Komppula et al., 2012). Ångström exponent of dry backscatter and extinction coefficients ($\hat{a}_\xi$) between two wavelengths can be derived using Eq. (557):

$$\hat{a}_\xi(\lambda_1, \lambda_2) = -\frac{\log(\xi_1/\xi_2)}{\log(\lambda_1/\lambda_2)},$$

where the subscript 1 and 2 represents different wavelengths. Another widely used parameter to express aerosol characteristics in lidar studies is the particle lidar extinction-to-backscatter ratio (lidar ratio, $s_\alpha$), which is defined as the ratio of extinction coefficient to backscatter coefficient at a specific light wavelength:

$$s_\alpha(\lambda) = \frac{\alpha(\lambda)}{\beta(\lambda)} = \frac{4\pi}{P(\pi) - \omega}. \quad (668)$$

As is shown in Eq. (36), lidar ratio is determined by the scattering phase function at $180^\circ$ $P(\pi)$ and the single scattering albedo $\omega$. $P(\pi)$ is mainly influenced by particle size and $\omega$ indicates the content and mixing state of light absorbing components.

Lidar ratio is often utilized in aerosol type classification and is proved to be very sensitive to particle sizes (Zhao et al., 2017). Particle type information can also be regard as an alternative representative of hygroscopicity. The lidar ratio can provide information on particle type and also serve as a proxy for particle hygroscopicity. Therefore, lidar ratio of dry particles could be a reliable parameter to estimate $\text{AR}_\xi$.

Next, $\hat{a}_\xi$, $s_\alpha$, and humidogram parameters are utilized to estimate $\text{AR}_\xi$. $\text{AR}_\xi$ of all the $3\beta+2\alpha$ parameters is calculated. Statistical relationship among humidogram parameters, $\hat{a}_\xi$, $s_\alpha$, $\kappa_{\text{d}}$, and $\text{AR}_\xi$ are used in our new method. Based on the statistical relationship, $\text{AR}_\xi$ can be estimated by $\hat{a}_\xi$, $s_\alpha$, and $\kappa_{\text{d}}$. The estimation of $\text{AR}_\xi$ is introduced in Sect. 3.1.3 in detail. The implement of $\hat{a}_\xi$ and $s_\alpha$ is quite similar to the microphysical inversion process for particle size distribution retrieval.
Microphysical inversion is a physics-based approach but will bring huge uncertainties in retrieving particle number concentrations. Constraining AR$_\xi$ directly with statistical relationship is a much more simple and straightforward way. Finally, After AR$_\xi$ of backscatter and extinction at different wavelengths are derived, CCN number concentration can be calculated by multiplying AR$_\xi$ by the corresponding $\xi_{\text{dry}}$. The average value of CCN concentrations calculated by different $\xi_{\text{dry}}$ is the final retrieval result.

The schematic diagram of the whole algorithm is shown in Fig. 3.

### 3.3.23.1.2 Appropriate retrieval layers

#### Derivation of humidogram parameters, dry backscatter, and dry extinction from lidar measurement

A constraint needs to be satisfied when quantifying the enhancements of backscatter and extinction coefficients with lidar measurements. The selected vertical layers must be well-mixed, so we can guarantee that the variations of particle backscatter/extinction coefficients are caused by different RH and not by various aerosol types or loads. Atmospheric vertical homogeneity is fulfilled if the layer has little variability of virtual potential temperature profile and water vapor mixing ratio profile (Lv et al., 2017). Additional analyses can also be considered to evaluate vertical mixing of air masses, such as backward trajectory, horizontal wind velocities at different altitude, or the third moment of the frequency distribution of vertical wind velocities (Bedoya-Velásquez et al., 2018).

Once vertical homogeneity is ensured, physical and chemical properties at dry condition can be assumed to be uniform in the selected layer, and the number concentrations are proportional to air molecule number density. Accordingly, the relative variations of particle backscatter/extinction coefficients against different RH can be achieved after normalizing the backscatter and extinction coefficients with air molecule number density.

Humidogram parameterization is needed to find a representative parameter for the relationship between enhancement factor and RH. Unlike in situ controlled-RH measurements, there is no such a generic reference RH as dry condition for lidar measurements to derive enhancement factor. Inferring backscatter and extinction coefficients at dry condition ($\xi_{\text{dry}}$) is also an important issue in CCN retrieval. Therefore, humidogram parameterization of lidar-derived optical properties should combine $\xi_{\text{dry}}$ and $f_\xi (\text{RH}, \lambda)$ together.

Many equations to parameterize enhancement factors have been proposed by previous studies (Titos et al., 2016). Two one-parameter equations are selected to test their performance on estimating $\xi_{\text{dry}}$ and representing particle hygroscopic growth characteristics. The first equation is the most commonly used one initially introduced by Kasten (1969):

$$\xi(\text{RH}, \lambda) = \xi_{\text{dry}}(\lambda) \cdot f_\xi(\text{RH}, \lambda) = \xi_{\text{dry}}(\lambda) \cdot (1 - \text{RH})^{-\gamma_\xi(\lambda)}$$  \hspace{1cm} (774)

where the exponent $\gamma_\xi$ is the fitting parameter and describes the hygroscopic behavior of the particles; the other equation is proposed based on physical understanding by Brock et al. (2016), which has been reported to have better performance in describing light scattering enhancement factor than Eq. (47) (Shin et al., 2018):

$$\xi(\text{RH}, \lambda) = \xi_{\text{dry}}(\lambda) \cdot f_\xi(\text{RH}, \lambda) = \xi_{\text{dry}}(\lambda) \cdot \left[1 + \kappa_\xi(\lambda) \frac{\text{RH}}{1 - \text{RH}}\right]^{-\gamma_\xi(\lambda)}$$  \hspace{1cm} (885)
where $\kappa_\xi$ is the fitting parameter and shows significant correlation with bulk hygroscopic parameter $\kappa$ (Kuang et al., 2017). Here, Eq. (47) and Eq. (58) are denoted as $\gamma$-equation and $\kappa$-equation respectively. With given backscatter and extinction at different RH, $\xi_{\text{dry}}$ and $\gamma_\xi$ or $\kappa_\xi$ can be fitted simultaneously by means of least squares.

Comparisons between the performances of $\gamma$-equation and $\kappa$-equation on inferring backscatter and extinction at dry condition are carried out to select a better parameterization. Four RH ranges (60%-90%, 60%-70%, 70%-80%, and 80%-90%) are selected. The fitted $\xi_{\text{dry}}$ are compared with the $\xi_{\text{dry}}$ calculated by Mie model. The slopes of linear regressions, determination coefficients ($R^2$), and relative errors are listed in Table 2. Apparently, $\kappa$-equation has a better performance than $\gamma$-equation for all RH ranges. Inferring $\xi_{\text{dry}}$ with $\gamma$-equation will underestimate about 10%-30%. It is consistent with the finding of Haarig et al. (2017) that $\gamma$-equation does not hold for RH lower than 40%. The bias of backscatter is found to be larger than the bias of extinction.

