

1 **Advancements in the Aerosol Robotic Network (AERONET)**
2 **Version 3 Database – Automated Near Real-Time Quality**
3 **Control Algorithm with Improved Cloud Screening for Sun**
4 **Photometer Aerosol Optical Depth (AOD) Measurements**

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16

17 **Abstract.** The Aerosol Robotic Network (AERONET) provides highly accurate, ground-truth measurements of the
18 aerosol optical depth (AOD) using Cimel Electronique Sun/Sky radiometers for more than 25 years. In Version 2
19 (V2) of the AERONET database, the near real-time AOD was semi-automatically quality controlled utilizing mainly
20 cloud screening methodology, while additional AOD data contaminated by clouds or affected by instrument
21 anomalies were removed manually before attaining quality assured status (Level 2.0). The large growth in the
22 number of AERONET sites over the past 25 years resulted in significant burden to manually quality control millions
23 of measurements in a consistent manner. The AERONET Version 3 (V3) algorithm provides fully automatic cloud
24 screening and instrument anomaly quality controls. All of these new algorithm updates apply to near real-time data
25 as well as post-field deployment processed data, and AERONET reprocessed the database in 2018. A full algorithm
26 redevelopment provided the opportunity to improve data inputs and corrections such as unique filter specific
27 temperature characterizations for all visible and near-infrared wavelengths, updated gaseous and water vapor
28 absorption coefficients, and ancillary data sets. The Level 2.0 AOD quality assured data set is now available within
29 a month after post-field calibration, reducing the lag time from up to several months. Near real-time estimated
30 uncertainty is determined using data qualified as V3 Level 2.0 AOD and considering the difference between the
31 AOD computed with the pre-field calibration and AOD computed with pre-field and post-field calibration. This
32 assessment provides a near real-time uncertainty estimate where average differences of AOD suggest a +0.02 bias
33 and one sigma uncertainty of 0.02, spectrally, but the bias and uncertainty can be significantly larger for specific
34 instrument deployments. Long-term monthly averages analyzed for the entire V3 and V2 databases produced
35 average differences (V3–V2) of +0.002 with a ± 0.02 standard deviation, yet monthly averages calculated using
36 time-matched observations in both databases were analyzed to compute an average difference of -0.002 with a
37 ± 0.004 standard deviation. The high statistical agreement in multi-year monthly averaged AOD validates the
38 advanced automatic data quality control algorithms and suggests that migrating research to the V3 database will
39 corroborate most V2 research conclusions and likely lead to more accurate results in some cases.

40 1 Introduction

41 Space-based, airborne, and surface-based Earth observing platforms can remotely retrieve or measure aerosol
42 abundance. Each method has its own assumptions and dependencies in which the aerosol total column abundance
43 quantified by aerosol optical depth (AOD) introduces uncertainty in the retrieval or measurement. At the forefront,
44 ground based Sun photometry has been considered the ground truth in the measurement of AOD given minimal
45 assumptions, reliable calibration, and weak dependency on trace gases at carefully selected wavelength bands thus
46 resulting in highly accurate data (Holben et al., 1998). Meanwhile, AOD inferred from other observing platforms
47 such as satellite retrievals provide quantitative AOD but with significantly higher uncertainty (Remer et al., 2005; Li
48 et al., 2009; Levy et al., 2010; Sayer et al., 2013). Further, in situ measurements lack the ability to provide a reliable
49 columnar AOD due to the requirement of measuring aerosols vertically in each layer while not perturbing or
50 modifying the particle properties during the measurement (Redemann et al., 2003; Andrews et al., 2017). Light
51 Detection and Ranging (LIDAR) is fundamental in the determination of the vertical aerosol extinction distribution
52 (Welton et al., 2000; Omar et al., 2013). Quantification of columnar AOD from ground-based LIDAR, for example,
53 may be less reliable due to low signal to noise ratio during the daylight hours at high altitudes and below the overlap
54 region in which the aerosols very near the surface are poorly observed by LIDAR. Satellite retrieval issues include
55 determining the AOD for very high aerosol loading episodes, cloud adjacency effects, land/water mask depiction,
56 surface reflectance, highly varying topography, and aerosol type assumptions (Levy et al., 2010; Levy et al., 2013;
57 Omar et al., 2013). With each of these measurement platforms, uncertainties exist with AOD; however, these
58 concerns are minimized with AOD measurements from surface based Sun photometry such as from the federated
59 Aerosol Robotic Network (AERONET). Ground-based Sun photometry, a passive remote sensing technique, is
60 robust in measuring collimated direct sunlight routinely during the daytime in mainly cloud-free conditions (Shaw
61 1983; Holben et al., 1998; Takamura and Nakajima 2004, Smirnov et al., 2009; Kazadzis et al., 2018). While these
62 surface-based measurements are only point measurements, the federated AERONET provides measurements of
63 columnar AOD and aerosol characteristics over an expansive and diverse geographic area of the Earth's surface at
64 high temporal resolution.

65
66 Standardization of Sun photometer instrumentation, calibration, and freely available data dissemination of AOD and
67 related aerosol databases highlights the success of the federated AERONET. For more than 25 years, the
68 AERONET federation has expanded due to the investments and efforts of NASA (Goddard Space Flight Center,
69 GSFC) (Holben et al. 1998), University of Lille (PHOTométrie pour le Traitement Opérationnel de Normalisation
70 Satellitaire (PHOTONS)) (Goloub et al., 2007), University of Valladolid (Red Ibérica de medida Fotométrica de
71 Aerosoles (RIMA)) (Toledano et al., 2011), other subnetworks (e.g., AEROCAN (Bokoye et al., 2001), AeroSpan
72 (Mitchell et al., 2017), AeroSibnet (Sakerin et al., 2005), CARSNET (Che et al., 2015)), and collaborators at
73 agencies, institutes, universities, and individual scientists worldwide. Conceived in the late 1980s, AERONET's
74 primary objective was to provide an aerosol database for validation of Earth Observing System (EOS) satellite
75 retrievals of AOD and atmospheric correction (Kaufman and Tanré, 1996). In addition to columnar direct Sun AOD,
76 sky radiances were used to infer aerosol characteristics initially from Nakajima et al. (1996) (SkyRad.PAK) and

77 later by the Dubovik and King (2000) inversion algorithm to obtain products such as aerosol volume size
78 distribution, complex index of refraction, single scattering albedo, and phase functions.

79
80 AERONET is a network of autonomously operated Cimel Electronique Sun/sky photometers used to measure Sun
81 collimated direct beam irradiance and directional sky radiance and provide scientific quality column integrated
82 aerosol properties of AOD and aerosol microphysical and radiative properties (Holben et al., 1998;
83 <https://aeronet.gsfc.nasa.gov>). The development and growth of the program relies on imposing standardization of
84 instrumentation, measurement protocols, calibration, data distribution and processing algorithms derived from the
85 best scientific knowledge available. This instrument network design has led to a growth from two instruments in
86 1993 to over 600 in 2018. During that time, improvements were made to the Cimel instruments to provide weather-
87 hardy, robust measurements in a variety of extreme conditions. While the basic optical technology has evolved
88 progressively from analog to digital processing over the past 25 years, the most recent Sun/sky/lunar CE318 Model
89 T instruments provide a number of new capabilities in measurement protocols, integrity, and customizability
90 (Barreto et al., 2016).

91
92 All of the slightly varying models of the Cimel instruments can have measurement anomalies affecting direct Sun
93 measurements which include measurements in the presence of clouds, various obstructions in the instrument's field
94 of view, or systematic instrumental issues such as electrical connections, high dark currents, and clock shifts to
95 name a few. Some of these issues depend on instrument model and, for more than a decade, these anomalies have
96 been removed semi-automatically utilizing the cloud screening method developed by Smirnov et al. (2000) and
97 further quality controlled by an analyst to remove additional cloud contaminated data and instrument artifacts from
98 the database. Chew et al. (2011) identified up to 0.03 AOD bias at Singapore due to optically thin cirrus clouds for
99 Version 2 Level 2.0 data. Coincidentally, Huang et al. (2011) examined how cirrus clouds could contaminate AOD
100 measurements up to 25% (on average) of the data in April at Phimai, Thailand, in the Version 2 Level 2.0 data set.
101 The number of AERONET sites has increased to more than 600 sites in the network as of 2018 and the labor
102 intensive effort of quality controlling hundreds of thousands of measurements manually had resulted in a significant
103 delay of quality assured data (Level 2.0) in the AERONET Version 2 database.

104
105 With these issues at hand, the cloud screening quality control procedure was reassessed as well as all other aspects
106 of the AERONET processing algorithm including instrument temperature characterization, ancillary data set
107 updates, and further quality control automation. Utilizing these improvements, the Version 3 Level 2.0 quality
108 controlled dataset requires only the pre-field and post-field calibrations to be applied to the data so these data can
109 now be released within a month of the final post-field instrument calibration instead being of delayed up to several
110 months. As encouraged by the AERONET community, automatic quality controls in Version 3 are now also applied
111 to near real-time Level 1.5 AOD products allowing for improved data quality necessary for numerous applications
112 such as numerical weather prediction, atmospheric transport models, satellite evaluation, data synergism, and air
113 quality.

114

115 The AERONET Version 3 processing algorithm marks a significant improvement in the quality controls of the Sun
116 photometer AOD measurements particularly in near real-time. The revised AERONET algorithm is introduced by
117 first reviewing the calculations made to compute the AOD plus changes in the input data sets and the resulting
118 calculation of optical depth components. Next, the preprocessing steps and data prescreening are discussed for the
119 Version 3 quality control algorithm. Cloud screening and instrument quality control algorithm changes are
120 discussed with reference to Smirnov et al. (2000), and the solar aureole cirrus cloud screening quality control is
121 introduced for the first time. The automation of instrument anomaly quality controls and additional cloud screening
122 is described in the subsequent sections. Lastly, the AERONET Version 2 and Version 3 database results are
123 analyzed for the entire data set as well as for selected sites.

124 2 Aerosol Optical Depth Computation

125 Sun photometry is a passive remote sensing measurement technique in which mainly collimated light generally not
126 scattered or absorbed by the atmosphere illuminates a photodiode detector and this light energy is converted to a
127 digital signal. The digital signal (V) measured by the instrument is proportional to the solar irradiance. The relative
128 solar calibration is derived from the Langley method (Ångstrom 1970; Shaw et al., 1973) utilizing the digital counts
129 from the instrument versus the optical air mass to obtain the calibration coefficient (V_o) by choosing the intercept
130 where optical air mass is zero at the top of the atmosphere (Shaw, 1983). The relative extraterrestrial solar
131 irradiance is proportional to V_o . As shown by Holben et al. (1998) and for completeness in this discussion, the Beer-
132 Lambert-Bouguer law converted to instrument digital counts is shown in Eq. (1):

133

$$V(\lambda) = V_o(\lambda) * d^2 * \exp[-\tau(\lambda)_{Total} * m], \quad (1)$$

134 where $V(\lambda)$ is the measured spectral voltage of the instrument dependent on the wavelength (λ), $V_o(\lambda)$ is the relative
135 extraterrestrial spectral calibration coefficient dependent on λ , d is the ratio of the average to the actual Earth-Sun
136 distance (Michalsky, 1988; USNO, 2018), $\tau(\lambda)_{Total}$ is the total optical depth, and m is the optical air mass, which is
137 strongly dependent on the secant of the solar zenith angle (Kasten and Young, 1989). For the Cimel Sun
138 photometer, the voltage signal is expressed as integer digital counts or digital number (DN). The error in the $\tau(\lambda)_{Total}$
139 is generally dependent on the optical air mass (m) by $\delta\tau$ proportional to m^{-1} and hence the AOD computation error
140 will tend be maximum at $m=1$ (Hamonou et al., 1999). Cimel instrument repeatability is tested during calibration
141 procedures by comparing voltage ratios between the field instrument and reference instrument to be less than $\pm 1\%$
142 (Holben et al., 1998). The absolute uncertainty in the AOD measurement can be described as Eq. (2), with
143 calibration uncertainty of V_o being the overwhelmingly dominant error source:

144

$$\delta\tau = \frac{1}{m} * \left(\frac{\delta V}{V} + \frac{\delta V_o}{V_o} + \tau * \delta m \right) \cong \frac{1}{m} * \frac{\delta V_o}{V_o} \quad (2)$$

145

146 The spectral aerosol optical depth (AOD; $\tau(\lambda)_{Aerosol}$) should be computed from the cloud-free spectral total optical
 147 depth ($\tau(\lambda)_{Total}$) and the subtraction of the contributions of Rayleigh scattering optical depth and spectrally dependent
 148 atmospheric trace gases as shown in Eq. (3).

149

$$\tau(\lambda)_{Aerosol} = \tau(\lambda)_{Total} - \tau(\lambda)_{Rayleigh} - \tau(\lambda)_{H_2O} - \tau(\lambda)_{O_3} - \tau(\lambda)_{NO_2} - \tau(\lambda)_{CO_2} - \tau(\lambda)_{CH_4} \quad (3)$$

150

151 The Rayleigh optical depth ($\tau_{Rayleigh}$) is calculated based on the assumptions defined in Holben et al. (1998), optical
 152 air mass (Kasten and Young 1989), and formula by Bodhaine et al. (1999), except correcting the result based on the
 153 NCEP derived station pressure. The ozone (O_3) optical depth (τ_{O_3}) is dependent on the O_3 absorption coefficient
 154 (a_{O_3}) for the specific wavelength, the geographic and temporally dependent multi-year monthly climatological Total
 155 Ozone Mapping Spectrometer (TOMS) O_3 concentration (C_{O_3}), and the O_3 optical air mass (m_{O_3}) (Komhyr et al.,
 156 1989) using the following formulation: $\tau_{O_3} = a_{O_3} * C_{O_3} * m_{O_3}/m$. Similarly, nitrogen dioxide (NO_2) optical depth
 157 (τ_{NO_2}) is computed using absorption coefficient (a_{NO_2}) and geographic and temporally dependent multi-year monthly
 158 climatological Ozone Monitoring Instrument (OMI) NO_2 concentration (C_{NO_2}) assuming NO_2 scale height is equal to
 159 aerosol: $\tau_{NO_2} = a_{NO_2} * C_{NO_2}$. The water vapor optical depth (τ_{H_2O}) is calculated based filter dependent (e.g., 1020nm
 160 and 1640nm) A and B coefficients (discussed further below) and precipitable water in cm (u) using the following
 161 linear formulation: $\tau_{H_2O} = A + Bu$. The carbon dioxide (CO_2) optical depth (τ_{CO_2}) and methane (τ_{CH_4}) use station
 162 elevation dependent formulations: $\tau_{CO_2} = 0.0087 * P/P_0$ and $\tau_{CH_4} = 0.0047 * P/P_0$, assuming the U.S. standard
 163 atmosphere (1976) and absorption constants derived from HITRAN. Further descriptions of these calculations are
 164 provided below.

165

166 Table 1 provides a list of the spectral corrections used in the calculation of AOD and precipitable water from
 167 935nm. The nominal standard aerosol wavelengths are 340nm, 380nm, 440nm, 500nm, 675nm, 870nm, 1020nm,
 168 and 1640nm. For wavelengths shorter than and equal to 1020nm, these channels are measured using a Silicon
 169 photodiode detector with a spectral range from 320nm to 1100nm. If the Cimel instrument has an InGaAs detector
 170 with a 900nm to 1700nm spectral range, then the 1640nm wavelength is measured along with a redundant 1020nm
 171 measurement used to compare instrument optical characteristics between detectors, lenses, and collimator tubes.
 172 The Cimel SEAPRISM instrument models, which are deployed on ocean or lake platforms as part of the
 173 AERONET-Ocean Color component to retrieve normalized water leaving radiances at 8–12 additional visible band
 174 wavelengths for ocean and lake remote sensing studies, are similarly corrected for atmospheric effects (Zibordi et
 175 al., 2010).

176

177 Rayleigh optical depth calculations require the use of the station pressure (Bodhaine et al., 1999) as well as the
 178 optical air mass (Kasten and Young 1989). To determine AERONET site station pressure (P_s), the NCEP/NCAR
 179 reanalysis mean sea level pressure and geopotential heights at standard levels (1000hPa, 925hPa, 850hPa, 700hPa,
 180 and 600hPa) are fitted by a quadratic function in logarithmic space to infer the station pressure at the corresponding
 181 interpolated geopotential height. The NCEP/NCAR reanalysis data are available routinely at six hourly temporal

182 resolution and 2.5 degrees spatial resolution (Kalnay et al., 1996). Errors in the station pressure are generally less
 183 than 2hPa when the station elevation is accurate and the weather conditions are benign (i.e., atmospheric pressure
 184 tends to be stable), since aerosol measurements are typically performed in mainly cloud-free conditions.

185
 186 The 935nm wavelength is used to determine the water vapor optical depth contribution, which is consequently
 187 subtracted from the longer aerosol wavelengths (i.e., 709nm SEAPRISM, 1020nm, and 1640nm). The AOD at
 188 935nm is extrapolated based on the Ångström exponent (AE) computed from the linear regression of the AOD and
 189 wavelengths in logarithmic space within the range of 440–870nm excluding channels affected by water vapor
 190 absorption (Eck et al., 1999). To extract the precipitable water (PW) in cm from the 935nm measurements, the
 191 Rayleigh optical depth and the AOD components need to be subtracted from the total optical depth at 935nm. As a
 192 result, the dimensionless column water vapor abundance (u) is obtained using the following equations:

$$193 \quad T_W = \ln[T_{935nm[Measured]}] - \ln[T_{935nm[Extrapolated]}] \quad (4)$$

$$-\ln[T_W] = \ln[V_{o_{935nm}} * d^2] - \ln[V_{935nm}] - m * (\tau_{935nm_{AOD}} + \tau_{935nm_{Rayleigh}}) \quad (5)$$

$$\ln\left[\frac{T_W}{C}\right] = -A * (m_W * u)^B \quad (6)$$

$$u = \frac{\left[\frac{\ln T_W}{-A}\right]^{1/B}}{m_W} \quad (7)$$

194
 195 where T_W is the water vapor transmission and constants A and B are absorption constants unique to the particular
 196 935nm filter, C is an absorption constant assumed to be equal to one (Ingold et al., 2000), d and m are defined in Eq.
 197 (1), m_W is the water vapor optical air mass (Kasten et al., 1965), and u is the total column water vapor abundance
 198 (Schmid et al., 2001; Smirnov et al., 2004). The total column water vapor abundance (u) is converted to total
 199 column water content or PW by using the normalization factor ($u_o=10 \text{ kg/m}^2$) and dividing it by the mean value of
 200 water density ($\rho_o=1000 \text{ kg/m}^3$) to obtain water column height units of cm (Bruegge et al., 1992; Ingold et al., 2000).

201
 202 In the calculation of the filter dependent A and B constants, the water vapor absorption optical thickness is
 203 determined by the integration of water vapor extinction coefficient over height from the bottom to the top of the
 204 atmosphere. This calculation requires the following inputs to determine the extinction at each height: HITRAN
 205 spectral lines with assumed US1976 model standard atmosphere temperature and pressure profiles; the absorption
 206 continuum lookup table from the Atmospheric and Environmental Research (AER) Radiative Transfer Working
 207 Group (Clough et al., 1989; Mlawer et al., 2012); and Total Internal Partition Sums that define the shape and
 208 position of lines dependent on temperature (Gamache et al., 2017). Nine defined total column water vapor amounts
 209 (0.5 cm, 1.0 cm, 1.5 cm, 2.0 cm, 2.5 cm, 3.0 cm, 4.0 cm, 5.0 cm, and 6.5 cm) are used to generate water vapor

210 absorption optical depth lookup tables. From these lookup tables, transmittances are calculated based on the
211 bandpass and averaged spectral solar irradiance for the quiet Sun obtained from the University of Colorado
212 LASP/NRL2 model (Coddington et al., 2016) to generate filter-specific A and B coefficients. The one sigma
213 uncertainty in the calculation of PW in cm is expected to be less than 10% compared to GPS precipitable water
214 retrievals (Halthore et al., 1997; Bokoye et al., 2003; Sapucci et al., 2007; Alexandrov et al., 2009; Prasad et al.
215 2009; Bock et al., 2013; Van Malderen et al., 2014; Pérez-Ramírez et al., 2014; Campenelli et al., 2018). The
216 spectral water vapor optical thickness ($\tau_{H_2O}(\lambda)$) is determined by computing the average of all A and B constants
217 from the suite of filters affected by water vapor absorption (i.e., 709nm SEAPRISM, 935nm, 1020nm, and 1640nm)
218 in the AERONET database. The $\tau_{H_2O}(\lambda)$ is also dependent on the dimensionless total column water vapor abundance
219 (Michalsky et al., 1995; Schmid et al., 1996):

$$\tau_{H_2O}(\lambda) = \bar{A}(\lambda) + \bar{B}(\lambda) * u \quad (8)$$

221
222 The contribution of ozone (O_3) optical depth is determined utilizing the total column TOMS monthly average
223 climatology (1978–2004) of O_3 concentration at $1.00^\circ \times 1.25^\circ$ spatial resolution, the O_3 optical air mass using O_3
224 scale height adjustment by latitude (Komhyr et al., 1989), and the O_3 absorption coefficient (Burrows et al., 1999).
225 The OMI O_3 data set is not used here due to instrument sampling anomalies (McPeters et al., 2015). While the
226 TOMS O_3 data set is extensive and generally characterizes the distribution of O_3 , recent changes in concentration
227 could introduce some minor uncertainty in AOD. Similarly, the nitrogen dioxide (NO_2) optical depth is calculated
228 using the total column OMI monthly average climatology (2004–2013) of NO_2 concentration at $0.25^\circ \times 0.25^\circ$ spatial
229 resolution and the NO_2 absorption coefficient (Burrows et al., 1998). Tropospheric NO_2 is highly variable spatially
230 due to various source emissions and stratospheric NO_2 concentrations are more stable spatially than the tropospheric
231 NO_2 and can bias the calculation of AOD if neglected (Arola and Koskela 2004; Boersma et al., 2004). Therefore,
232 regions with high tropospheric NO_2 emission will tend to have greater proclivity for deviating from climatological
233 means. Further, NO_2 can vary significantly on the diurnal scale (Boersma et al., 2008). Improved satellite
234 observations, models, or collocation with surface-based PANDORA instruments measuring temporal total column
235 O_3 and NO_2 may assist in reducing the uncertainty and determination of the total column NO_2 optical depth
236 contribution in later versions of the algorithm (Herman et al., 2009; Tzortziou et al. 2012). Concentrations for
237 carbon dioxide (CO_2) and methane (CH_4) are assumed constant and optical depths are computed based on the
238 HITRAN-derived absorption coefficients of 0.0087 and 0.0047 for the 1640nm filter, respectively, and adjusted to
239 the station elevation.

240
241 The calibration of the AOD measurements is traced to a Langley measurement performed by a reference instrument
242 (Shaw 1983; Holben et al., 1998). The reference instruments obtain a calibration based on the Langley method
243 morning only analyses based on typically 4 to 20 days of data performed at a mountaintop calibration sites. The
244 primary mountaintop calibration sites in AERONET are located at Mauna Loa Observatory (19.536° N, 155.576°
245 W, 3402 m) on the island of Hawaii and Izana Observatory (28.309° N, 16.499° W, 2401 m) on the island of

246 Tenerife in the Canary Islands (Toledano et al., 2018). These reference instruments are routinely monitored for
247 stability and typically recalibrated every three to eight months. Reference instruments rotate between mountaintop
248 calibration sites and inter-calibration facilities at NASA GSFC (38.993° N, 76.839° W, 87 m) in Maryland,
249 Carpentras (44.083° N, 5.058° E, 107 m) in France, and Valladolid (41.664° N, 4.706° W, 705 m) in Spain, where
250 reference instruments operate simultaneously with field instruments to obtain pre-field and post-field deployment
251 calibrations. For periods when the AOD is low ($\tau_{440nm} < 0.2$), optical air mass is low ($m < 2$), and aerosol loading is
252 stable, the reference Cimel calibration may be transferred to field instruments (Holben et al., 1998). Eck et al. 1999
253 estimates the reference instrument calibration uncertainty impact on AOD varies from 0.0025 to 0.0055 with the
254 maximum representing uncertainty only in the UV channels (340nm and 380nm). In Version 3, the field instrument
255 AOD uncertainty is still estimated to be from 0.01 to 0.02 with the maximum representing the uncertainty only in
256 the UV channels (340nm and 380nm).

257
258 The Version 2 processing used default temperature corrections based on three sensor head temperature (T_S) ranges
259 ($T_S < 21^\circ\text{C}$, $21^\circ\text{C} \leq T_S \leq 32^\circ\text{C}$, and $T_S > 32^\circ\text{C}$) using a constant nominal temperature sensitivity only for the 1020nm filter
260 direct Sun measurements. In Version 3, measurement temperature sensitivity has been updated for all wavelengths
261 $\geq 400\text{nm}$ and all measurement types (i.e., direct solar, sky, water, and lunar viewing measurements). Beginning in
262 2010, the temperature sensitivity was characterized for almost all wavelengths uniquely for each Cimel instrument.
263 The temperature effect on signal (i.e., digital number per $^\circ\text{C}$) is a function of the combined sensitivity of the detector
264 and the filter material itself. If any Cimel data relying on a filter was in use prior to 2010 and the filter was not
265 temperature characterized, then the default values for the filter and manufacturer type are applied, if established.
266 Filters in the ultraviolet (i.e., 340nm and 380nm) are not measured for temperature dependence because of low
267 integrating sphere radiance output at these wavelengths. Due to temperature dependence of the field instrument and
268 the reference instrument, the Sun and sky calibration transfer needs to be adjusted by computing the ratio of the
269 Cimel temperature coefficients for each wavelength and for the temperature observed at the time of the calibration.
270 In addition, when the AOD is computed for field instruments, the sensor head temperature is measured for each
271 direct Sun measurement so these data can be adjusted to the temperature response of the instrument optics (i.e.,
272 combined effect of the detector and filters) and electronics.

273
274 The temperature response is measured at the AERONET calibration facilities using an integrating sphere and a
275 temperature chamber where the temperature is varied from -40°C to $+50^\circ\text{C}$. The wavelength dependent
276 temperature coefficient is typically determined from the slope of ordinary least squares regression fit of the digital
277 voltage counts versus the sensor head temperature reading. For this relationship, the second order polynomial fit is
278 computed for 1020nm, while other filters use either a linear or second order polynomial fit (depending on the larger
279 correlation coefficient). For Cimel Model 4 and some Model 5 instruments with two Silicon photodiode detectors,
280 the digital counts for solar aureole and sky instrument gains are used to determine temperature coefficients for each
281 detector (Holben et al., 1998; <https://aeronet.gsfc.nasa.gov>). Some Model 5 and all Model T instruments perform

282 the direct Sun and sky measurements on the same detector (Silicon or InGaAs) and typically utilize the solar aureole
283 gain digital counts (Barreto et al., 2016; <https://aeronet.gsfc.nasa.gov>).

284
285 According to Holben et al. (1998), all instruments generally perform measurements sequentially from longer
286 wavelength to the shortest wavelength filters on a rotating filter wheel inside the sensor head, which positions each
287 filter in front of the photodiode detector and behind the sensor head lenses and collimator tube. The robotically
288 controlled sensor head points automatically at the Sun based on the time and geolocation of the instrument. The
289 laboratory tuned 4-quadrant detector provides nearly perfect solar and lunar tracking to one motor step or $\sim 0.1^\circ$
290 immediately following the geographic pointing. A dual tube external collimator with internal baffles attached to the
291 top of the sensor head reduces stray light effects into the sensor head 1.2° field of view optical train.

292
293 The instrument performs measurements of the Sun using measurement triplets, that is, performing the series of
294 measurements of all filters at time hh:m0:00 (time notation for hours, minutes, seconds), where for duration of about
295 eight seconds, and then repeating these measurements at hh:m0:30 and hh:m1:00. The resulting one-minute
296 averaged measurement sequence is defined as a triplet measurement and the maximum to minimum range of these
297 measurements is termed the triplet variability. The triplet measurement advantageously allows for separation of
298 homogeneously dispersed aerosols versus highly temporally variable clouds. The triplet measurements are
299 performed either every 15 minutes for older Model 4 instruments or every three minutes for newer Model 5 and
300 Model T instruments increasing the temporal availability of the AOD measurements in the AERONET database.

301 **3 Automatic Quality Controls of Sun Photometrically Measured Aerosol Optical Depth**

302 The AERONET database has provided three distinct levels for data quality: Level 1.0, Level 1.5, and Level 2.0. In
303 Version 2, Level 1.0 was defined as prescreened data, Level 1.5 represented near real-time automatically cloud-
304 cleared data, and Level 2.0 signified automatically cloud-cleared, manually quality controlled data set with pre and
305 post-field calibrations applied. In Version 3, the definitions have been modified substantially for Level 1.5 and
306 Level 2.0. Version 3 Level 1.5 now represents near real-time automatic cloud screening and automatic instrument
307 anomaly quality controls and Level 2.0 additionally applies pre-field and post-field calibrations. The Version 3 fully
308 automated cloud screening and quality control checks eliminate the need for manual quality control and cloud
309 screening by an analyst and increases the timeliness of quality assured data. Note that in all cases each subsequent
310 data quality level requires the previous data level to be available as input (e.g., Level 1.5 requires Level 1.0 and
311 Level 2.0 requires Level 1.5). The following sections will describe these new definitions and automatic quality
312 controls in detail and the impact these new quality assurance measures have on the AERONET database.