The RH range of humidogram equations also influences the fitting results. Table 2 shows the fitted $\xi_{\text{dry}}$ have larger bias when the value of RH increase. The fitted humidogram parameters $\gamma_\xi$ and $\kappa_\xi$ from different RH ranges are compared to each other, and the results are displayed in Table 3. Parameterization equations are not always perfect for the whole RH ranges, so humidogram parameters fitted with various RH ranges can be different. If $\gamma_\xi$ and $\kappa_\xi$ are used to represent hygroscopic behavior of particles, more careful attention should be paid to the RH ranges.

Based on the comparisons above, Eq. (58) ($\kappa$-equation) is selected as our humidogram equation to derive $\xi_{\text{dry}}$ and $\kappa_\xi$. The RH range for parameter fitting used is fixed to 60%-90% in the following method.

3.3.3.3 Estimation of $AR_{\xi}$

Ångström exponents, lidar ratios, and optical humidogram parameters $\kappa_\xi$ are used to estimate optical-related activation ratio $AR_{\xi}$. Concerning the Ångström exponents and lidar ratios are not independent to each other (any parameter can be calculated from other parameters), we reduce the number of parameters to a sufficient number to represent all the information. The selected nine parameters are listed in Table 4. There are no explicit expressions between these parameters and $AR_{\xi}$, and the relationships between them are highly nonlinear. One possible way to seek the relationship between the nine parameters and $AR_{\xi}$ solve this problem is to build a lookup table, but too many input parameters would make the lookup table so large to build and operate.

In the past few decades, machine learning has been a field that has developed rapidly, which experiences a very wide range of applications (Grange et al., 2018). Compared to traditional statistical methods, many machine learning techniques are nonparametric and do not need to fulfill many assumptions required for statistical methods (Immitzer et al., 2012). Random forest (RF) is an ensemble decision tree machine learning method that can be used for regression. (Breiman, 2001; Tong et al., 2003). Beside the free restraints on input parameters and assumptions, RF also has the advantage of being able to explain and investigate the learning process (Kotsiantis, 2013). The Python module $\text{RandomForestRegressor}$ from the Python Scikit-Learn
library (http://scikit-learn.org/stable/modules/generated/sklearn.ensemble.RandomForestRegressor.html, last access: 18 December 2018) are utilized as the RF model. The nine parameters in Table 4 are the input parameters for the RF model, and the AR$_{\xi}$ of the $3\beta+2\alpha$ are the output parameters.

Some tuning parameters required by RF model need to be specified by users. Experiments are made to determine the optimal values of the tuning parameters. Experiment results are showed in Fig. S3-S7 in the Supplement and the detailed settings of the RF model are listed in Table S1-S2 in the Supplement. In this case, the results are rather insensitive to the tuning parameters. Data simulated with datasets measured from campaign C1-C4 are utilized as the training data, and those from C5 are used as test data.

3.43.2 Sensitivity test

Both systematic and random errors exist in lidar-retrieved backscatter and extinction coefficients (Mattis et al., 2016). Systematic errors in backscatter and extinction can come from instrumentation setup, data processing method, and retrieval algorithm. Sensitivity test is carried out to test the impact of systematic errors of backscatter and extinction on CCN retrieval. Errors in backscatter or extinction influence the value of Ångström exponents and lidar ratios but have no impact on $\kappa_{\xi}$. The errors of individual backscatter or extinction are considered to be independent, though systematic errors of different parameters are related. The systematic errors are given in the range of -20% to 20% with an interval of 2%. In each test, the error is only applied to one parameter, and other parameters are error-free.

RH is another crucial factor in this new method to retrieve CCN. Profiles of RH derived by remote sensing techniques are also influenced by errors. At present, RH profiles are usually obtained with the combination of temperature from microwave radiometer and water vapor mixing ratio from MWRL. Both measurements can cause systematic and random errors in RH (Bedoya-Velásquez et al., 2018). Errors in RH will influence the values of $\xi_{\text{dry}}$ and $\kappa_{\xi}$, which in turn influence all the nine input parameters. Systematic errors ranging from -10% to 10% in intervals of 1% are considered for RH. Random errors in observations can be reduced by temporal averaging but cannot be eliminated. The influence of random errors in backscatter, extinction, and RH on CCN retrieval are investigated with Monte Carlo method. Errors obeying Gaussian distribution are generated randomly with the mean value of zero. The standard deviation of Gaussian distribution is 10% for backscatter/extinction, 25% for backscatter and extinction, and 5% for RH. The procedure is repeated for 2000 times. All the 80575 sets of data from campaign C5 are used for sensitivity test.

4 Results and discussions

3.4.1 Supersaturations for lidar CCN retrieval

CCN number concentrations are related with supersaturations. Critical diameters of each supersaturations calculated with twenty-five size-resolved $\kappa$ distributions are shown in Fig. 23a. Most of the critical diameters at supersaturation of 0.07% are
larger than 200 nm, while critical diameters at supersaturation of 0.80% are around 50 nm. Suitable supersaturations for lidar CCN retrieval depend on the ability of lidar optical properties to provide information about number and hygroscopicity of CCN-related sizes.

Size cumulative contributions of particle number of all measured particle size distribution and corresponding calculated backscatter and extinction at dry condition are also displayed in Fig. 23a. As the cumulative contributions of particle number suggest, particles with diameter less than 100 nm dominate particle number concentrations (over 65%). However, most backscatter and extinction come from particles larger than 200 nm (around 90%) and almost 100% come from particles larger than 100 nm. If critical diameter is small, dry backscatter and extinction are insensitive to particles diameters that contribute to most CCN concentrations.

Size-resolved enhancement contributions of backscatter and extinction are calculated to discuss hygroscopicity sensitive size of optical enhancement factor measurement. The enhancement contribution is defined as the difference between optical cross-sections of RH at 90% and 60%, and represents the proportion of each size to the enhancement in backscatter or extinction. As is shown in Fig. 23b, the contributions of the extinction enhancements are concentrated in the diameters within 200 nm to 700 nm, and extinction enhancement at 355 nm is related to smaller particles than that at 532 nm. Strong oscillations are found in size enhancement contributions of backscatter coefficients. Similar to particle number, particles with diameters smaller than 100 nm contributes little to the enhancements of both backscatter and extinction.

Figure 3b also shows that different $\kappa_F$ is sensitive to the hygroscopicity of different size. Size-dependent hygroscopicity is important to estimate CCN rather than a bulk hygroscopicity information, especially for different supersaturation conditions. One humidogram may indicate the bulk hygroscopicity, but it is the hygroscopicity of small particles that influences CCN number concentrations most. Using $\kappa_F$ of all the $3\beta+2\alpha$ can provide some information about the hygroscopicity of small particles.

Comparing sensitive size of optical properties and critical diameters at different supersaturations, $3\beta+2\alpha$ MWRL systems have potential to retrieve CCN number concentrations at supersaturations smaller than 0.20%. It is not recommended to estimate CCN concentrations using lidar data at supersatations larger than 0.40%.