313

314 **3.1 Preprocessing Steps and Prescreening**

315 Most preprocessing data quality criteria operate on voltage (V, expressed as the integer digital number (DN)) or
316 sensor head temperature (T_s). The impact of these conditions may immediately remove data from Level 1.0

317 consideration or later only impact Level 1.5 and Level 2.0 AOD. Each quality control section describes the
318 reasoning for the screening at the specified data quality level. Digital count anomalies typically result from
319 anomalous electronic issues such as very low or high battery voltages, malfunctioning amplifiers, or loose
320 connections of internal control box components. These digital count anomalies mostly affect older Cimel Model 4
321 (CE318-1) and Model 5 (CE318N) instruments (Holben et al., 1998; <https://aeronet.gsfc.nasa.gov>), while several of
322 these connection issues have been mitigated in the Cimel Model T (CE318-T) instruments (Barreto et al., 2016).

323 **3.1.1 Electronic Instability**

324 Cimel Model 4 instruments use a 16-bit analog/digital (A/D) converter in the processing unit in which the analog
325 signal from the sensor head detector to the control box is subject to electronic noise. Cimel Model 5 instruments use
326 a 16-bit A/D converter inside the sensor head and the instrument invokes electronic chopping to reduce electronic
327 noise. Cimel Model T instruments utilize an increased quantization from 16 bits to 24 bits, which significantly
328 reduces noise effects. Cimel Model 5 and Model T instruments internally adjust for the dark current (V_D) with each
329 measurement and no separate record is logged. Cimel Model 4 instruments perform V_D measurements after each
330 sky scan (approximately hourly) for each spectrally dependent instrument gain parameter (i.e., Sun, aureole, and
331 sky). Large V_D values generally represent significant instrument electronic instability. Quality controls applied to the
332 V_D will remove the entire day for Model 4 instrument data from all of the quality levels for either of the following
333 conditions: 1) a single dark current measurement is greater than 100 counts for greater than N-1 wavelengths, where
334 N is the total number of wavelengths or 2) more than three dark current measurements are greater than 100 counts
335 for three or more wavelengths.

336
337 Amplifiers in the Cimel Model 4 instruments can produce unphysical increases in the digital counts or decreases in
338 the AOD for the 340nm and 380nm wavelengths at large optical air mass (Fig. 1). These instability issues are
339 evaluated simply using a relative threshold with respect to the available visible wavelength AOD measurements. If
340 the τ_{380} is greater than $0.5 * \tau_{340}$ and $(\tau_{440} + \tau_{500 \text{ or } 675} < \tau_{380} + \tau_{340} - 2.0)$, then the triplet measurements for 340nm and
341 380nm are removed from the database for Level 1.5 and subsequent levels. These quality controls are limited to
342 Model 4 instruments that were not manufactured after 2001; however, the early AERONET database (1993–2005)
343 contains much of these data. New Cimel Model T instruments are replacing Model 4 instruments but over 40 Model
344 4 instruments remain active in 2018.

345
346 The instrument may rarely malfunction by producing constant digital voltages for triplet measurements and the
347 result of keeping these data in the database leads to unphysical variations in the AOD. A frequency analysis is
348 performed to determine if any digital number (DN) values occur more than 10 times in a day. If more than 50% of
349 the DNs are from the same triplet measurement, then this measurement is identified as an anomalous measurement.
350 If more than 50% of the triplet measurements in the day are considered anomalous, then the entire day will be
351 removed from Levels 1.5 and 2.0.

352 3.1.2 Radiometer Sensitivity Evaluation

353 The Cimel 4-quadrant solar near infrared detector requires enough sensitivity to track the Sun and a DN threshold of
354 100 in the near infrared is needed to have sufficient signal. Near infrared wavelengths (e.g., 1020nm) typically have
355 a higher measured solar DN(V) due to higher atmospheric transmission in the presence of fine mode dominated
356 aerosols even in very high aerosol loading conditions. When the DN ($V_{870\text{nm}}$ or $V_{1020\text{nm}}$) is less than 100 counts for
357 any measurement of the solar triplet, then the entire solar triplet AOD will be removed for all wavelengths from
358 Level 1.0 and subsequent levels due to potential solar tracking accuracy issues.

359
360 Version 2 data processing assessed the instrument electronic and diffuse light sensitivity by defining a digital
361 number (DN) of 10 to remove solar AOD triplet measurements. Electronic issues impact Cimel Model 4
362 instruments in the UV and short visible wavelengths due to high DN(V_D). Scattered diffuse light into the collimated
363 field of view can affect all instruments and produce unusual AOD changes with optical air mass especially when the
364 aerosol loading is high and optical air mass is large. The signal to noise ratio of the Cimel instrument requires setting
365 a minimum threshold for the determination of the solar measured DN(V) to limit the effect of diffuse radiance in the
366 instrument field of view (Sinyuk et al., 2012). When a dark current DN(V_D) (e.g., ~50–100) is nearly equal to or
367 larger than the measured solar DN(V) (e.g., ~25–50) will result in V and τ decreasing with increasing optical air
368 mass. All wavelengths are evaluated to determine if the measured solar DN(V) (subtracted from the closest
369 temporal dark current DN(V_D) for Model 4 instruments only) is less than $\text{DN}(V_O)/1500$, then the identified
370 wavelength will be removed from all AOD levels. A threshold of 1500 is calculated from a DN of 15000, a typical
371 average DN(V_O) for Cimel Models 4 and 5, normalized to a minimum signal DN of 10. The maximum product of
372 AOD times optical air mass ($\tau_m = \tau * m$) of approximately 7.3 is computed by the natural logarithm of 1500 (i.e., \ln
373 $(15000/10)$) for Cimel Model T instruments. For non-Model T instruments, the 100 DN threshold for 870nm and
374 1020nm limits the τ_m to approximately 5.0 (i.e., $\ln(15000/100)$) for only those two wavelengths. The τ_m maximum
375 threshold applies to all channels; however, the signal count can decrease significantly with optical air mass and
376 depend on the wavelength dependence of V_O . For values exceeding the τ_m maximum threshold, the diffuse radiation
377 increases the signal and, as a result, unfiltered AODs show a decrease in magnitude as optical air mass increases for
378 high AOD even when DN(V_D) equals zero. A measured solar DN(V) lower than the ratio $\text{DN}(V_O)/1500$ threshold
379 will result in the removal of the solar triplet AOD for the specific wavelength (Fig. 2).

380 3.1.3 Digital Number Triplet Variance

381 As mentioned in Sect. 2, the Cimel instrument performs a direct Sun triplet measurement at regular intervals
382 throughout the day. A variance threshold is applied based on the root mean square (RMS) differences of the triplet
383 measurements relative to the mean of these three values. If the $(\text{RMS}/\text{mean}) * 100\%$ of the digital number triplet
384 values is greater than 16%, then these data are not qualified as Level 1.0 AOD (Eck et al., 2014). The digital
385 number temporal variance threshold is sensitive to clouds with large spatial-temporal variance in cloud optical depth
386 and optically thick clouds such as cumulus clouds as well as issues due to poor tracking of the instrument.

387 **3.1.4 Sensor Head Temperature Anomaly Identification**

388 Each Cimel instrument has a fixed resistance (Model 4) or band gap (Models 5 and T) temperature sensor inside the
389 optical head within 0.5 cm of the detector, filter wheel, and optical train assembly. As discussed in Sect. 2, the
390 instrument optics and digital counts can have dependence to the sensor head temperature (T_S) which is saved with
391 each measurement triplet. Sensor head temperatures may be erroneous due to instrument electronic instability or
392 communication issues. These potentially unphysical values of T_S are evaluated by a number of algorithm steps such
393 as checks for 1) constant T_S values, 2) unphysical extreme high or low T_S , 3) potentially physical yet anomalously
394 low T_S with respect to the NCEP/NCAR reanalysis ambient temperatures, and 4) unphysical T_S decreases (dips) or
395 increases (spikes). When the algorithm removes a T_S reading or the T_S measurement is missing, an assessment is
396 made on the instrument temperature response based on $\pm 15^\circ\text{C}$ of the NCEP/NCAR reanalysis temperature for the
397 date and location to determine whether the temperature characterization coefficient for a specific wavelength would
398 result in a change of AOD by more than 0.02. If this condition is met for a specific wavelength, then data associated
399 with this wavelength-specific triplet measurement will be removed at Level 1.5 and subsequent levels while
400 preserving other less temperature dependent spectral triplet measurements.

401 **3.1.5 Eclipse Circumstance Screening**

402 During episodic solar or lunar eclipses, AOD will increase to the maximum obscuration of the eclipse at a particular
403 location on the Earth's surface. The AOD increases due to the reduction of the irradiance and the celestial body
404 (Moon or Earth) obscuring the calibrated light source (Sun or Moon). While any one point on Earth infrequently
405 experiences an eclipse, when an eclipse episode does occur, the eclipse can affect many locations nearly
406 simultaneously making manual removal tedious at sites distributed globally. To automate the removal of eclipse
407 episodes, the NASA solar and lunar eclipse databases are queried for eclipse circumstances based on geographic
408 position of the site to produce a table of eclipse episodes starting from 1992. The eclipse tool utilizes established
409 Besselian elements based on the Five Millennium Canon of Solar Eclipses: -1999 to +3000 (Espenak and Meeus
410 2006) to quantify the geometric and temporal position of the celestial bodies (Sun, Earth, and Moon), determine the
411 type of eclipse (e.g., partial, annular, total), and predict times of the various stages of the solar or lunar eclipse. For
412 the Version 3 database, the eclipse site-specific tables are used to discretely remove triplet measurements affected by
413 any stage of the eclipse circumstance. For example, during a solar eclipse, solar triplets will be removed between
414 the partial eclipse first contact to the partial eclipse last contact regardless of the eclipse obscuration or magnitude
415 for Level 1.5 data and subsequent levels (Fig. 3). The partial eclipse first contact is defined as the time at which the
416 penumbral shadow is visible at a point on the Earth's surface and the partial eclipse last contact is defined as the
417 time at which the penumbral shadow is no longer visible a point on the Earth's surface. Efforts to retain AOD during
418 solar eclipse episodes have been attempted by the authors in which up to 95% of the AOD can be corrected based on
419 adjusting calibration coefficients by the eclipse obscuration. However, spectral calibration coefficients also need to
420 be adjusted to account for the solar atmosphere spectral irradiance, which becomes more dominant during the solar
421 eclipse episode and is a topic of further investigation.

422 3.1.6 Very High AOD Retention

423 Cloud screening procedures in the next section may inadvertently remove aerosol in very high aerosol loading cases
424 due to biomass burning smoke and urban pollution as discussed by Smirnov et al. (2000). For Version 3, each triplet
425 reaching Level 1.0 is evaluated for possible retention in the event that a specific Level 1.5 cloud screening procedure
426 removes the triplet. When the AOD measurement for 870nm is >0.5 and AOD 1020nm >0.0 , these conditions will
427 potentially qualify the triplet for very high AOD retention. Further analysis is performed on those qualified triplets
428 to remove the effect of heavily cloud-contaminated data using the AE for the wavelength ranges of 675–1020nm or
429 870–1020nm (Eck et al., 1999). If the $AE_{675-1020nm} > 1.2$ (or $AE_{870-1020nm} > 1.3$, if AOD_{675nm} is not available), and the
430 AE for the same range is less than 3.0, then the triplet qualifies for very high AOD retention and the triplet can be
431 retained at Level 1.5 even if the measurement does not pass Level 1.5 cloud screening quality control steps in Sect.
432 3.2.

433 3.1.7 Total Potential Daily Measurements

434 Cloud screening methods in Sect. 3.2 may incompletely remove all cloud-contaminated points and leave data
435 fragments. To mitigate this issue, a methodology was developed based on the total number of potential
436 measurements in the day and calculated AE values. The total number of potential measurements in the day is
437 defined as the number of triplet measurements plus the number of wet sensor activations. If the number of
438 remaining measurements after all screening steps in Sect. 3.2 are performed is less than three measurements or less
439 than 10% of the potential measurements (whichever is greater), then the algorithm will remove the remaining
440 measurements. This condition is repeated after each cloud screening step in Sect. 3.2 and will only be activated
441 when the very high AOD restoration is not triggered (see Sect. 3.1.6) or when the $AE_{440-870nm}$ is less than 1.0 for a
442 triplet measurement indicating large particles such as clouds may contaminate the remaining measurements.

443 3.1.8 Optical Air Mass Range

444 The basic Cimel Sun photometer Sun and sky measurement protocols were specified to NASA requirements in
445 Holben et al. (1992, 1998, and 2006), and have only been slightly modified since that time for improved
446 measurement capability of the Model 5 and Model T instruments (Barreto et al., 2016). All instruments
447 systematically perform direct Sun measurements between the optical air mass (m) of 7.0 in the morning and m of 7.0
448 in the evening. In Version 2 and earlier databases, AERONET data processing limited the Level 1.5 and Level 2.0
449 AOD computation from m of 5.0 in the morning to m of 5.0 in the evening. The m limitation may avoid potential
450 error in the computation of the optical air mass at large solar zenith angles (Russell et al., 1993) and possible
451 increased cloud contamination (Smirnov et al., 2000). For Version 2 and 3 processing, the Kasten and Young 1989
452 formulation was used to account for very small differences in the optical air mass calculations at high solar zenith
453 angles. Noting that the AOD error ($\delta\tau/m$) has a minimum at large m (conversely a maximum at solar noon), the
454 maximum m of 5.0 was extended to m of 7.0 in Version 3 processing. The larger optical air mass range leads to an
455 increase in the number of solar measurements occurring in the early morning and the early evening contributing to
456 additional AOD measurements used for input for almucantar and hybrid inversions plus an increase in AOD

457 measurements at high latitude sites when solar zenith angles may be large even at solar noon. The impact on the
 458 cloud screening performance appears to be minimal for measurements closer to the horizon. The fidelity of the
 459 Version 3 cloud screening (see Sect. 3.2) AODs supports the extended optical air mass range for Level 2.0.

460 3.2 Level 1.5 AOD Cloud Screening Quality Controls

461 As discussed in Sect. 3.1, several preprocessed criteria and parameters are necessary to quality control the AOD data
 462 quality in near real-time (NRT). Cloud screening procedures proposed by Smirnov et al. (2000) were designated to
 463 remove or reduce cloud contaminated AOD measurements. However, these procedures also had the effect of
 464 surreptitiously removing occasionally other non-cloud anomalies such as repeated AOD diurnal dependence when
 465 AOD had a large maximum at midday and minimum at high optical air masses due to environmental impacts on the
 466 optical characteristics of the instrument (e.g., moisture on the sensor head lens or spider webs in the collimator
 467 tube). While these cloud screening methods have been implemented for about 25 years, the state of knowledge has
 468 progressed over this period and thus necessitates review and modification of cloud screening quality control
 469 procedures (Kaufman et al. 2005, Chew et al., 2011; Huang et al., 2011). The calculation of the AOD at Level 1.0
 470 essentially represents the following in Eq. (9):

$$471 \tau_{app\ Total} = \frac{1}{\Gamma_{anomaly}} \left(\tau_{aerosol} + \frac{\tau_{cirrus}}{C_{cirrus}} + \tau_{liquid\ cloud} + \tau_{eclipse} \right) \quad (9)$$

472 where $\tau_{app\ Total}$ is the apparent total optical depth, which at this point in the data processing, may be affected by the
 473 contributions of liquid cloud droplets ($\tau_{liquid\ cloud}$), cirrus amplification factor (C_{cirrus}) applied to the cirrus crystal
 474 optical depth (τ_{cirrus}) due to strong forward scattering into the field of view of the instrument, solar or lunar eclipses
 475 ($\tau_{eclipse}$), and instrument anomalies ($\Gamma_{anomaly}$ adjustment factor). Given cloud free conditions and perfect instrument
 476 operation, the additional non-aerosol τ components would be zero and C_{cirrus} and $\Gamma_{anomaly}$ would be one. However,
 477 the Cimel Sun photometer always attempts to measure the Sun if it can be tracked regardless of the total optical
 478 depth magnitude.