4.14.2 CCN number concentrations retrieved with error-free data

With error-free data as input, the model predicted extinction-related activation ratio at 532 nm ($\text{AR}_{532}$) and the retrieved CCN number concentrations at supersaturations of 0.07%, 0.10%, and 0.20% are compared to the theoretical calculated values. A total of 80575 pairs of data calculated from campaign C5 are used for verification. The retrieval results are displayed in Fig. 4. The values $\text{AR}_{532}$ at a specific supersaturation are distributed in a wide range and can span over an order of magnitude, indicating that the relationship between CCN and optical parameters is very complex. According to Fig. 4, all data points are distributed almost evenly on both sides of the 1:1 line and the relative errors of most points are within 20%. The determination coefficients ($R^2$) of CCN concentrations are all larger than 0.97, and the results do not show obvious systematic deviations.
The retrieval errors are found to grow with supersaturation. Retrieval results for higher supersaturations (i.e. 0.40% and 0.80%) is displayed in Fig. S4-S8 in the Supplement. There are larger errors for supersaturations of 0.40% and 0.80%. Only 47.76% of the retrieved CCN number concentration at supersaturation of 0.80% have relative errors less than 20%. The results are consistent with the previous analysis in Sect. 3.1, which means demonstrate again that lidars may not be sufficient enough to retrieve CCN number concentrations at supersaturations larger than 0.40%.

4.24.3 Importance of size-related and hygroscopicity-related parameters

RF models can evaluate the importance of features (input parameters) by calculating the mean decrease impurity (MDI) for each feature among all the trees in the forest. The MDIs and corresponding standard deviations of each parameter at different supersaturations are shown in Fig. 5. Importance of the nine input parameters varies with supersaturations. For 0.07% and 0.10%, $\kappa_{a355}$ and $\kappa_{b1064}$ are the two most important parameters, showing the impact of hygroscopicity on the relationship between CCN and optical properties. For 0.20%, $\hat{d}_{a355,532}$ becomes much more important. Among the nine input parameters, $\kappa_\xi$ are denoted as hygroscopicity-related parameters, and $\hat{d}_\xi$ are denoted as size-related parameters. Particularly, $s_a$ can be regarded as both size- and hygroscopicity-related parameter. As is shown in Fig. 5, hygroscopicity-related parameters, especially $\kappa_{a355}, \kappa_{b1064}$, and $s_{532}$, play crucial roles in retrieving CCN. Size-related parameters have already been proved to be vital in retrieving CCN, however, humidogram parameters $\kappa_\xi$ have not been implemented in previous methods. CCN concentrations retrieved with and without $\kappa_\xi$ are compared to show the importance of $\kappa_\xi$. When retrieving CCN without $\kappa_\xi$, the RF model is also trained with datasets from campaign C1-C4, but the input data only contains Ångström exponents and lidar ratios. The retrieved CCN concentrations are all compared with datasets from campaign C5, and the results are listed in Table 5. $R^2$ of retrieved CCN decreases from 0.991 to 0.887 for supersaturations of 0.07%, from 0.992 to 0.857 for 0.10%, and from 0.973 to 0.785 for 0.20%. Retrieval errors also increase overwhelmingly, and there are significant positive systematic biases. Parameters which are derived from backscatter and extinction enhancements, $\kappa_\xi$, are indispensable parameters in CCN retrieval.

4.34.4 Impact of systematic and random error on CCN retrieval

Figure 6 shows the relative errors of CCN retrieved with systematic errors in backscatter and extinction. Errors of retrieved CCN increase as errors of backscatter and extinction increase, and higher supersaturations are more affected by errors of optical parameters. Errors in extinction coefficients at 355 nm ($\alpha_{355}$) influence the retrieval results most. In average, a positive relative error of 20% in $\alpha_{355}$ will cause about 20% overestimate in CCN number concentrations for supersaturation of 0.07%, about 40% overestimate for 0.10%, and about 60% overestimate for 0.20%. A negative error of 20% in $\alpha_{355}$ will underestimate CCN concentrations, and the degree of impact is slightly smaller than positive error. Errors in extinction coefficient at 532 nm ($\alpha_{532}$) and at 355nm have opposite effect on retrieval error. Bigger $\alpha_{355}$ means more small particles and higher number concentrations, and bigger $\alpha_{532}$ means more large particles. Errors in $\alpha_{532}$ do not show significant impact at supersaturations
of 0.07% and 0.10%, but an overwhelming effect is found at supersaturations of 0.20%. It is interesting to note that the errors in backscatter coefficients do not affect the results much. However, in practical applications of MWRLs, the errors in extinction are always much larger than the errors of backscatter. If the error of retrieved CCN concentrations needs to be limited to 20% at supersaturation of 0.20%, the errors of retrieved extinction coefficients should to be controlled within 5%.

The test result of systematic error in RH is shown in Fig. 7. When RH has a negative systematic error, CCN concentrations are overestimated, and the extent of overestimation increases as the error increase. A negative error of 10% in RH will overestimate CCN at supersaturations at 0.20% by about 60% in average, and the standard deviation is over 60%. Effects of positive errors in RH is much smaller than negative errors but more complex. The standard deviations of retrieval relative error increase with RH error, and the extreme value of the mean retrieval error appears at the RH error of 5%.

Underestimating RH will cause much more errors than overestimation. Great care should be paid to RH profiles if enhancements of backscatter and extinction with RH are utilized.

The relative error of retrieved CCN with random errors are presented in Table 6. The mean values of relative error is -2.8%, -1.3%, and 1.3% for CCN at supersaturations of 0.07%, 0.10%, and 0.20%, respectively, and the corresponding standard deviations are 29.7%, 31.5%, and 42.9%. The impact of random errors on the nine input parameters is also evaluated and is shown in Fig. 8. Random errors (10% for backscatter and extinction, and 5% RH) underestimate $\kappa_\xi$ by 30%-35% in average, and the standard deviations are about 40% or more. $s_{\alpha 355}$, $s_{\alpha 532}$, and $\hat{\beta}_{532}^{1064}$ are overestimated by 5%-10%.

5 Summary

CCN number concentration at cloud base is a crucial and scarce parameter to constrain the relationship between aerosols and clouds. A new method to retrieve CCN number concentrations using backscatter and extinction coefficients from MWRL measurements is proposed. Enhancements of backscatter and extinction coefficients with RH are implemented to derive dry backscatter/extinction $\xi_{\text{dry}}$ and humidogram parameter $\kappa_\xi$. The ratio of CCN number concentration to dry backscatter or extinction coefficient $AR_\xi$, which is estimated by $\kappa_\xi$, Ångström exponents, and lidar ratios, is introduced to retrieve CCN number concentrations.

The method is established and verified by theoretical simulations using Mie theory and $\kappa$-Köhler theory with in situ measured particle size distributions, mixing states, and chemical compositions. The values of $AR_\xi$ are found to have large variations due to different size distributions and hygroscopicity. Theoretical analyses show that optical properties provided by current $3\beta+2\alpha$ MWRL systems basically contains size distribution and hygroscopicity information of particles with diameters larger than 100 nm, which only fits the critical diameters for supersaturations lower than 0.20%. Accordingly, CCN number concentrations at supersaturations of 0.07%, 0.10%, and 0.20% are retrieved. The performance of the new method is evaluated with error-free data, and CCN number concentrations at all three supersaturations are in good agreements with theoretical calculated values. Sensitivity tests are carried out to show the influence of systematic and random errors of lidar-derived optical properties and auxiliary RH profiles on CCN retrieval. Systematic errors in extinction coefficients and RH are found to have large impact on
error in retrieved CCN. Parameters fitted from backscatter and extinction enhancements (i.e. $\xi_{\text{dry}}$ and $\kappa_\xi$) is significantly influenced by RH. The uncertainty of RH profiles derived by remote sensing techniques is a major problem in CCN retrieval. Optical properties near cloud base from lidar measurements always influenced by high RH. Thus, transforming backscatter and extinction coefficients at ambient RH to dry conditions is a must for CCN retrieval, and accurate RH profiles are highly demanded.

The importance of humidogram parameters $\kappa_\xi$ is demonstrated by comparing the error of CCN concentration retrieved with and without $\kappa_\xi$. Neglecting hygroscopicity information contained in backscatter and extinction enhancements will bring huge errors to CCN retrieval by lidars. The performance of two parameterization schemes for backscatter and extinction humidograms are evaluated. The $\kappa$-equation shows better performance on inferring dry backscatter and extinction than $\gamma$-equation. The $\kappa$-equation, therefore, is recommended to describe the hygroscopic behaviors of the backscatter and extinction coefficients from lidar measurements. The fitted hygroscopic parameter are found to be sensitive to fitting RH range when the RH range is limited and relatively high (between 60%-90%). This is an extreme essential problem for current research for aerosol hygroscopicity with lidar measurements. Great care should be paid to the RH range when evaluating the hygroscopic growth of the lidar-related optical properties.

It should be noted that the theoretical analyses in this paper are based on datasets of continental aerosols, and the implement of Mie theory also limits the scope of the results. The results can be applied in the North China Plain but are not fit for sea salts and mineral dust. Studies with datasets of other aerosol types should be carried out in the future. Although the applicability of this new method is limited by large uncertainties in RH profiles, comparison between real measured MWRL data and airborne in situ measurement should also be conducted.

This work furthers our understanding of the relationship between CCN and aerosol optical properties and providing an optional way to retrieve CCN number concentration profiles from lidar measurements. The newly proposed method has potential to provide long-term CCN at cloud base for aerosol-cloud-interaction studies.

**Author contribution.** C. Zhao and C. Li determined the main goal of this study. W. Tan and G. Zhao designed the methods. W. Tan carried them out and prepared the manuscript with contributions from all co-authors.

**Competing interests.** The authors declare that they have no conflict of interest.

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References


**Table 1.** Locations, time periods, parameters, and instruments of five field campaigns

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<td>7 March to 4 April, 2009</td>
<td>12 July to 14 August, 2009</td>
<td>22 July to 30 August, 2012</td>
<td>9 July to 30 August, 2013</td>
<td>4 June to 14 July, 2014</td>
</tr>
<tr>
<td>PNSD</td>
<td>TSMPS+APS</td>
<td>TSMPS+APS</td>
<td>SMPS+APS</td>
<td>TSMPS+APS</td>
<td>TSMPS+APS</td>
</tr>
<tr>
<td>(m_{\text{BC}})</td>
<td>MAAP</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>HBF</td>
<td>TSI 3563-nephelometer</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Size-resolved chemical composition</td>
<td>–</td>
<td>substrates sampled by BLPI</td>
<td>–</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Location</th>
<th>Wuqing</th>
<th>Wuqing</th>
<th>Xianghe</th>
<th>Xianghe</th>
<th>Wangdu</th>
</tr>
</thead>
<tbody>
<tr>
<td>Campaign-name</td>
<td>C1</td>
<td>C2</td>
<td>C3</td>
<td>C4</td>
<td>C5</td>
</tr>
<tr>
<td>Time-period</td>
<td>7 March to 4 April, 2009</td>
<td>12 July to 14 August, 2009</td>
<td>22 July to 30 August, 2012</td>
<td>9 July to 30 August, 2013</td>
<td>4 June to 14 July, 2014</td>
</tr>
<tr>
<td>PNSD</td>
<td>TSMPS+APS</td>
<td>TSMPS+APS</td>
<td>SMPS+APS</td>
<td>TSMPS+APS</td>
<td>TSMPS+APS</td>
</tr>
<tr>
<td>(m_{\text{BC}})</td>
<td>MAAP</td>
<td>MAAP</td>
<td>MAAP</td>
<td>MAAP</td>
<td>MAAP</td>
</tr>
<tr>
<td>HBF</td>
<td>TSI 3563</td>
<td>TSI 3563</td>
<td>TSI 3563</td>
<td>TSI 3563</td>
<td>TSI 3563</td>
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<tr>
<td>Size-resolved chemical composition</td>
<td>–</td>
<td>substrates sampled by BLPI</td>
<td>–</td>
<td>–</td>
<td>–</td>
</tr>
</tbody>
</table>
Table 2. Slopes of linear regressions, determination coefficients ($R^2$), and relative errors (RE) between Mie model simulated particle dry backscatter/extinction coefficients and those inferred from humidogram functions. 404575 pairs of the simulations from in situ data set are used. The RE are given in the form of mean value ± one standard deviation (std).