480
 481 Clouds are a major factor in the effort to quality control remotely sensed aerosol data (Smirnov et al. 2000; Martins
 482 et al. 2002; Kaufman et al., 2005; Chew et al., 2011; Kahn and Gaitley 2015). A significant portion of the liquid
 483 cloud contribution is removed by the prescreening prior to Level 1.0 as discussed in Sect. 3.1.3. The $\tau_{app\ Total}$ should
 484 be adjusted based on a multiplier dependent on the cirrus crystal size ($\tau_{correct} = C_{cirrus} * \tau_{app\ Total}$) according to Kinne et
 485 al. (1999). While this cirrus coefficient (C_{cirrus}) is not specifically modelled by Kinne et al. (1999) for the Cimel
 486 instrument field of view half angle of 0.6° , this multiplier is likely to be close to one for small cirrus crystals (e.g.,
 487 $r_{eff} = 6\mu\text{m} - 16\mu\text{m}$), but near two for larger cirrus crystal sizes (e.g., $r_{eff} = 25\mu\text{m} - 177\mu\text{m}$). These adjustment factors
 488 would result in the reduction of the $\tau_{app\ Total}$ due to forward scattering in the presence of cirrus. On the other hand,
 489 liquid water cloud droplets would significantly increase the $\tau_{app\ Total}$ in a manner similar to large dust particles.

490

491 Cimel instruments also may have internal and external anomalous conditions that modify the optical characteristics
492 or response of the instrument resulting in amplification or dampening impacts ($I_{anomaly}$) of varying magnitudes on
493 the computation of the $\tau_{app\ Total}$. These anomaly adjustments can be difficult to quantify and can have strong
494 dependence on optical air mass (m) or the sensor head temperature (T_S). As a result, the following sections will
495 describe the mechanisms in which these additional cloud and anomaly components are automatically eliminated or
496 reduced as close to zero as possible to provide a quality assured AOD ($\tau_{aerosol}$) after final calibration is applied (see
497 Sect. 4) across the global AERONET AOD database.

498 3.2.1 Cloud Screening Quality Controls

499 As Level 1.0 AOD data may have cloud contamination, these data should be considered as potentially cloud
500 contaminated where the triplet measurement represents the apparent AOD ($\tau_{app\ aerosol}$) as defined in the previous
501 section. Table 2 provides a summary of the cloud screening quality control changes from Version 2 to Version 3
502 and these changes are discussed in detail below and Sect. 3.2.2.

503
504 Cimel triplet measurements are performed typically every three minutes (every 15 minutes for older instrument
505 types) and these triplet measurements can detect rapid changes in the $\tau_{app\ aerosol}$ by analyzing the maximum to
506 minimum variability (i.e., the $\Delta\tau_{app\ aerosol}\{MAX-MIN\}$). Assuming that spatial and temporal variance of aerosols
507 plus clouds is much greater than aerosols alone, in many cases, $\Delta\tau_{aerosol}$ would be near zero and $\Delta\tau_{cloud}$ should be
508 much larger than zero when especially liquid phase cloud droplets exist. For Version 2 and earlier databases,
509 Smirnov et al. (2000) methodology utilized all available wavelengths to perform $\tau_{app\ aerosol}$ triplet screening for cloud
510 contamination. Therefore, large triplet variability would indicate the presence of clouds due to large $\Delta\tau_{cloud}$.
511 Analyses (e.g., Eck et al., 2018) have shown that removing the entire triplet measurement when only one or more of
512 the shorter wavelengths indicates a large variation ($\Delta\tau_{aerosol}(\lambda)$ much greater than zero) may not be the most robust
513 approach. For example, in cases of highly variable fine mode aerosols such as smoke can produce large triplet
514 variability as a result of the inhomogeneous nature of the aerosol plume especially for shorter wavelengths (e.g.,
515 340nm, 380nm, 440nm) where fine mode dominated aerosol particles can have radii similar to short wavelength
516 measurements.

517
518 Considering these factors, several potential techniques were explored utilizing various wavelength combinations and
519 utilizing the Spectral Deconvolution algorithm (SDA) fine and coarse mode triplet separation (O'Neill et al., 2001,
520 2003). While the SDA algorithm derived triplets for coarse mode AODs relative change tended to show utility in
521 cloud removal, the SDA algorithm itself could not be applied universally to the AERONET database to due
522 anomalous results in which fine and coarse mode AODs can have a negative relationship when the number of
523 available wavelengths or wavelength range is not satisfied. Anomalies in SDA retrievals can occur when the
524 uncertainty in AOD is relatively large near solar noon compared to the magnitude of AOD as is sometimes the case
525 when only the pre-field deployment calibration has been applied. Upon further consideration of the triplet
526 variability technique, analyses indicated that using all three longest standard AERONET wavelengths (i.e., 675nm,

527 870nm, and 1020nm) could be used to remove a triplet measurement when they have high triplet variability that
528 exceeds 0.01 or 0.015*AOD (whichever is greater). The reduction in the threshold of the triplet variability criterion
529 is proportional to the magnitude decrease AOD uncertainty compared to UV wavelengths (0.02) to those of visible
530 and near infrared wavelengths (0.01).

531
532 While Smirnov et al. (2000) did not impose an Ångstrom exponent limitation, Version 3 processing constrains the
533 $AE_{440-870nm}$ of Level 1.5 data to be within -1.0 and $+3.0$. In general, the $AE_{440-870nm}$ values outside this range are
534 unphysical and should not be used due to the inconsistency of the AOD spectral dependence. These inconsistencies
535 typically occur at very low optical depth (<0.05) where the uncertainty of the AOD may be up to 100% of the actual
536 value thus producing AE values that are invalid.

537
538 The AOD time series smoothness uses a number of numerical methods and fits dependent on the application. For an
539 AOD time series, rapid and large increases are usually the result of cloud contamination. In Version 2 and prior
540 versions, a technique proposed by Smirnov et al. (2000) to implement a smoothness methodology similar to
541 Dubovik et al. (1995). In this scheme, the triplet measurements were considered as discrete points and differences in
542 logarithm of $\tau_{app\ aerosol}$ and relative difference in times between those measurements were utilized to calculate the
543 first derivative differences in which an arbitrary parameter D (similar to the norm of the second derivative) is
544 calculated. In Version 2 and earlier versions, when the value of D was greater than 16 for an AOD measurement
545 time sequence for 500 nm or 440nm, then this triplet was removed from the data set. Further, the smoothness
546 procedure was repeated or measurements were rejected for the day if less than three triplets remained for the day as
547 discussed in Smirnov et al. (2000). While the $D=16$ threshold was empirically derived, the smoothness parameter is
548 somewhat arbitrary in origin and operates in logarithmic coordinates rather than natural ones. For example, the
549 distribution of aerosol measurements in a single day is typically normally distributed rather than logarithmically
550 distributed. Further, the D parameter smoothness procedure was not always successful at removing cloud-
551 contaminated data and this may be related to the fact that the empirically derived D parameter was tuned for 15-
552 minute triplet measurement intervals rather than three-minute intervals now commonly observed in the network.
553 Therefore, an approach adhering to the relative change in the total optical depth with time is feasible and a more
554 straightforward physical quantification of the change in $\tau_{app\ aerosol}$ with time.

555
556 The AOD time series smoothness in Version 3 evaluates the same $\tau_{app\ aerosol}$ 500nm wavelength (or 440nm if 500nm
557 is not available). The Version 3 smoothness method computes the relative rate of change of $\tau_{app\ aerosol}$ per minute and
558 if $\Delta\tau_{app\ aerosol}/\Delta t > 0.01$ per minute, then the larger triplet measurement in the pair is removed and the smoothness
559 procedure will continue to remove triplets until measurement pairs in the day do not surpass the smoothness
560 threshold. The selection of this threshold of 0.01 per minute hinges on the premise that the triplet average does not
561 change rapidly within one minute. The Version 3 smoothness procedure could be affected by extreme changes in
562 AOD due to anomalous aerosol plumes (e.g., biomass burning or desert dust plumes) where a strong gradient exists.

563

564 After the cirrus cloud screening quality control (to be discussed in the Sect. 3.2.2), triplets are evaluated for spurious
565 or isolated measurements remaining during the day after applying the cloud screening quality control procedures.
566 So-called “standalone points” may be relevant given the ability of the instrument to perform measurements in cloud
567 breaks or gaps. Here, the definition of a standalone triplet is when no triplets are available within 1 hour of the
568 measurement. If the $AE_{440-870nm}$ is greater than 1.0, the algorithm retains the triplet measurement; otherwise, the
569 measurement will be removed from the data set. Further, daily averaged data are evaluated for temporal stability
570 using the AOD stability during the day at 500nm (or 440nm) and daily outlier triplets using the 3-sigma check for
571 AOD at 500nm (or 440nm) and $AE_{440-870nm}$ to be within ± 3 standard deviations (Smirnov et al. 2000). Finally, each
572 wavelength is evaluated to be greater than or equal to -0.01 (based on uncertainty of 0.01; Eck et al., 1999). At this
573 point in the quality control algorithm, the remaining triplet measurements are not expected to have a major
574 component of τ_{cloud} or τ_{cirrus} .

575

576 3.2.2 Novel Cirrus Removal Method Utilizing Solar Aureole Curvature

577 Utilizing satellite and surface-based LIDAR, studies have shown the AERONET Version 2 Level 2.0 AOD data are
578 impacted by homogeneous optically thin cirrus clouds with a bias up to 0.03 in AOD (DeVore et al., 2009; Chew et
579 al., 2011; Huang et al., 2011). The optically thin cirrus bias can influence radiative forcing calculations and satellite
580 validation when clouds contaminate the measurement (DeVore et al., 2012). In addressing the shortcoming of
581 Smirnov et al. (2000) and manual checks in which the identification of optically thin cirrus clouds give relatively
582 weak signal in the AOD or AE, the authors leveraged high angular resolution radiance measurements routinely
583 performed in the solar aureole region (3.2° – 6.0° scattering angle range). While cirrus detection may be possible with
584 other scattering angle ranges, Cimel Sun photometer radiance measurements do not presently have high enough
585 angular resolution from 6.0° – 35.0° to reliably and consistency detect cirrus induced atmospheric phenomena (e.g.,
586 solar halos and sun dogs), since these events depend on cirrus crystal shape and orientation and are not always
587 detectable beyond levels of cloud optical depth variability.

588

589 The use of the solar aureole radiance (L_A ; $\mu W/cm^2/sr/nm$) with respect to the scattering angle (ϕ ; in radians) has
590 been demonstrated using the Sun and Aureole Measurement (SAM) aureolegraph instrument to indicate the
591 presence of large particles such as cirrus crystals (DeVore et al., 2009, 2012; Haapanala et al., 2017). The effect of
592 the surface reflectance is much less than the radiance of the solar aureole so it is ignored; however, this may become
593 important at very large solar zenith angles and bright surfaces such as snow (Eiden 1968). All Cimel instrument
594 models perform solar aureole measurements at the nominal 1020nm wavelength. The Cimel performs solar triplet
595 measurements directly on the solar disk, while solar aureole radiances are measured mainly during the almucantar,
596 principal plane, and hybrid sky scans. These solar aureole measurements are performed hourly for Models 4 and 5
597 instruments during sky scan scenarios and for Model T instruments before each solar triplet as well as for the hourly
598 almucantar and hybrid sky scan measurements.

599

600 The AERONET measurements of the solar aureole directional radiances (L_A) depend on the absolute calibration of
 601 the integrating sphere. The integrating spheres at the AERONET calibration centers provide an absolute calibration
 602 traceable to a NIST standard lamp hosted at the NASA GSFC calibration facility. The uncertainty in the radiance
 603 calibration is typically less than 3% due to systematic degradation in the lamp levels, changes in integrating sphere
 604 characteristics, and instrument spectral signal response. The solar aureole radiance magnitudes also depend on the
 605 instrument Sun sensitivity gain settings for each wavelength for Cimel Model 4 and 5 instruments, while the Model
 606 T instruments use an internal instrument gain switch applying to all wavelengths (Barreto et al., 2016). The L_A
 607 measurements have calibration and temperature correction applied and are measured by all Cimel instruments at the
 608 440nm, 675nm, 870nm, and 1020nm wavelengths. Due to lower AOD in fine mode aerosol loading situations, less
 609 Rayleigh scattering, and lower calibration uncertainty, the L_A measurements at 1020nm have less noise for
 610 evaluating cirrus cloud presence.

611
 612 Given that the L_A measurements are performed at discrete φ , we calculate the ordinary least squares linear regression
 613 fit on logarithmic scale when more than three scattering angles are available to determine the intercept (a), slope (b),
 614 and the correlation coefficient (R). If R is less than or equal to 0.99, then we do not proceed to check for cirrus
 615 contamination. When R is greater than 0.99, the curvature (k_o) for the first available scattering angle (φ_o) in the
 616 3.2° – 6.0° scattering angle range is calculated using the equation of curvature of the signed planar curve, which gives
 617 the rate of turning of the tangent vector in Eq. (10) (Kline 1998):

$$k = \frac{y''}{(1 + y'^2)^{\frac{3}{2}}} \quad (10)a$$

618
 619
 620 The curvature (k) can be formulated by assuming the Power Law function and its derivatives, and, in our
 621 application, using the first scattering angle (φ_o) in radians for φ below:

$$y = a * \varphi^b \quad (10)b$$

$$y' = a * b * \varphi^{b-1} \quad (10)c$$

$$y'' = a * b * (b - 1) * \varphi^{b-2} \quad (10)d$$

622
 623
 624 According to the k formulation, the stronger the forward scattering peak, then the smaller the value of curvature
 625 since the second derivative is small and the first derivative is large due to the steepness of the solar aureole
 626 radiances. Further, the overall slope of curvature for all of the scattering angles (3.2° – 6.0°) can be calculated using
 627 the assumption that $y'^2 \gg 1$ rendering the addition of 1 in the denominator of Eq. (10)a insignificant. The slope of
 628 the logarithm of curvature versus logarithm of scattering angle is desired and this slope can be calculated using a
 629 and b from the linear regression above by converting from logarithmic coordinates. Therefore, we derive the Eq.
 630 (11) to determine the slope of curvature dependent only on the slope of the linear regression fit of L_A and φ on
 631 logarithmic scale as follows:

632

$$\ln k = a + (1 - 2b) * \ln \varphi \quad (11)$$

633

634 Here, the slope of curvature (M) is defined as $(1-2b)$. The value of M will typically be positive since b will tend to
635 be negative due to the dimming of the solar aureole with increasing scattering angle. Alternatively, M can be
636 calculated numerically for each k and φ to obtain similar results. A small value of curvature (k_o) at the smallest
637 scattering angle available represents the possible existence of large particles producing a forward scattering peak.
638 The slope of curvature (M) represents the average characterization of the solar aureole shape across the scattering
639 angle 3.2° – 6.0° range where a large magnitude signifies the potential presence of large particles as curvature
640 increases with increasing scattering angle across the forward scattering peak.

641

642 The Micropulse LIDAR Network (MPLNET) is a global network of LIDARs monitoring the vertical distribution of
643 aerosols and clouds (Welton et al., 2000, 2002; Campbell et al., 2002). To determine the thresholds for these Sun
644 photometer solar aureole curvature parameters for different surface types and aerosol environments, the MPLNET
645 LIDAR cloud identification database was used at eight collocated AERONET sites as shown in Table 3. Multi-year
646 MPLNET LIDAR deployment data were analyzed and matched with AERONET observations when the solar zenith
647 angle was less than 30° to minimize the spatio-temporal differences of the zenith pointing LIDAR versus the
648 slantwise pointing of the Sun photometer in which sky condition can be quite different at large solar zenith angles.
649 The MPLNET cloud base height data product was matched with MERRA reanalysis vertical temperature profile
650 corresponding to the geopotential height pressure surface. When a cloud top temperature is less than -37°C , a cloud
651 is designated to be cirrus, while other non-cirrus clouds may contain liquid or mixed phase particles (Sassen and
652 Campbell, 2001; Campbell et al., 2015; Lewis et al., 2016). The partitioning the AERONET data set of solar
653 aureole radiances in terms cirrus clouds, non-cirrus clouds, all clouds, and clear (no cloud base detected) sky
654 condition categories allowed for the empirical determination of potential thresholds for the curvature parameters.
655 For each site, AERONET curvature parameters (k and M) were computed for almucantar and principal plane solar
656 aureole (L_A) measurements (i.e., left and right scans separately) and further categorized based on the coincident
657 LIDAR detected sky condition. These solar aureole radiances have calibration and temperature characterization
658 applied for the 1020nm channel and these L_A measurements were only quality controlled based on the correlation
659 threshold of 0.99 discussed above.

660

661 Figure 4a shows the number distribution of the k at NASA GSFC (38.99° N, 76.84° W) for each of the four LIDAR
662 sky condition categories. The number of the potential clouds is large for magnitudes of k less than $2.0\text{E}-5$.
663 Similarly, Fig. 4b and Fig. 4c show the number distributions of the M at NASA GSFC for each LIDAR sky
664 condition category. In Fig. 4b, the number of potential clouds generally dominates when the M is greater than 4.3
665 with generally clear or possibly cloudy conditions when M is less than or equal to 4.3. Some overlapping of the
666 categories for M may be related to the differences in the viewing geometry of the sky between the Sun photometer
667 and the LIDAR or inhomogeneous cloud conditions.

668
669 Algorithmically combining the two thresholds of k and M produces a defined distribution of clear versus cloudy sky
670 condition categories. When the threshold of $k < 2.0E-5$ is applied first, then the distribution of mainly cloudy
671 conditions becomes more distinct as shown for NASA GSFC in Fig. 4c. The maximum in the number distribution
672 for cirrus is near $M=4.6$ and the maximum in the number distribution of clear sky condition is at $M=4.3$ (Fig. 4c). At
673 Singapore (1.29° N, 103.78° E), Fig. 5c suggests that the distinction of small aerosol particles and larger cirrus cloud
674 ice crystals allows for adequate separation to identify an observation as cloud contaminated using a threshold of M
675 greater than 4.3. Figure 6a shows the number distribution of the curvature at the first scattering angle for coincident
676 AERONET and MPLNET observations at the SEDE BOKER (30.85° N, 34.78° E). Figure 6c shows the distinction
677 is similarly distributed as GSFC and Singapore to potentially identified cirrus contaminated observations. For Fig.
678 6a, the clear sky condition category is much higher in number than other sky condition categories; however, the k
679 values less than the first scattering angle threshold of $2E-5$ (shown by the orange vertical line) indicates a
680 significant presence of dust particles rather than cirrus clouds due to forward scattering of dust. Note that as for Fig.
681 4 and Fig. 5, the x-axis of Fig. 6a is truncated to $1E-4$ but the number distribution continues at values near zero for
682 larger first point curvatures. SEDE BOKER data in Fig. 6c exhibits a significant contribution of clear conditions are
683 preserved indicating that this method does not appear to misidentify dust as cirrus at this mixed dust and urban
684 pollution site.

685
686 When evaluating all of the collocated AERONET/MPLNET sites in Table 3 (Fig. 7), the maximum in the number
687 distribution for cirrus is at $M=4.3$ after the $k < 2.0E-5$ threshold is applied with a relative minimum for the clear
688 conditions for $M > 4.3$. Given this information, an empirical threshold of $M > 4.3$ can be established for maximizing
689 the removal of cirrus clouds and minimizing removal of potentially clear data points. As mentioned previously, the
690 almucantar and principal plane sky scans are performed on an hourly basis. If cirrus clouds are homogeneously
691 distributed in the sky, then this assumption allows for the application of the temporal screening of triplet
692 measurements within 30 minutes of the solar aureole measurement time. As a result, a significant number of cirrus
693 contaminated measurements for $M \leq 4.3$ are likely removed with this procedure given the normally distributed
694 number distribution of cirrus identified solar aureole measurements around $M=4.3$. For the Cimel Model T
695 instruments, sky scan aureole measurements are superseded by a special solar aureole scan (CCS) performed from
696 3.0° to 7.5° scattering angle range at 0.3° increments (left and right) after each triplet solar measurement; therefore,
697 temporal screening for these triplet measurements is applied within two minutes of the CCS scan. Overall, the
698 aureole curvature cirrus cloud screening quality control decreases the probability of a cirrus bias in the AOD data set
699 globally by using this standard procedure. However, the Version 3 Level 1.5 AOD data set may still be influenced
700 by optically thin or sub-visible cirrus clouds with ice crystals similar in diameter to coarse mode aerosols such as
701 those found at polar latitudes or when solar aureole measurements are not available due to instrument malfunction or
702 incomplete data transfer.

703

704 Figure 8 shows solar aureole radiances have significant nonlinearity with scattering angle when impacted by cirrus
705 clouds while measurements without cirrus are more linear. The SEDE BOKER site is influenced by desert dust.
706 Dust particles can affect the calculation of the k parameter to be close to the threshold of $2E-5$ even when cirrus
707 clouds are not present (SEDE BOKER case 1); however, the overall slope is more linear for the non-cirrus case
708 compared to the cirrus case (SEDE BOKER case 2). As a result, the M parameter is much lower and the algorithm
709 action would be to preserve the SEDE BOKER Case 1 data and remove data for SEDE BOKER case 2. Note that
710 the k parameter is quite low for SEDE BOKER Case 1 and in general dusty sites may frequently have k less than
711 $2E-5$; therefore, the M curvature parameter is needed to prevent inadvertent removal of aerosol data. For fine mode
712 at GSFC case 1 and Singapore, small values of k and large values of M result in removal of the cirrus-contaminated
713 data. For comparison, the GSFC case 2 shows significant linearity when cirrus clouds are not present. The GSFC
714 case 3 and Trinidad Head case show the variation in these curvature parameters at low optical depths in which only
715 one of the curvature parameters indicates the possibility of cirrus clouds. While these two curvature parameters may
716 be used independently in certain conditions, the current algorithm must employ both curvature parameter thresholds
717 to avoid inadvertently identifying aerosols as clouds in dust and low aerosol loading conditions.

718 3.3 Level 1.5 Quality Controls to Screen Instrument Anomalies

719 While cloud-screening quality controls remove a significant portion of data impacted by cloud contamination and
720 some instrument anomalies, a portion of the remaining AOD data set can be impacted by internal or external
721 instrument anomalies. Most instrument anomalies can be removed utilizing the prescreening steps outlined in the
722 Sect. 3.1, but a number of issues still exist which are more evident after the cloud screening quality controls have
723 been applied to the data set. A data set with some clouds can mask or offset patterns in the AOD spectra that can
724 clearly identify data anomalies dependent on optical air mass. For AERONET instruments, data anomalies either
725 dependent on the optical air mass, the sensor head temperature, or leakage, degradation, or looseness of the optical
726 interference filter. Section 3.1 addresses the quality control procedure with respect to the instrument temperature
727 dependence. Some instrument anomalies dependent on the optical air mass include deviations of the measurement
728 time to the true time (i.e., time shift) and obstruction of light into the silicon or InGaAs detector (e.g., dust, moisture,
729 spider webs). Measurements performed at high latitudes have a slowly varying optical air mass and thus optical air
730 mass pattern recognition is more difficult. The AOD spectra may have optical air mass dependence for out of band
731 leakage or degradation of transmittance due to irregularities in the optical filter composition or the AOD may have
732 significant variability due to a loose filter inside the sensor head.

733
734 The retained spectral AOD measurements passing the quality controls from Sect. 3.1 and Sect. 3.2 are evaluated as
735 input for the quality controls in the present section. The removal of nearly all of the clouds and most instrument
736 anomalies from the previous steps allow for more defined pattern recognition. This section will discuss the pattern
737 recognition techniques utilized for the time shift and AOD diurnal dependence, provide a description of the detector
738 consistency, and AOD spectral dependence quality controls. Further, the AOD diurnal dependence algorithm can be
739 used jointly with the detector consistency and AOD spectral dependence quality controls to remove anomalous data

740 with more certainty. These quality controls can be applied for multiple days to remove data impacted by anomalies
741 for more than one day even when clouds interrupt the day-to-day AOD pattern. The final data set is evaluated for
742 the remaining number of observations in a day and deployment period.

743 3.3.1 Time Shift Screening

744 AERONET data are transferred by satellite Data Collection Platform (DCP), PC, or SIM card data transfer. The
745 older Vitel satellite transmitters provided a handshake between the instrument and transmitter allowing for time
746 adjustment and newer Sutron Satlink transmitters provide a GPS time stamp to each message. While time shift is
747 not an issue for satellite transmissions, the time shift can become more significant for PC data transfer and even
748 some instruments using SIM card data transfer. AERONET has developed a program called cimel_https_connect
749 that can update the processing unit clock of Cimel Model 5 instruments. Older instruments (Model 4) and old non-
750 AERONET data transfer software (e.g., Cimel ASTPwin) do not have the capability to synchronize the Cimel
751 control box with the time-synced AERONET server. Most non-AERONET software requires the PC time to be
752 updated from a timeserver or GPS system to provide accurate clock synchronization. Even some newer Model T
753 instruments transferring data by PC or SIM can have faulty GPS modules in which the clock deviated significantly.
754 Cimel Model T instruments may allow for the PC software (e.g., cimelTS_https_connect) updating the time and
755 overriding the GPS module.

756
757 A Cimel clock that deviates from true time can result in an optical air mass calculation not appropriate for the actual
758 time especially when the optical air mass varies relatively rapidly diurnally. This instrument anomaly can result in
759 significant changes in the AOD, which affects all wavelengths but most greatly shorter wavelengths (e.g., 340nm,
760 380nm, and 440nm) at large optical air mass when it changes rapidly. In general, longer wavelength AODs (675nm,
761 870nm, and 1020nm) have less impact from erroneous optical air mass calculations due to less influence of
762 molecular (Rayleigh) scattering. As a result, AODs from the longer wavelengths tend to be more stable and AODs
763 from the shorter wavelengths will tend to crossover the longer wavelengths only at one end of the day (near sunrise
764 or near sunset). The timing of the wavelength crossover depends on whether the Cimel clock is too fast or too slow
765 with respect to the actual time. For example, if the time is slow (fast) relative to the actual time, the temporally
766 deviated optical air mass magnitude will be larger (smaller) than the actual optical air mass and thus the short
767 wavelength AODs will be lower (higher) and possibly cross the longer wavelength AODs (significantly increase
768 spectral dependence). In general, Cimel clock temporal deviations in AOD data can be identified using the
769 following:

- 770 1. When the shortest available wavelength AOD crosses neighboring UV, visible, and NIR channel
771 AODs near sunset and the short wavelength AOD is decreasing significantly relative a longer stable
772 wavelength (e.g., 870nm) AOD, this condition indicates the Cimel clock is too fast (Fig. 9a).
- 773 2. When the shortest available wavelength AOD crosses neighboring UV, visible and NIR channel
774 AODs near sunrise and the short wavelength AOD is increasing significantly relative to a longer stable
775 wavelength (e.g., 870nm) AOD, this condition indicates the Cimel clock is too slow (Fig. 9b).

776

777 The AOD differences and trends are used for a specific optical air mass interval (2.5–7.0), where the temporal clock
778 deviation amplifies the error in optical air mass calculations. Individual day screening is limited to mainly cloud
779 free periods with low AOD in areas with significant variation in optical air mass from ~1.0–7.0.

780

781 The time shift algorithm is applied over a multi-day period. The algorithm scans the current day plus 19 days in the
782 past (~3 week period) to determine if three or more days indicate the occurrence of a time shift. If the multi-day
783 time shift criteria of three or more days are met, then data between the current day and the last occurrence of the
784 time shift are removed from the field deployment. Although the Cimel clock could possibly be adjusted
785 periodically, most time shift issues tend to occur at remote sites and this approach will maximize the removal of data
786 over the multi-day period to minimize the negative impact on the data from the clock-shifted anomalies. Moderate
787 to high aerosol loading can partly mask the temporal AOD time shift pattern and these data periods may not be
788 removed completely unless they occur between periods of lower aerosol loading when the clock shift spectral AOD
789 pattern is more defined.