<table>
<thead>
<tr>
<th>RH (%)</th>
<th>$\xi$</th>
<th>$\gamma$-equation</th>
<th>$\kappa$-equation</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>slope</td>
<td>$R^2$</td>
<td>RE(%)</td>
</tr>
<tr>
<td>60-90</td>
<td>$\alpha_{355,dry}$</td>
<td>0.850</td>
<td>0.998</td>
</tr>
<tr>
<td></td>
<td>$\alpha_{532,dry}$</td>
<td>0.820</td>
<td>0.998</td>
</tr>
<tr>
<td></td>
<td>$\beta_{355,dry}$</td>
<td>0.784</td>
<td>0.960</td>
</tr>
<tr>
<td></td>
<td>$\beta_{532,dry}$</td>
<td>0.812</td>
<td>0.972</td>
</tr>
<tr>
<td></td>
<td>$\beta_{1064,dry}$</td>
<td>0.878</td>
<td>0.986</td>
</tr>
<tr>
<td>60-70</td>
<td>$\alpha_{355,dry}$</td>
<td>0.913</td>
<td>1.000</td>
</tr>
<tr>
<td></td>
<td>$\alpha_{532,dry}$</td>
<td>0.900</td>
<td>0.999</td>
</tr>
<tr>
<td></td>
<td>$\beta_{355,dry}$</td>
<td>0.939</td>
<td>0.989</td>
</tr>
<tr>
<td></td>
<td>$\beta_{532,dry}$</td>
<td>0.939</td>
<td>0.990</td>
</tr>
<tr>
<td></td>
<td>$\beta_{1064,dry}$</td>
<td>0.966</td>
<td>0.997</td>
</tr>
<tr>
<td>70-80</td>
<td>$\alpha_{355,dry}$</td>
<td>0.852</td>
<td>0.999</td>
</tr>
<tr>
<td></td>
<td>$\alpha_{532,dry}$</td>
<td>0.827</td>
<td>0.998</td>
</tr>
<tr>
<td></td>
<td>$\beta_{355,dry}$</td>
<td>0.799</td>
<td>0.950</td>
</tr>
<tr>
<td></td>
<td>$\beta_{532,dry}$</td>
<td>0.833</td>
<td>0.966</td>
</tr>
<tr>
<td></td>
<td>$\beta_{1064,dry}$</td>
<td>0.898</td>
<td>0.987</td>
</tr>
<tr>
<td>80-90</td>
<td>$\alpha_{355,dry}$</td>
<td>0.756</td>
<td>0.922</td>
</tr>
<tr>
<td></td>
<td>$\alpha_{532,dry}$</td>
<td>0.702</td>
<td>0.994</td>
</tr>
<tr>
<td></td>
<td>$\beta_{355,dry}$</td>
<td>0.547</td>
<td>0.848</td>
</tr>
<tr>
<td></td>
<td>$\beta_{532,dry}$</td>
<td>0.593</td>
<td>0.925</td>
</tr>
<tr>
<td></td>
<td>$\beta_{1064,dry}$</td>
<td>0.702</td>
<td>0.934</td>
</tr>
</tbody>
</table>
Table 3. Slopes of linear regressions and determination coefficients (R²) between $\gamma_\xi$ or $\kappa_\xi$ fitted from RH range 60%-90% and those fitted from limited RH ranges (60%-70%, 70%-80%, and 80%-90%).

<table>
<thead>
<tr>
<th>RH (%)</th>
<th>$\xi$</th>
<th>$\gamma_\xi$</th>
<th>$\kappa_\xi$</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>slope</td>
<td>R²</td>
<td>slope</td>
</tr>
<tr>
<td>60-70</td>
<td>$\alpha_{355}$</td>
<td>0.992</td>
<td>0.958</td>
</tr>
<tr>
<td></td>
<td>$\alpha_{532}$</td>
<td>0.969</td>
<td>0.978</td>
</tr>
<tr>
<td></td>
<td>$\beta_{355}$</td>
<td>1.019</td>
<td>0.814</td>
</tr>
<tr>
<td></td>
<td>$\beta_{532}$</td>
<td>0.790</td>
<td>0.797</td>
</tr>
<tr>
<td></td>
<td>$\beta_{1064}$</td>
<td>0.806</td>
<td>0.834</td>
</tr>
<tr>
<td>70-80</td>
<td>$\alpha_{355}$</td>
<td>1.021</td>
<td>0.996</td>
</tr>
<tr>
<td></td>
<td>$\alpha_{532}$</td>
<td>1.015</td>
<td>0.997</td>
</tr>
<tr>
<td></td>
<td>$\beta_{355}$</td>
<td>1.115</td>
<td>0.968</td>
</tr>
<tr>
<td></td>
<td>$\beta_{532}$</td>
<td>1.078</td>
<td>0.973</td>
</tr>
<tr>
<td></td>
<td>$\beta_{1064}$</td>
<td>0.999</td>
<td>0.979</td>
</tr>
<tr>
<td>80-90</td>
<td>$\alpha_{355}$</td>
<td>0.941</td>
<td>0.939</td>
</tr>
<tr>
<td></td>
<td>$\alpha_{532}$</td>
<td>0.957</td>
<td>0.969</td>
</tr>
<tr>
<td></td>
<td>$\beta_{355}$</td>
<td>0.741</td>
<td>0.679</td>
</tr>
<tr>
<td></td>
<td>$\beta_{532}$</td>
<td>0.970</td>
<td>0.851</td>
</tr>
<tr>
<td></td>
<td>$\beta_{1064}$</td>
<td>1.090</td>
<td>0.816</td>
</tr>
</tbody>
</table>
Table 4. Lidar derived parameters for predicting optical-related CCN activation ratio $\text{AR}_\text{e} / \text{AR}_\xi$

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>$\kappa_{\alpha 355}$</td>
<td>Fitted parameter of extinction humidogram at 355 nm in $\kappa$-equation form</td>
</tr>
<tr>
<td>$\kappa_{\alpha 532}$</td>
<td>Fitted parameter of extinction humidogram at 532 nm in $\kappa$-equation form</td>
</tr>
<tr>
<td>$\kappa_{\beta 355}$</td>
<td>Fitted parameter of backscatter humidogram at 355 nm in $\kappa$-equation form</td>
</tr>
<tr>
<td>$\kappa_{\beta 532}$</td>
<td>Fitted parameter of backscatter humidogram at 532 nm in $\kappa$-equation form</td>
</tr>
<tr>
<td>$\kappa_{\beta 1064}$</td>
<td>Fitted parameter of backscatter humidogram at 1064 nm in $\kappa$-equation form</td>
</tr>
<tr>
<td>$s_{\alpha 355}$</td>
<td>Particle dry lidar extinction-to-backscatter ratio at 355 nm</td>
</tr>
<tr>
<td>$s_{\alpha 532}$</td>
<td>Particle dry lidar extinction-to-backscatter ratio at 532 nm</td>
</tr>
<tr>
<td>$\lambda_{\alpha 355 &amp; 532}$</td>
<td>Ångström exponent of particle dry extinction coefficients between 355 and 532 nm</td>
</tr>
<tr>
<td>$\lambda_{\beta 532 &amp; 1064}$</td>
<td>Ångström exponent of particle dry backscatter coefficients between 532 and 1064 nm</td>
</tr>
</tbody>
</table>
Table 5. Slopes of linear regressions, determination coefficients (R²), and relative errors (RE) between theoretical calculated CCN number concentrations and CCN number concentrations retrieved with/without $\kappa_\xi$ as input parameter. The relative errors are given in the form of mean value ± one standard deviation (std).

<table>
<thead>
<tr>
<th>Supersaturation Ratio</th>
<th>With $\kappa_\xi$</th>
<th>Without $\kappa_\xi$</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>slope</td>
<td>R²</td>
</tr>
<tr>
<td>0.07%</td>
<td>0.991</td>
<td>0.991</td>
</tr>
<tr>
<td>0.10%</td>
<td>0.992</td>
<td>0.989</td>
</tr>
<tr>
<td>0.20%</td>
<td>1.005</td>
<td>0.973</td>
</tr>
</tbody>
</table>
Table 6. Mean and one standard deviation (std) values of relative errors in retrieved CCN number concentrations at different supersaturations with error-free and random error (10% for backscatter/extinction ratio and 5% for relative humidity) conditions.