790

791 **3.3.2 Detector Consistency Quality Control**

792 The instrument external collimator on the sensor head avoids stray light and reduces front lens contamination, while
793 the internal sensor head defines the field of view of the instrument (nominally 1.2°) by the achromatic front lens,
794 filter, and field stop before each detector. The external collimator is composed of two tubes and the aperture design
795 varies slightly by instrument type. The Cimel Model 4 instrument type has two Silicon photodiode detectors in the
796 sensor head to measure the Sun and sky while newer model instruments have one Silicon photodiode and one
797 InGaAs photodiode detector to measure the Sun and sky on both detectors. One of the detectors could be impacted
798 by an obstruction such as a spider web, insect debris, dust, or moisture. For Cimel Model 4 and some Model 5
799 instruments, the sky scan scenario performs two measurements at the 6° azimuth angle for the almucantar and 6°
800 scattering angle for the principal plane at each wavelength over both detectors. For these older instruments, the
801 solar aureole gain is used for the solar Silicon diode detector and the sky gain is used for the sky Silicon diode
802 detector. These redundant measurements can allow for detection of the change in the relative signal but this method
803 is currently more appropriate to use for quality controlling the inversion products due to uncertainty in sky
804 calibration. Newer Model 5 and Model T instruments (with the solar and sky measurements performed on both
805 detectors) do not have the redundant sky measurement; instead, these instruments have a redundant solar
806 measurement at 1020nm in both collimator tubes, where each solar measurement of the triplet is performed within
807 eight seconds of each other. The AOD 1020nm measurements on Silicon and InGaAs detectors can be compared
808 directly to determine if an obstruction exists in front of either of the detectors. Applying a similar approach to Giles
809 et al. (2012), the difference limit ($\Delta\tau_{Limit}$) can be computed using the optical air mass and AOD magnitude dependent
810 formulation (Eq. (12)):

811

$$\Delta\tau_{Limit} = \frac{(0.04 + (0.02 * MIN[\tau_{1020nm}]))}{m} \quad (12)$$

812

813 where $MIN[\tau_{1020nm}]$ is the minimum of the AOD at 1020nm obtained from the redundant AOD 1020nm
 814 measurements on Silicon and InGaAs detectors and m is the optical air mass. The difference limit for an AOD
 815 1020nm minimum of 1.0 will result in the 0.06/m 1020nm difference limit described in Giles et al. (2012). A more
 816 lenient approach is used here based on the AOD magnitude to prevent removal of data for low AOD at 1020nm. At
 817 low AOD, the average field instrument uncertainty (up to 0.01) becomes more significant while the maximum AOD
 818 error occurs at midday and differences due to their temperature dependency can contribute up to 0.02 AOD bias.
 819 Given the relative difference in the AOD 1020nm measurements, the maximum uncertainties in both 1020nm
 820 measurements must be considered. Therefore, the 0.02 threshold is derived from the average uncertainty (up to
 821 0.01) and the 0.04 limit is derived from the maximum midday error in AOD and temperature dependency (up to
 822 0.02). When more than 10% of the total measurements for the day exceed the $\Delta\tau_{Limit}$, data are removed in the
 823 following manner:

- 824 1. If the AOD 1020nm Silicon subtracted by the AOD 1020nm InGaAs detector is greater than $\Delta\tau_{Limit}$, then the
 825 Silicon side has an obstruction and the entire measurement is removed for both Silicon and InGaAs AOD
 826 data.
- 827 2. If AOD 1020nm Silicon subtracted by the AOD 1020nm InGaAs is less than $-\Delta\tau_{Limit}$, then the InGaAs
 828 detector has an obstruction and only the InGaAs AOD for 1020nm and 1640nm measurements are
 829 removed.
- 830 3. If the redundant AOD 1020nm values are nearly the same ($-\Delta\tau_{Limit} \geq \Delta\tau \geq \Delta\tau_{Limit}$), then an obstruction could
 831 possibly exist in the event that a substance (e.g., spider webs, dust, moisture) similarly obstruct both
 832 detectors.

833 For condition (3), this case is further evaluated by the AOD diurnal dependence quality control in the next section.

834 3.3.3 Aerosol Optical Depth Diurnal Dependence

835 The AERONET instrument has spectral calibrations made and typically applied both before and after field
 836 deployment. When the instrument operates in the field, the pre-field spectral calibration applied to the near real-time
 837 data is constant. If the calibration changes significantly during the instrument deployment, the error in the
 838 computation of the AOD increases with decreasing optical air mass where the maximum error occurs when optical
 839 air mass approaches one ($\delta\tau * m$; Hamonou et al., 1999). As a result, an apparent diurnal dependence in the AOD can
 840 occur depending on the magnitude of the deviation from the pre-field calibration. When both the pre-field and post-
 841 field calibrations are applied and data still show a diurnal dependence in the AOD, then the deviation in the field
 842 measurements is due to a non-linear change in the calibration coefficient since Level 2.0 data utilize a linear
 843 interpolation between the pre-field and post-field calibration coefficients.

844

845 Midday maximum (concave pattern) or midday minimum (convex pattern) of AOD diurnal dependence can be
 846 observed at any AOD magnitude but are typically more pronounced at lower aerosol loading due to calibration

847 offset (Cachorro et al., 2004) or instrument anomalies. Quality controls developed for the analysis of the AOD
848 diurnal dependence need to consider the impact of clouds and missing data to assess whether to remove these data
849 while minimizing the removal of data exhibiting true diurnal dependence. For example, one cloud-free day may
850 show diurnal dependence, but on another day, the morning or afternoon data may not be available due to missing
851 data during cloudy or rainy periods. The algorithm must have a sufficient number of observations to perform a
852 robust assessment of the AOD diurnal dependence.

853
854 Variation in the number of available measurements in a day due to clouds or instrument issues can limit the
855 application of a single day only approach. As a result, the morning and afternoon periods must have at least five
856 measurements separately and the analysis of the full day must have at least 10 measurements. To analyze the
857 diurnal dependence and reduce the impact of outliers, the GNU Scientific Library robust least squares (RLS) linear
858 regression fit is performed for AOD versus the inverse optical air mass (m^{-1} , where m is approximately the cosine of
859 the solar zenith angle). The slope and correlation coefficient (R) values derived from the linear fit are used as
860 thresholds to determine the magnitude and strength of the diurnal dependence (Table 4).

861
862 The nominal AERONET 440nm, 675nm, 870nm, and 1020nm wavelengths for the Silicon detector and 1640nm for
863 the InGaAs detector are assessed for diurnal dependence and potential removal of all spectral channels. An example
864 of the AOD diurnal dependence of 1020nm wavelength is shown in Fig. 10 at the Rio Branco (9.96° S, 67.87° W)
865 AERONET site where the site manager indicated spider webs were obstructing measurements. If data are removed
866 for the InGaAs detector, then only InGaAs detector data are removed, while removal of the Silicon detector data will
867 remove all data including InGaAs detector data, if any. The AOD diurnal dependence is classified as two
868 categories: independent and dependent. If the algorithm meets the strict thresholds for “independent” diurnal
869 dependence, then all channels exhibiting diurnal dependence can remove data for a day, except the 1020nm channel
870 since some old data with temperature defaults may exhibit false diurnal dependence. Otherwise, all of the above
871 channels are used for the “dependent” diurnal dependence quality control. The dependent diurnal quality control
872 relies on more lenient thresholds for the slope and R ; however, the removal of data generally requires that another
873 quality control flag is set such as the detector consistency quality control (Sect. 3.3.2), where an obstruction was
874 identified in front of one of the detectors or at least one additional qualified wavelength meeting the slope and R
875 thresholds. When a qualified wavelength indicates dependent AOD diurnal dependence for Day or both AM and
876 PM and the AM and PM slopes are positive, then the entire day can qualify for independent removal. This
877 methodology allows for a more skilled approach in removing only data affected by instrumental anomalies while
878 minimizing the removal of data coincidentally producing a true diurnal dependence signature.

879
880 The AOD diurnal dependence identification can be complicated by changes in aerosol loading during the day, cloud
881 artifacts, and missing data. A multi-day scan must be performed to maximize the removal of data impacted by
882 instrument anomalies. A multi-day assessment example is provided in Fig. 11 for Rio Branco. Figure 11a shows
883 that the spectral AOD varies significantly diurnally for the period from 26 August to 5 September 2011, especially

884 for the 870nm and 1020nm near infrared wavelengths. Figure 11b shows evaluation of the slope and correlation
885 coefficient (R) for the AOD 1020nm daily variation, which shows 7 of the 10 days exceeding the thresholds (slope >
886 0.1 and $R > 0.94$) and wavelengths established in Table 4. For these data to qualify for dependent AOD diurnal
887 dependence removal, additional information is needed such as another qualified wavelength with slope and R
888 exceeding the thresholds. For this case, the AOD 870nm daily slope and correlation parameters (not shown) also
889 exceed the thresholds, which lead to the elimination of these data from Levels 1.5 and 2.0. Similar to the time shift
890 screening in Sect. 3.3.1, the AOD diurnal dependence algorithm scans the last 19 days including the current day to
891 determine the first occurrence and last occurrence of the dependent and independent AOD diurnal dependence.
892 When three or more days are identified, data are removed from the first occurrence to the last occurrence of AOD
893 diurnal dependence during the 20-day period. The multi-day screening allows for the elimination of data affected by
894 an obstruction in the instrument field of view even with moderately high aerosol loading in the NIR wavelengths
895 and when days with incomplete number of measurements from the established protocol due to clouds.

896 **3.3.4 Reverse Spectral Dependence**

897 While the majority of the cloud screening quality controls remove aerosol measurements contaminated by clouds,
898 some spurious points or slowly varying changes in cloud properties may still affect the data set at this point in the
899 algorithm. A new method (Fig. 12) utilizing the Ångström exponent (AE) is applied to the remaining data set for
900 evaluation of cloud contamination. Ångström exponents derived from anomalous AOD measurements due to
901 instrument artifacts may produce a similar signature. The spectral dependence among the wavelengths is now much
902 improved compared to Version 2 by removing temperature dependencies that influenced the calculation of the AE at
903 low AODs reducing the effect of improper spectral dependence due to temperature anomalies.

904
905 The AE is computed utilizing the ordinary least squares fit of the logarithms of AOD and wavelength for the ranges
906 of 440–870nm, 870–1640nm (if 1640nm is available), and the 870–1020nm (for Silicon detectors only) range (Eck
907 et al., 1999). The reverse spectral dependence algorithm in Fig. 12 removes cloud contaminated points utilizing
908 these AE ranges depending on the instrument model. Figure 13 shows the removal of the anomalously high AOD at
909 the Bratts Lake (50.20° N, 104.71° W) AERONET site in southwest Canada. In Fig. 13b, all negative and a few
910 positive AE values are identified and the algorithm removes nearly all of the residual cloud contamination in this
911 case. However, the penultimate and final measurements in Fig. 13c have slightly higher AOD than the previous
912 hour of data, which may be due to marginal contamination by optically thin cirrus clouds. Additional algorithm
913 development is still needed to further enhance the removal cloud contaminated data with small ice crystals while not
914 removing dust aerosols.

915 **3.3.5 Aerosol Optical Depth Spectral Dependence**

916 The wavelength dependence of AOD typically is strong for fine mode aerosols (e.g., pollution or smoke) and weak
917 for coarse mode aerosols (e.g., dust or sea salt). The AE provides an index of the strength of the spectral
918 dependence related to the estimation of the possible aerosol size (Eck et al., 1999). In general, the $AE_{440-870nm}$ will

919 typically provide values between approximately 0.0 and 3.0. These prospective values indicate no spectral
920 dependence at $AE_{440-870nm}$ of 0.0 and very strong spectral dependence with an $AE_{440-870nm}$ near 3.0 (AE values of 3.0
921 have not been observed in good quality data with sufficiently high AOD). The spectral dependence can be used to
922 evaluate the quality of each channel given that most channels in the measurement suite adhere to the stated AOD
923 uncertainty of 0.01 for wavelengths $\geq 400nm$ and 0.02 for wavelengths $< 400nm$ (Eck et al., 1999). The fit of the
924 AOD with wavelength on logarithmic scale should generally be linear for coarse mode dominated or fine/coarse
925 mode particle mixtures. However, in moderate to high aerosol loading cases (especially when fine mode
926 dominated), a quadratic or cubic assumption is needed to fit the data depending on the wavelength range under
927 evaluation (Eck et al., 1999; O'Neill et al., 2008). The ordinary least squares (OLS) methodology is perturbed by
928 the presence of outliers and therefore skews the fit towards outliers. If the boundary wavelengths are impacted by
929 anomalies, the ordinary least squares can poorly fit other intermediate wavelengths.

930
931 In an effort to reduce the influence of outliers, the GNU Scientific Library (GSL Version 2.2.1 C compilation)
932 robust least squares (RLS) technique is utilized to improve the removal of spectral AOD outliers. In general, the
933 OLS technique is sensitive to the endpoints and to the number of points used in the regression. For example, the
934 outlier detection will have less skill with a few points or anomalous endpoints. The RLS scheme uses an iterative
935 approach with up to 100 passes using the Tukey biweight function and assigning the outliers a lower weight with
936 each pass. The RLS approach allows for the more meticulous removal of wavelengths out of spectral dependence
937 and more importantly preserves mid-visible wavelengths that could be removed incorrectly when utilizing the
938 ordinary least squares method.

939
940 Outlier detection is performed utilizing the uncertainty of the AOD measurement and providing an allowable
941 tolerance in the fit given potential irregular nature of the uncertainty (0.01 to 0.02). For wavelengths $\geq 400nm$ and
942 $< 1600nm$, the allowable AOD difference between the measurements and fit for a candidate wavelength is
943 $(0.02 * AOD) + 0.02$, based on the stated AOD uncertainty for these wavelengths (Holben et al., 1998; Eck et al.,
944 1999). For wavelengths $< 400nm$ and $1640nm$, the allowable AOD difference between the measurements and fit for
945 a candidate wavelength is $(0.02 * AOD) + 0.04$, which is adjusted for greater uncertainty at the UV wavelengths and
946 greater uncertainty in the larger spectral range to fit the 1640nm wavelength.

947
948 The spectral outlier procedure begins by identifying and removing any negative AOD values that are not within the
949 allowable AOD difference from the RLS linear fit. Negative AOD due to slight calibration drift can be observed at
950 very clean locations; otherwise, these negative values may be anomalous. The algorithm will evaluate each
951 wavelength separately and compute the RLS linear fit based on the remaining wavelengths producing the slope,
952 intercept, and R^2 values, where the slope and intercept are used to compute the AOD fit at the wavelength under
953 evaluation. If the algorithm does not identify any wavelengths for removal, then the procedure is complete. If AOD
954 is low ($AOD_{440nm} < 0.1$) and one wavelength AOD exceeds the maximum allowable difference, then the wavelength
955 will be removed due to the linear fit deviation. However, if more than one wavelength has AOD marked for removal

956 for the low AOD condition, then the wavelength with the largest departure from the linear fit to the measurement
957 and largest R^2 will qualify for removal.

958
959 In the case of higher AOD ($AOD_{440nm} \geq 0.1$), the algorithm stores the information from the RLS linear fit and
960 continues to perform a RLS quadratic fit ($400nm \leq \lambda \leq 1020nm$) or a RLS cubic fit ($\lambda = 1640nm$). If the candidate
961 wavelength deviates from the allowable difference in fit to the measurements for the higher order fits, then the
962 wavelength will be removed if it is identified as a wavelength that corresponds to the maximum deviation for the
963 RLS linear fit. Figure 14 provides an example of this condition at the Osaka (34.65° N, 135.59° E) AERONET site.
964 After each wavelength removal regardless of order of the fit, the algorithm repeats until no wavelength removals
965 occur or when less than three wavelengths remain.

966 **3.3.6 Large Aerosol Optical Depth Triplet Variability**

967 In addition to growth of hygroscopic aerosols near cumulus cloud boundaries and large triplet variability at short
968 wavelengths in highly variable fine mode plumes, a misaligned filter due to improper filter wheel movement or dust
969 on the filter may produce large AOD triplet variability ($AOD_{Max} - AOD_{Min}$). The cloud screening triplet
970 variability quality control (Sect. 3.2.1) removes the entire measurement when 675nm, 870nm, and 1020nm AOD
971 triplets all have large triplet variability exceeding the threshold (0.01 or $0.015 * AOD$, whichever is greater). A
972 situation may exist where one of those wavelengths or shorter wavelengths are impacted by a filter anomaly making
973 it necessary to assess the large AOD triplet variability. If the triplet measurement is identified for high AOD
974 retention (Sect. 3.1.6), then the following large adjacent triplet quality control is not performed because very high
975 aerosol loading in fine mode events can lead to large triplet variability naturally. Occasionally, if the triplet is very
976 large and exceeds the limit of $0.03 + 0.2 * AOD$, then the wavelength is removed independently of the next longer
977 wavelength.

978
979 To further screen anomalous triplets individually or the entire day, each triplet and wavelength is evaluated using the
980 triplet variability from the shortest wavelength (e.g., 340nm) and the next longer wavelength (e.g., 380nm). The
981 allowable triplet variability limit is computed based on the aerosol loading and the AOD triplet variability of the
982 next longer wavelength: $0.03 + 0.02 * AOD + triplet_variability_of_next_longer_wave$. If the total number of triplets
983 for a wavelength exceeding the large triplet variability threshold is more than 25%, then the AOD measurements for
984 the wavelength are removed completely for the entire day. Figure 15 shows the large triplet variability removal at
985 the PEARL (80.05° N, 86.42° W) AERONET site in northern Canada. The triplets at shorter wavelengths may
986 naturally exhibit relatively large triplet variability hence it is necessary to check the shorter wavelength in
987 comparison to the next longer wavelength which typically will be more stable if clouds do not impact the
988 measurements.

989 **3.3.7 Remaining Measurements Evaluation**

990 After the previous quality control algorithms have been applied, extraneous data points may remain and are
991 identified for possible removal. A number of conditions have been implemented based on the total data removed for
992 the day, number of wavelengths remaining for the day, and number of measurements for a wavelength for a
993 deployment. These “cleanup” conditions below will remove all wavelengths in a day for any of the following
994 conditions dependent on the “retain high AOD” from Sect. 3.1.6 and the number of wavelengths in a day:

- 995 1. If retain high AOD and less than two wavelengths remain in a day
- 996 2. If retain high AOD and two wavelengths but are not 870nm and 1020nm in a day
- 997 3. If not retain high AOD and less than three wavelengths remain in a day
- 998 4. If not retain high AOD and less than half of the wavelengths remain in a day

999
1000 Each wavelength must be evaluated for remnant data artifacts. If greater than 50% of the total cloud screened AOD
1001 data for a wavelength in a day are removed, then AOD measurements for the candidate wavelength will be removed
1002 for the day. Further, a condition is implemented to remove specific wavelengths for an entire deployment. For
1003 example, if the number of measurements for a wavelength is less than 20% of the total cloud screened data set for a
1004 deployment, then all of the measurements for the specified wavelength will be removed for the deployment. These
1005 removal conditions are necessary to fully quality control the spectral AOD data set and avoid unphysically irregular
1006 and fragmented data sets.

1007 **3.4 Algorithm Performance Assessment**

1008 Data quality controls applied to the quality controlled Level 1.0 data set are evaluated for removal performance for
1009 each part of the Level 1.0 prescreening and Level 1.5 algorithm. The Level 1.0 prescreening is applied to about 84
1010 million solar triplet measurements from 1993–2018. The radiometric sensitivity screening (see Sect. 3.1.2) for the
1011 DN of 1020nm removes about 36% and the digital voltage triplet variance greater than 0.16 (see Sect. 3.1.3)
1012 removes nearly 11% of the Level 1.0 data. The remaining Level 1.0 prescreening that check for radiometric
1013 sensitivity screening for DN of 870nm, extreme temperatures ($T_S \leq -40^\circ\text{C}$ or $T_S > 100^\circ\text{C}$), and bad measurement
1014 configuration conditions remove approximately 0.5% of the Level 1.0 data. Therefore, nearly half (48%) of the
1015 initial 84 million solar triplet measurements are removed by the Level 1.0 prescreening steps due to the presence of
1016 clouds in the solar measurements that greatly reduce the signal (e.g., stratus clouds) or exhibit significant temporal
1017 variability within the one minute triplet measurement sequence (e.g., cumulus clouds).

1018
1019 The Level 1.5 quality control algorithm is divided into the two main steps for cloud screening and instrument data
1020 anomaly removal. Figure 16 shows the percentage of the Level 1.0 data removed by the Level 1.5 cloud screening
1021 quality control. Over 23% of the removal in the cloud screening algorithm was due to the large triplets at the long
1022 wavelengths (675nm, 870nm and 1020nm). Nearly 5% of the removal of the Level 1.0 data was due to the presence
1023 of cirrus clouds as detected by the solar aureole curvature algorithm and is significant since a cirrus contamination
1024 bias is evident in the AOD in Version 2 Level 2.0 data set. The “Unqualified” category indicates data that are not

1025 triplets or lack the sufficient channels to participate in the cloud screening part of the algorithm and these
1026 measurements are rejected from Level 1.5. Finally, spectral AOD removed due to too low negative values
1027 ($AOD < -0.01$) has maximum removal of approximately 0.5% for 380nm and 1% for 340nm of the total Level 1.5
1028 AOD measurements due to 0.02 uncertainty in the UV at very low optical depths, while other AOD wavelengths
1029 have generally much less than 0.5% removal. After all of the data are cloud screened, about 66% of the Level 1.0
1030 data are passed to the second part of the Level 1.5 instrument quality control algorithm for examination of the
1031 instrument anomalies and other spurious clouds and artifacts.

1032

1033 The second stage of the Level 1.5 quality control algorithm utilizes measurements passed from the cloud screening
1034 algorithm. While the cloud screening algorithm rejects the entire measurement in the presence of clouds, the
1035 instrument quality controls can also reject the entire measurement or remove data by wavelength depending on the
1036 anomalous condition. Figure 17 shows the removal of Level 1.5 cloud screened data due to mainly instrument
1037 anomalies for each wavelength. More than 2.5% of the data are removed due to the AOD diurnal dependence
1038 screening, about 2% for the time shift screening, and 1.5% for the AOD 1020nm difference screening. These three
1039 instrument quality control algorithms remove in general the most across all wavelengths. Some removal occurs
1040 significantly spectrally for the InGaAs channel (1640nm). The InGaAs channels can be affected in some
1041 instruments more significantly by water contamination as the InGaAs side of the collimator is facing away from the
1042 Sun when in the parked or resting position. Further, when the algorithm removes all of the Silicon channels, the
1043 remaining InGaAs channels are also removed since no other independent method exists to check the InGaAs
1044 channel data quality. The “Remaining” measurements removal shows that nearly 4% of the cloud screened data are
1045 removed from the InGaAs data set. The AOD spectral dependence removes more than 2% of the 340nm wavelength
1046 data, which tends to be the most unstable wavelength (due to filter degradation), and about 0.5% for all other
1047 wavelengths. The temperature screening removal of missing or anomalous temperatures mostly affects the Silicon
1048 1020nm wavelength with nearly 1% of the cloud-screened data removed due to its large temperature dependence
1049 compared to the other wavelengths.

1050 **4 Assessment of the Quality Assurance Data Set**

1051 The aerosol optical depth (AOD) data will be qualified for consideration of Level 2.0 once it passes the Level 1.5
1052 checks. To reach Level 2.0, these data must meet the following conditions:

- 1053 1. Data must have pre-field and post-field calibration applied; or in some cases, the pre-field deployment or
1054 post-field deployment calibration may be made constant for the deployment after evaluation of the best
1055 calibration values.
- 1056 2. Temperature characterization must be applied utilizing the temperature correction for the instrument or
1057 default values for each wavelength.
- 1058 3. Instrument must be designated as the primary instrument for the site.

1059

1060 Once the above conditions are met, these data are considered to reach Level 2.0. These Level 2.0 data are
1061 recommended for publication and use in various atmospheric applications. The automated quality control algorithm
1062 attempts to preserve aerosol data while removing data artifacts. Some unusual atmospheric conditions (e.g., small
1063 cirrus particles $r < 5 \mu\text{m}$) or rare instrument anomalies (e.g., loose filters or partially removed multi-da AOD diurnal
1064 dependence) affecting the AOD may rarely pass through the algorithm and users are advised to consider inspecting
1065 these data carefully when using them for detailed studies. Further, optical air mass dependent anomalies such as the
1066 time shift and AOD diurnal dependence quality controls may allow data to pass when aerosol loading is high or too
1067 few data exist to make an assessment. These quality controls can determine patterns more skillfully at lower aerosol
1068 loading which could result in retaining potentially contaminated high aerosol loading periods when the pattern may
1069 be less defined and does not meet the quality control thresholds.

1070
1071 The subsequent sections discuss the impact of the temperature characterization on the Version 3 Level 2.0 AOD data
1072 to quantify the change in regards to the Version 2 Level 2.0 data set. Further, the assessment of the Version 3 near
1073 real-time product is made to determine the average bias of the AOD based on the applied calibration. Finally, an
1074 analysis is made of the Version 3 Level 2.0 AOD long-term averages for select AERONET sites and these are
1075 compared to the Version 2 Level 2.0 AOD long-term averages.

1076

1077 **4.1 Temperature Characterization Evaluation**

1078 The accurate measurement of the spectral direct-beam Sun intensity (from which AOD is computed) depends on the
1079 sensor head temperature of the instrument as discussed in Sect. 2. The sensor head temperature can vary
1080 significantly since the optical head canister is heated by the Sun and can be much higher ($>10^\circ\text{C}$) than the ambient
1081 temperature especially near solar noon. The temperature sensitivity of the Silicon detector is more significant for
1082 the 1020nm filter due to the proximity to the edge of the spectral range of the detector in which temperature
1083 dependence becomes more significant. The temperature dependence for all wavelengths may vary due to the
1084 composition and/or manufacturing quality of the filters and/or detectors. Due to technical difficulty, the ultraviolet
1085 wavelength ($\lambda < 400\text{nm}$) filters have not been temperature characterized in Version 3; however, UV filters may have
1086 a temperature dependence. Figure 18 shows the difference in the AOD temperature coefficients for Version 3
1087 temperature correction applied to Version 3 data and Version 2 temperature correction applied to Version 3 AOD
1088 data from 1993–2018. The AOD varies most significantly for the Silicon 1020nm channel with a full range of ~ 0.02
1089 for sensor head temperatures between -25°C and $+55^\circ\text{C}$. Notably, the shorter wavelength channels and the InGaAs
1090 wavelengths (i.e., 1020nm and 1640nm) do not show significant change in AOD less than 40°C . All of the
1091 wavelengths, except the Silicon 1020nm, show an AOD difference decrease from -0.005 to -0.010 for temperatures
1092 greater than 40°C , which may be due to changes in instrument characteristics (e.g., electronic instability in the
1093 instrument) at high temperatures. The decreasing AOD difference with increasing temperature may be related to the
1094 smaller number of observations at high temperatures and contribution by instruments with temperature
1095 characterization measurements that did not reach temperatures greater than 40°C . Temperature characterization has

1096 proven to be small yet necessary adjustment to the AOD computation and this improvement is especially exhibited
1097 in polar regions or sites with very low aerosol loading in which the Version 3 AOD spectra have much less
1098 crossover allowing for the computation of more accurate Ångström exponents than in the Version 2 data set.

1099 **4.2 Level 1.5 Near Real-time Aerosol Optical Depth Bias and Uncertainty**

1100 The Version 3 near real-time data set provides improved data quality compared to Version 2 since the algorithm has
1101 improved cloud screening and instrument quality controls applied to the data. The data set can vary in the near real-
1102 time interval from current day up to one month as ancillary data sets are received and processed, hence, these
1103 database changes invoke reprocessing of the AOD throughout the near real-time phase. Once AOD data have been
1104 pre-field and post-field calibrated, then these data may be raised to Level 2.0 as described in Sect. 4. The near real-
1105 time data using only constant pre-field calibration is compared to the quality assured data set that uses both the pre-
1106 field and post-field calibrations applied to the data with the assumption of linear interpolation. Figure 19 shows the
1107 distribution by wavelength for this comparison of the near real-time and quality assured data set for the entire
1108 database of Level 2.0 qualified data excluding calibration site data and deployments using a copied pre-field or post-
1109 field calibration. These results are based on the Version 3 Level 2.0 data set in which the Level 1.5 algorithm scans
1110 the entire deployment. The AOD difference histograms were computed for optical air mass ranges ($1.0 \leq m < 7.0$ and
1111 $1.0 \leq m < 1.5$). The optical air mass $1.0 \leq m < 7.0$ range includes all of the data; however, these AOD difference
1112 magnitudes will be constrained by the improved AOD measurements at large optical air mass and influenced toward
1113 Northern hemisphere winter mid-latitude sites when AOD tends to be low. The optical air mass $1.0 \leq m < 1.5$ range
1114 includes data will provide AOD measurements near solar noon and these measurements are generally less accurate
1115 ($\delta\tau \cdot m$) than at larger optical air mass. In addition, optical air mass $1.0 \leq m < 1.5$ range data include a greater influence
1116 of tropical locations and data from the mid-latitude summer when AOD tends to be moderate to high.

1117
1118 Figure 19 shows the AOD average differences for the $1.0 \leq m < 7.0$ range indicate a positive bias in which the AOD
1119 for the pre-field only calibration tends to be on average +0.003 to +0.009 higher than the AOD using the
1120 interpolated calibration. Similarly, AOD average differences for the $1.0 \leq m < 1.5$ range show a positive bias and
1121 similar wavelength variations but up to two times larger differences than for the $1.0 \leq m < 7.0$ range. The largest
1122 average differences and standard deviations are for the UV wavelengths, which have greater uncertainty as
1123 discussed in Sect. 2. The AOD differences for the wavelengths longer than 500nm have about less than half the bias
1124 of the UV wavelengths. The Level 1.5 algorithm performance improves with increased data availability such as a
1125 greater number of wavelength or number of days. When an instrument deployment begins, some of the Level 1.5
1126 algorithm steps such as multi-day removal schemes are not available until several days into the deployment
1127 producing larger differences in the near real-time AOD with respect to the final product. While wavelength
1128 dependent biases of +0.003 to +0.009 for the $1.0 \leq m < 7.0$ range and +0.006 to +0.015 for the $1.0 \leq m < 1.5$ range exist
1129 when only the pre-field calibration is applied, the difference can vary significantly depending on each instrument
1130 deployment necessitating continued post-field calibration and maintenance effort.