<table>
<thead>
<tr>
<th>Supersaturation Ratio</th>
<th>Error-free (mean ± std)</th>
<th>Random Error (mean ± std)</th>
</tr>
</thead>
<tbody>
<tr>
<td>0.07%</td>
<td>-0.8% ± 6.0%</td>
<td>-2.8% ± 29.7%</td>
</tr>
<tr>
<td>0.10%</td>
<td>0.1% ± 6.3%</td>
<td>-1.3% ± 31.5%</td>
</tr>
<tr>
<td>0.20%</td>
<td>3.9% ± 9.0%</td>
<td>1.3% ± 42.9%</td>
</tr>
</tbody>
</table>
Figure 1. (a) Boxplot of particle number size distributions (PNSDs) in the datasets from five field campaigns. Each PNSD is normalized by its maximum value at the peak diameter. Green markers “+” represent the mean value of each diameter. The boxes extend from the lower to upper quartile values, with orange lines at the median. The whiskers extend from the box to the minimum/maximum values or extend from the box by 1.5 times of interquartile range. The flyers are not shown in the plot. (b) Twenty-five typical size-resolved $\kappa$ distributions. Each dotted line with color represents one size-resolved $\kappa$ distribution. The solid black line represents the mean value of the size-resolved $\kappa$ distributions.
Figure 2. (a) Cumulative contributions (accumulate from large particle size to small particle size) of particle number concentrations (measured), dry particle backscatter coefficients (simulated), and dry particle extinction coefficients (simulated). The solid and dashed lines represent the median values of five field campaigns, and the shadows cover from the lower to upper quartile values. The box plots in brown contain statistical information about critical diameter of each supersaturation condition (right y-axis). The boxes extend from the lower to upper quartile values, with lines at the median. The whiskers extend from the box to the minimum/maximum values or extend from the box by 1.5 times of interquartile range. The markers “o” are the flyers. (b) Normalized size-resolved enhancement contributions when relative humidity increase from 60% to 90%, which are theoretically calculated by the mean particle number size distribution, the mean black carbon mass concentration (4.717 μg m⁻³), the mean mass ratio of externally mixed black carbon (0.664%), and the mean size-resolved κ distribution.
Figure 223. Schematic diagram of newly proposed method to retrieve cloud condensation nuclei number concentrations using multiwavelength Raman lidar.
Figure 3. (a) Cumulative contributions (accumulate from large particle size to small particle size) of particle number concentrations (measured), dry particle backscatter coefficients (simulated), and dry particle extinction coefficients (simulated). The solid and dashed lines represent the median values of five field campaigns, and the shadows cover from the lower to upper quartile values. The box plots in brown contain statistical information about critical diameter of each supersaturation condition (right y-axis). The boxes extend from the lower to upper quartile values, with lines at the median. The whiskers extend from the box to the minimum/maximum values or extend from the box by 1.5 times of interquartile range. The markers “o” are the flyers. (b) Normalized size-resolved enhancement contributions when relative humidity increases from 60% to 90%, which are theoretically calculated by the mean particle number size distribution, the mean black carbon mass concentration (4.717 μg m⁻³), the mean mass ratio of externally mixed black carbon (0.664%), and the mean size-resolved κ distribution.
Figure 4. Comparison of the theoretical calculated extinction-related CCN activation ratio at 532 nm and the model predicted extinction-related CCN activation ratios at 532 nm at supersaturations of (a) 0.07%, (c) 0.10%, and (e) 0.20%, and of the theoretical calculated CCN number concentrations and the retrieved CCN number concentrations at supersaturations of (b)
0.07%, (d) 0.10%, and (f) 0.20%. A total of 80575 pairs of data calculated from campaign C5 are used. The solid line is 1:1 line, and the dashed lines are 20% relative difference lines. Colors represent the relative density of the data points normalized by the maximum data density of each panel. The relative error showed in the figure is mean value ± one standard deviation.
Figure 5. Importance of each feature (input parameter) output by the Random Forest model for predicting optical-related CCN activation ratios at supersaturations of (a) 0.07%, (b) 0.10%, and (c) 0.20%. The values of feature importance indicate the decrease in impurity for each feature. The length of the bars represents the mean values among all trees and the error bars give the standard deviations.
Figure 6. Relative errors in retrieved CCN number concentrations at supersaturations of (a) 0.07%, (b) 0.10%, and (c) 0.20% as a function of systematic errors in backscatter or extinction. The markers are the mean values, and the error bars denote the standard deviations.
Figure 7. Relative errors in retrieved CCN number concentrations at supersaturations of 0.07%, 0.10%, and 0.20% as a function of systematic errors in relative humidity. The markers are the mean values, and the error bars denote the standard deviations.
**Figure 8.** Relative errors in fitted and calculated parameters with 10% random errors for backscatter/extinction and 5% random error for relative humidity. The dots are the mean values, and the error bars denote the standard deviations.
### S1 Site information

**Figure S1.** Site locations of Wuqing (39°23′N, 117°01′E, 7.4 m a.s.l), Xianghe (39°45′N, 116°58′E, 36 m a.s.l), and Wangdu (38°40′N, 115°08′E, 51 m a.s.l). Filled colors represents (a) elevation and (b) averaged aerosol optical depth (AOD). The AOD data is from reanalysis datasets of the Modern-Era Retrospective Analysis for Research and Applications, Version 2 (MERRA-2, Global Modeling and Assimilation Office (GMAO) (2015), MERRA-2 instM_2d_gas_Nx: 2d,Monthly mean,Instantaneous,Single-Level,Assimilation,Aerosol Optic al Depth Analysis V5.12.4, Greenbelt, MD, USA, Goddard Earth Sciences Data and Information Services Center (GES DISC), Accessed: [11 September 2018], 10.5067/XOGNBQEPLUC5). The averaged AOD is calculated from monthly mean values of all months during the five field campaigns shown in Table 1.
S2 Time series of the normalized particle number size distribution (PNSD)

Figure S2. Time series of the normalized particle number size distribution from the five field campaigns. (a)-(e) represents campaign C1-C5, respectively.
S3.1 Aerosol model assumptions

We assume the aerosol particles act as follows:
(1) Aerosol particles are spherical, which means the simulation results are not appropriate for mineral dust.
(2) Particles are partially externally mixed and partially core-shell mixed. Only two kinds of aerosols are contained: pure black carbon (BC) and BC coated by non-light-absorbing components. Note that if \( r_{\text{ext}} = 1 \), there exists pure BC and pure non-light-absorbing particles. \( r_{\text{ext}} \) is defined with Eq. (2) in the paper.
(3) The shape of BC mass size distribution (BCMSD) remains unchanged and the amount is related to the total BC mass concentration \( m_{\text{BC}} \). The fixed distribution comes from the average BCMSD obtained from Berner impactor measurements (Ma et al., 2012) and is shown in Fig. S3.

(4) \( r_{\text{ext}} \) is uniform among different particle sizes. Accordingly, number concentrations of externally mixed BC \( N_{\text{ext}} \) can easily be calculated from BCMSD and \( r_{\text{ext}} \):

\[
N_{\text{ext}}(D) = \frac{r_{\text{ext}} \cdot m_{\text{BC}}(D)}{\pi D^3 \cdot \rho_{\text{BC}}} \]  

(S1)

where \( D \) is diameter of the particle, \( \rho_{\text{BC}} \) is the density of BC. In this study, \( \rho_{\text{BC}} \) is assumed to be 1.5 g/cm\(^3\), which is also the density when retrieving \( r_{\text{ext}} \).

(5) For each particle size, the diameters of BC cores \( D_{\text{core}} \) are the same and can be derived using the following equation:

\[
D_{\text{core}}(D) = 3 \left[ \frac{6(1-r_{\text{ext}}) \cdot m_{\text{BC}}(D)}{\pi \rho_{\text{BC}} [N(D) - N_{\text{ext}}(D)]} \right]^{1/3} \]  

(S2)

where \( N(D) \) represents particle number size distribution (PNBSD).

Figure S32. Normalized size distribution of black carbon (BC) mass/volume concentration. The distribution is the average black carbon mass concentration obtained from Berner impactor measurements (Ma et al., 2012) and is normalized by the maximum value of the distribution.
(6) The size-resolved $\kappa$ distributions represent the bulk hygroscopicity of core-shell mixed particles, and externally mixed BC particles do not take up water.

All these assumptions above are strong and, to some extent, inconsistent with the reality, but are certified to be reasonable for calculating aerosol optical properties. Plenty of works on aerosol optical closure studies (Ma et al., 2011; Ma et al., 2012) and aerosol optical simulations (Kuang et al., 2017; Kuang et al., 2018; Zhao et al., 2018) have been carried out with these aerosol model assumptions. In particular, Zhao et al. (2017) use the aerosol model to simulate lidar backscatter and extinction under different relative humidity (RH) conditions.

### S3.2 Calculations of CCN number concentrations using $\kappa$-Köhler theory

According to $\kappa$-Köhler theory, CCN number concentrations at a specific supersaturation level can be calculated by PNSD and size-resolved $\kappa$ distribution. Based on Eq. (3), the critical supersaturation ratio required to activate a particle is decided by corresponding $\kappa$ and $D_{\text{dry}}$. In other word, we can get a critical activation dry diameter $D_c$ with a given supersaturation ratio and size-resolved $\kappa$ distribution. Then CCN number concentration $N_{\text{CCN}}(SS)$ thereby can be calculated with Eq. (S3):

$$N_{\text{CCN}}(SS) = \int_{D_{c,\text{SS}}}^{D_{\text{max}}} [N(D) - N_{\text{ext}}(D)] dD,$$  \hspace{1cm} (S3)

where $D_{\text{max}}$ correspond to the upper bounds of the measured PNSD. Note that we regard externally mixed pure BC as non-hygroscopic particles, so $r_{\text{ext}}$ and $m_{\text{BC}}$ should also be involved to calculate $N_{\text{ext}}$, which needs to be subtracted. Otherwise, $N_{\text{CCN}}$ will be overestimated.

### S3.3 Calculations of particle backscatter and extinction coefficients at different RH using $\kappa$-Köhler theroy and Mie theory

We use a modified BHMIE Fortran code and a modified BHCOAT Fortran code to calculate optical properties of homogeneous spherical particles and coated spherical particles, respectively. For a homogeneous spherical particle (i.e. externally mixed BC in this study), BHMIE can calculate particle scattering and extinction efficiency ($Q_{\text{sca}}$ and $Q_{\text{ext}}$) and scattering phase function with given light wavelength, particle diameter, and complex refractive index. For a coated spherical particle (i.e. core-shell mixed particle), diameters and complex refractive indices of both core and shell are needed in BHCOAT. The particle backscatter and extinction coefficients we need are derived from $Q_{\text{sca}}$ and $Q_{\text{ext}}$, and scattering phase function at 180° $P(\pi)$:

$$\alpha = \sum_i \left[ \int_{D_{\text{min}}}^{D_{\text{max}}} \frac{1}{4} D^2 Q_{\text{ext}}(D,i) N(D,i) dD \right],$$  \hspace{1cm} (S4)

$$\beta = \sum_i \left[ \int_{D_{\text{min}}}^{D_{\text{max}}} \frac{1}{16} D^2 Q_{\text{sca}}(D,i) P(\pi,D,i) N(D,i) dD \right],$$  \hspace{1cm} (S5)

where $D_{\text{min}}$ and $D_{\text{max}}$ correspond respectively to the lower and upper bounds of the measured PNSD, and the index $i$ indicates the mixing state of particles, i.e. external or core-shell in this paper. Polarization of lidar emitted laser is neglected.

Complex refractive indices are essential for Mie scattering calculation. Aerosol complex refractive indices are related to chemical components, morphology, and wavelengths of light (Cotterell et al., 2017). Both real part and imaginary part of refractive indices vary a lot in real ambient environment (Shettle and Fenn, 1979). Wavelength dependency of refractive indices...
at wavelengths of 355 nm, 532 nm, and 1064 nm are not significant except for brown carbon (Shettle and Fenn, 1979; Bond et al., 2013). Neglecting the effect of brown carbon in this study, we simply assume that complex refractive indices of corresponding components do not change with wavelengths. The refractive indices of BC and non-light-absorbing component (shell) are set to be 1.8+0.54i (Ma et al., 2012) and 1.53+10^{-7}i (Wex et al., 2002), respectively. Concerning aerosol hygroscopicity for core-shell mixed particles, diameters of BC cores \( D_{\text{core}} \) remain unchanged, and particle diameters \( D \) at different RH can be calculated with Eq. (3). The refractive index of the swelling shell (\( \tilde{m}_{\text{shell}} \)) is calculated following the volume mixing law (Hanel, 1968):

\[
\tilde{m}_{\text{shell}} = f_{\text{solute}} \cdot \tilde{m}_{\text{solute}} + (1-f_{\text{solute}}) \cdot \tilde{m}_{\text{water}}
\]

where \( \tilde{m}_{\text{solute}} \) is the refractive index of solute (i.e. 1.53+10^{-7}i in this study), \( \tilde{m}_{\text{water}} \) is the refractive index of pure water (1.33+10^{-7}i), and \( f_{\text{solute}} \) is the solute volume fraction of the in solution (shell), which is determined by Eq. (S7):

\[
f_{\text{solute}} = \frac{D_{\text{dry}} - D_{\text{core}}}{D^3 - D_{\text{core}}^3}
\]
Figure S4. Example of humidogram fitting using different functions. The example is calculated with one set of PNSD, BC, \( r_{\text{ext}} \), and size-resolved \( \kappa \) distribution. The dots represent Mie model simulations, and the dots in red (within RH range of 60-90%) are used to fit parameterization lines. The blue line is the result of \( \gamma \)-equation, and the green line represents the result of \( \kappa \)-equation.
Figure S5. Comparison between Mie model calculated dry particle backscatter or extinction and those fitted from humidograms.
S5 Relationship between the nine input parameters in Table 4

![Graph showing the relationship between the nine input parameters]

Figure S6. Relationship between $\kappa_a355$ and other 8 parameters.

Table S1. Determine coefficients ($R^2$) between the 9 input parameters in Table 4.

<table>
<thead>
<tr>
<th></th>
<th>$\kappa_a355$</th>
<th>$\kappa_a532$</th>
<th>$\kappa_\beta355$</th>
<th>$\kappa_\beta532$</th>
<th>$\kappa_\beta1064$</th>
<th>$s_a355$</th>
<th>$s_a532$</th>
<th>$\hat{d}_a355&amp;532$</th>
<th>$\hat{d}_\beta532&amp;1064$</th>
</tr>
</thead>
<tbody>
<tr>
<td>$R^2$</td>
<td>=</td>
<td>=</td>
<td>=</td>
<td>=</td>
<td>=</td>
<td>=</td>
<td>=</td>
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<td>=</td>
</tr>
<tr>
<td>$\kappa_a355$</td>
<td>0.880</td>
<td>=</td>
<td>=</td>
<td>=</td>
<td>=</td>
<td>=</td>
<td>=</td>
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</tr>
<tr>
<td>$\kappa_a532$</td>
<td>0.411</td>
<td>0.321</td>
<td>=</td>
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<tr>
<td>$\kappa_\beta355$</td>
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<td>0.644</td>
<td>0.450</td>
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<tr>
<td>$\kappa_\beta532$</td>
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<td>0.222</td>
<td>0.016</td>
<td>0.056</td>
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<tr>
<td>$\kappa_\beta1064$</td>
<td>0.085</td>
<td>0.079</td>
<td>0.680</td>
<td>0.292</td>
<td>0.019</td>
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<td>=</td>
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<tr>
<td>$s_a355$</td>
<td>0.026</td>
<td>0.070</td>
<td>0.117</td>
<td>0.423</td>
<td>0.070</td>
<td>0.360</td>
<td>=</td>
<td>=</td>
<td>=</td>
</tr>
<tr>
<td>$s_a532$</td>
<td>0.149</td>
<td>0.135</td>
<td>0.505</td>
<td>0.267</td>
<td>0.027</td>
<td>0.627</td>
<td>0.089</td>
<td>=</td>
<td>=</td>
</tr>
<tr>
<td>$\hat{d}_a355&amp;532$</td>
<td>0.062</td>
<td>0.023</td>
<td>0.550</td>
<td>0.169</td>
<td>0.464</td>
<td>0.409</td>
<td>0.023</td>
<td>0.317</td>
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</table>
Determine the tuning parameters for Random Forest model

In this study, we use the Python module *RandomForestRegressor* from the Python Scikit-Learn library (http://scikit-learn.org/stable/modules/generated/sklearn.ensemble.RandomForestRegressor.html, last access: 18 December 2018) as the Random Forest (RF) model tool. The tuning parameters of the model are listed in Table S1. More detailed meanings about the setting values please refer to the user guide provided by the website.

The most important tuning parameter in the model is the number of trees in the forest (*n_estimators*). The influence of *n_estimators* on the accuracy of retrieved CCN number concentrations is tested. Here we use the same test method as introduced in Section 4.2 in the paper. The determination coefficients ($R^2$) and the mean absolute relative error (MARE) between theoretical calculated and retrieved CCN number concentrations with different *n_estimators* are shown in Figure 3. The accuracy of the predictions increases as *n_estimators* grows bigger and are insensitive when *n_estimators* is bigger than 60. Considering computational and time cost, we finally set *n_estimators* to 100.

**Table S1.** Tuning parameters and their setting values of the Python module *RandomForestRegressor*.

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Description</th>
<th>Values</th>
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</thead>
<tbody>
<tr>
<td><em>n_estimators</em></td>
<td>The number of trees in the forest</td>
<td>100</td>
</tr>
<tr>
<td><em>criterion</em></td>
<td>The function to measure the quality of a split</td>
<td>“mse”</td>
</tr>
<tr>
<td><em>max_features</em></td>
<td>The number of features to consider when looking for the best split</td>
<td>“auto”</td>
</tr>
<tr>
<td><em>max_depth</em></td>
<td>The maximum depth of the tree</td>
<td>None</td>
</tr>
<tr>
<td><em>min_samples_split</em></td>
<td>The minimum number of samples required to split an internal node</td>
<td>2</td>
</tr>
<tr>
<td><em>min_samples_leaf</em></td>
<td>The minimum number of samples required to be at a leaf node</td>
<td>1</td>
</tr>
<tr>
<td><em>min_weight_fraction_leaf</em></td>
<td>The minimum weighted fraction of the sum total of weights (of all the input samples) required to be at a leaf node</td>
<td>0</td>
</tr>
<tr>
<td><em>max_leaf_nodes</em></td>
<td>Grow trees with <em>max_leaf_nodes</em> in best-first fashion</td>
<td>None</td>
</tr>
<tr>
<td><em>min_impurity_decrease</em></td>
<td>A node will be split if this split induces a decrease of the impurity greater than or equal to this value</td>
<td>0</td>
</tr>
</tbody>
</table>
Figure S73. Influence of the number of trees in RF model on retrieving CCN number concentrations. Dependencies of tree numbers on (a) $R^2$ and (b) MARE between theoretical calculated CCN number concentrations and retrieved CCN number concentrations under different supersaturations.
**Figure S84.** Comparison of the theoretical calculated extinction-related CCN activation ratio at 532 nm and the model predicted extinction-related CCN activation ratios at 532 nm at supersaturations of (a) 0.20%, (c) 0.40%, and (e) 0.80%, and of the theoretical calculated CCN number concentrations and the retrieved CCN number concentrations at supersaturations of (b) 0.20%, (d) 0.40%, and (f) 0.80%. A total of 80575 pairs of data calculated from campaign C5 are used. The solid line is 1:1 line, and the dashed lines are 20% relative difference lines. Colors represent the relative density of the data points normalized by the maximum data density of each panel. The relative error showed in the figure is mean value ± one standard deviation.
Figure S95. Comparison of the theoretical calculated extinction-related CCN activation ratio at 532 nm and the model predicted extinction-related CCN activation ratios at 532 nm at supersaturations of (a) 0.07%, (c) 0.10%, and (e) 0.20%, and of the theoretical calculated CCN number concentrations and the retrieved CCN number concentrations at supersaturations of (b) 0.07%, (d) 0.10%, and (f) 0.20%. A total of 80575 pairs of data calculated from campaign C5 are used. The solid line is 1:1 line, and the dashed lines are 20% relative difference lines. Colors represent the relative density of the data points normalized by the maximum data density of each panel. The relative error showed in the figure is mean value ± one standard deviation.
References


Hanel, G.: The real part of the mean complex refractive index and the mean density of samples of atmospheric aerosol particles, Tellus, 20, 371-379, 10.3402/tellusa.v20i3.10016, 1968.