1131

1132 When an instrument is deployed in the field, the pre-field calibration is used constantly until the post-field
1133 calibration is assessed and applied to the data using linear interpolation. The difference of pre-field calibration AOD
1134 minus the post-field calibration AOD average difference and standard deviation are computed in day bins for the
1135 number of days since the pre-field calibration. Figure 20 shows the AOD 500nm average difference for the optical
1136 air mass ranges: $1.0 \leq m < 7.0$ and $1.0 \leq m < 1.5$. Instruments typically operate in the field between 12 and 18 months
1137 from the pre-field calibration date; however, the instrument deployment may be delayed and the instrument may not
1138 begin operation for a few months after the pre-field calibration. Thus, the number of AOD measurements in the
1139 days since pre-field calibration bins increase to a maximum at about 100 days. Some instruments may operate longer
1140 in the field to support field campaigns and other scientific priorities. Figure 20 shows that the AOD average
1141 difference and the standard deviation slowly but steadily increase for each optical air mass range. At about 1.5 years
1142 after pre-field calibration (~550 days), the AOD average difference is about +0.010 with a standard deviation of
1143 0.015 for optical air mass $1.0 \leq m < 7.0$ range and +0.017 with a standard deviation of 0.021 for $1.0 \leq m < 1.5$. For the
1144 UV wavelengths, the average differences and standard deviations tend to increase slightly while the longer visible
1145 and near infrared wavelengths tend to decrease slightly. Therefore, the quality of the Level 1.5 near real-time AOD
1146 changes with time with high quality data at the start of the deployment but up to a +0.02 bias and 0.02 uncertainty
1147 for data collected more than 1.5 years since pre-field calibration.

1148

1149 **4.3 Multi-year Monthly Comparisons of Version 3 Level 2.0 to Version 2 Level 2.0 Databases**

1150 Long-term average differences between the Version 3 and Version 2 Level 2.0 data sets provide insight into the
1151 changes to be expected across most AERONET sites. The analysis of the Version 3 and Version 2 data sets shows
1152 mainly the differences in the AOD, $AE_{440-870nm}$, precipitable water (PW) in cm, and the number of days are clustered
1153 near zero (Fig. 21). Note that precipitable water data quality depends on the quality of the input wavelengths
1154 (675nm and 870nm) and no further quality control is made on the 935nm wavelength. The increases in the Version 3
1155 Level 2.0 multi-year monthly average AOD are often due to the increased presence of fine mode particles from high
1156 aerosol loading events as well as aerosols in near cloud environments (Eck et al., 2018). The decrease in the multi-
1157 year monthly average AOD is due to the improved removal of clouds in the Version 3 quality control algorithm.
1158 Generally, the results should be very similar between Version 3 and Version 2 in AOD calculation since the
1159 temperature characterizations as well as NO₂ absorption contributions typically have relatively minor contributions.

1160

1161 Other factors affecting the AOD calculation include the adjustment of site coordinates and elevation information for
1162 about 100 AERONET sites utilizing GPS or digital elevation model. A few rare extreme coordinate adjustments of
1163 more than 25 km included Petrolina_SONDA (9.0691° S, 40.3201° W), Ilorin (8.4841° N, 4.6745° E), and
1164 Ouagadougou (12.4241° N, 1.4872° W). A large site coordinate adjustment can complicate satellite matchups for
1165 these few cases but the review of all AERONET sites showed that less than a 5 km distance adjustment and less than
1166 100-meter elevation adjustment was needed for most of these 100 suspected sites.

1167

1168 Figure 22 shows similar plots to Fig. 21 except that the observations used for the multi-year monthly averages in
1169 both data sets the instantaneous observations are time matched, hence, each data set has the same number of
1170 observations and number of days. The time matched long-term average comparison provides insight into the AOD
1171 calculation differences rather than impacts due to cloud screening and instrument quality controls applied in Level
1172 1.5. Table 5 shows the multi-year monthly overall standard deviation and AOD maximum to minimum range is
1173 significantly reduced compared to the data set without time-matched observations. Figure 22a shows a slight
1174 decreasing trend of Version 3 AOD for increasing Version 2 AOD and most of the larger AOD deviations are for
1175 sites in Asia where the impact of the OMI NO₂ corrections may be contributing to the slight shift of up to 0.02 for a
1176 few months and sites.

1177

1178 For unmatched or time matched data sets in Table 5, the precipitable water climatology changed on average
1179 insignificantly. The multi-year monthly overall days difference (Table 5) for the unmatched precipitable water data
1180 set was near zero and the standard deviation was near 25 days while the maximum of +150 and minimum of -130
1181 days indicate significant variability due to the differences in quality controls between the algorithms. Overall, the
1182 changes from Version 2 to Version 3 in precipitable water are generally negligible in terms of the contribution to the
1183 calculation of the AOD.

1184

1185 Overall, the multi-year monthly overall average difference between Version 3 and Version 2 for unmatched data is
1186 +0.002 and time matched data is -0.002 indicating remarkable consistency between the long-term average quality
1187 assured data sets. For example, the NASA GSFC AERONET site multi-year monthly average (Fig. 23) located 20
1188 km north of Washington, D.C., shows minor variations in the AOD and increase in AE due to removal of cirrus
1189 clouds during the winter months and increasing AOD in the summer months due to the greater abundance of cloud
1190 processed or near cloud aerosols (Eck et al., 2014).

1191

1192 Comparison of $AE_{440-870nm}$ in Fig. 21b and Fig. 22b show significantly lower values for Version 3 than Version 2
1193 Level 2.0 at low optical depth. An analysis of long-term average data at Lulin, Taiwan (23.47° N, 120.87° E)
1194 identified significant reduction of Version 3 AE relative to Version 2 AE at very low AOD due to temperature
1195 characterization that resulted in improved AOD spectral dependence (Fig. 24). The Lulin site is a high altitude
1196 mountain station located in south central Taiwan, and this site is affected episodically by trans-boundary aerosol
1197 plumes from East and Southeast Asia (Lin et al., 2013; Wang et al., 2013). In eastern China, multi-year monthly
1198 averages from the XiangHe site (39.75° N, 116.96° E) show a significant Version 3 AOD increase of 0.2, while
1199 maintaining nearly the same AE and increasing the number of days up to near 40% for the multi-year monthly
1200 average in July and August (Fig. 25). The XiangHe site is located to the east of Beijing and is routinely impacted by
1201 urban pollution and episodically by biomass burning and desert dust events (Li et al., 2007). The significant
1202 increase in the AOD for XiangHe is likely due to the retention of highly variable fine mode aerosol events
1203 particularly at very high AOD, which were removed by the Version 2 cloud screening wavelengths utilizing large
1204 triplets less than 675nm (Eck et al., 2018). Additionally, some very high AOD events at XiangHe were previously

1205 removed by the Version 2 mid-visible low signal threshold but are now retained in Version 3, but often only for
1206 wavelengths longer than 675nm, so the statistics for these days are not accounted for in the 500nm data shown in
1207 Fig. 25.

1208
1209 At the Mongu (15.25° S, 23.15° E) site (Fig. 26), the biomass burning smoke typically occurs during the dry season
1210 from April through November due to biomass fuel cooking and agricultural burning (Eck et al., 2003). Comparisons
1211 of multi-year monthly averages for the Mongu site shows small deviations for AOD up to ± 0.01 with slight
1212 increases in Version 3 AE during December through March due to enhanced cirrus cloud removal from the solar
1213 aureole check. Notably, the number of days for the Mongu multi-year monthly averages significantly decreased by
1214 10% to 25% in Version 3 due to improved cloud screening and sensor head temperature anomalies affecting
1215 instrument performance. In Cinzana, Mali (Fig. 27), the aerosol loading is dominated by background dust aerosol
1216 with episodic contributions to the aerosol loading from biomass burning smoke from November to March (Cavaliere
1217 et al., 2010). The AERONET IER-Cinzana site (13.28° N, 5.93° W) multi-year monthly averages show generally
1218 0.03 lower AOD for Version 3 than Version 2 and nearly the same AE for both versions. The number of days for
1219 each month is 7% to 25% lower in Version 3 when compared to Version 2 mainly due to improved cirrus cloud
1220 screening.

1221 **5 Summary**

1222

1223 The Aerosol Robotic Network (AERONET) has adopted a new automated quality assurance algorithm called
1224 Version 3. The significant impacts of the Version 3 algorithm are updated and improved cloud screening and
1225 quality control methods, which are powerful tools in quality assuring the Sun photometer AOD data. Comparisons
1226 between the quality assured data sets of Version 3 and Version 2 show excellent agreement. Deviations can be
1227 explained by known algorithm differences such as changes in the cloud screening triplet variability, cirrus cloud
1228 detection and removal, implementation of temperature characterization, updates to NO₂ climatology, modification of
1229 site coordinates and elevation, and identification of instrument anomalies such as aerosol optical depth (AOD)
1230 diurnal dependence, AOD spectral dependence, and instrument electrical and temperature stability. The high
1231 statistical agreement in multi-year monthly averaged AOD substantiates Version 3 algorithms and suggests that the
1232 Version 3 database will validate most Version 2 research conclusions but exceptions can exist. For example, the
1233 Version 3 algorithm permitted AOD measurements of thick biomass burning smoke in Indonesia during the strong
1234 2015 El Nino event where Version 2 AOD data were not available (Eck et al., 2019). As a result, MODIS satellite
1235 retrieval modifications have been identified to capture more high optical depth events rather than masking them as
1236 clouds (Shi et al., 2018). Given AERONET algorithm enhancements, we recommend the Version 3 AOD database
1237 for scientific investigations.

1238
1239 Major highlights of this work include (not listed in priority):

- 1240 1. An automatic quality control algorithm significantly reduces the necessity of analysts to inspect millions of
1241 AERONET measurements. The AERONET Version 3 algorithm applied in near real-time provides high
1242 quality AOD for data assimilation applications. The Version 3 Level 2.0 data is provided within 30 days of
1243 the post-field calibration evaluation after the instrument deployment, improving the timeliness of quality
1244 assured data.
- 1245 2. Improvements to the total AERONET database cloud screening results in about 60% removal of clouds
1246 from the complete Sun photometer database and this value is similar to the coverage of clouds globally of
1247 about 68% (Rossow and Schiffer 1999). Autonomous Cimel Sun photometers can view gaps and nearby
1248 regions of the clouds and become inactive during rain periods due to wet sensor activation and AERONET
1249 sites are dominated by land locations which generally have lower cloud cover on average; therefore, these
1250 factors would reduce the difference between total AERONET cloud removal percentage and global satellite
1251 observations. Over 36% of the total data were removed by the 4-quadrant solar tracker sensitivity check
1252 due to less accuracy in tracking the Sun in cloudy conditions, while about 23% of the removal was due to
1253 the variability of clouds with respect to more homogeneous aerosol loading.
- 1254 3. Utilizing the shape of the solar aureole radiances with scattering angle, a cirrus detection algorithm was
1255 developed by leveraging MPLNET LIDAR cloud detection capabilities. The solar aureole cirrus algorithm
1256 eliminates ~5% of the Level 1.0 AOD data to reduce the bias of optically thin cirrus clouds in AERONET
1257 database.
- 1258 4. Spectral temperature correction has been implemented for all AERONET instruments using the sensor head
1259 temperature sensor reading. The temperature characterization shows significant AOD deviation ± 0.01
1260 variation between -25°C and $+50^{\circ}\text{C}$ for the Silicon 1020nm, since this wavelength is on the edge of the
1261 Silicon detector sensitivity range. Other wavelengths in the 440nm to 1640nm range have weak
1262 temperature dependence from -25°C and $+30^{\circ}\text{C}$ with a few wavelengths having greater temperature
1263 dependence at higher temperatures.
- 1264 5. New automated instrument anomaly screening provides a systematic and objective scheme to remove entire
1265 measurements or individual wavelengths from the AERONET AOD database. Importantly, obstructions to
1266 the instrument optics are now removed automatically using an AOD diurnal dependence algorithm based
1267 on the optical air mass. The AOD diurnal dependence technique employs several conditions that were
1268 developed to mitigate the removal of true diurnal dependence conditions while maximizing the removal of
1269 data significantly impacted by anomalies affecting the instrument optics.
- 1270 6. Bias and uncertainty estimates for near real-time AOD are computed by using the difference of the pre-
1271 field calibration AOD minus the interpolated calibration AOD. The near-real time AERONET data have
1272 an estimated bias up to $+0.02$ and one-sigma uncertainty up to 0.02 ; these values have slightly higher
1273 uncertainty for shorter wavelengths and slightly lower uncertainty for longer wavelengths.
- 1274 7. The AERONET Version 3 and Version 2 AOD quality controlled databases are analyzed to have a long-
1275 term monthly average difference of $+0.002$ with ± 0.02 standard deviation and greater agreement for time-
1276 matched observations with average difference of -0.002 with ± 0.004 standard deviation. The high

1277 statistical agreement in multi-year monthly averaged AOD validates the advanced automatic data quality
1278 control algorithms and suggests that migrating research to the Version 3 database will corroborate most
1279 Version 2 research results and likely lead to some more accurate results.

1280 8. Examination of long-term sites in various aerosol source regions indicates mainly subtle changes in AOD,
1281 AE and the number of days available; however, in some months, improved cloud screening, high aerosol
1282 loading retention, and improved instrument anomaly screening not attained by Version 2 explain larger
1283 deviations in these parameters.

1284

1285 AERONET Version 3 has evolved into a database with unparalleled presence in Sun photometry. Future algorithms
1286 could include improvements to the detection of cirrus clouds in polar environments, where the ice crystal size is
1287 approaching the size of large non-cloud aerosols, the determination of anomalies in high aerosol loading conditions,
1288 and the identification of true AOD diurnal dependence versus one generated by an instrument anomaly. Cimel
1289 radiometers will also measure the moon to derive lunar AOD (Berkoff et al., 2011; Barreto et al., 2013, 2016; Li et
1290 al., 2016). For example, current lunar measurement protocols do not include lunar aureole measurements analogous
1291 to the solar aureole measurements, hence the lack of these measurements potentially reduces the ability of the
1292 algorithm to remove cirrus clouds at night, and thus a variation of the quality control methodology may need to be
1293 developed. Other surface-based remote sensing networks such as MAN (Smirnov et al., 2009), SKYNET
1294 (Takamura and Nakajima 2004), GAW-PFR (Kazadzis et al., 2018), and PANDORA (Herman et al., 2009) may
1295 benefit by implementing applicable quality control methods established by AERONET.

1296

1297 *Data Availability.* Version 3 AOD data are available from the AERONET web site (<https://aeronet.gsfc.nasa.gov>)
1298 and the web site provides these data freely to the public. Data may be acquired by utilizing several download
1299 mechanisms including site-by-site download tools and web service options for near real-time data acquisition.

1300

1301 *Author contributions.* For five years, the AERONET staff (listed from DG to BH) worked individually and
1302 collaboratively drawing on their decades of project scientific, engineering and programming expertise to develop
1303 and assess the Version 3 AOD processing system presented herein. Traditional assignment of co-authorship is not
1304 possible. Aside from the first author, contributing AERONET staff is listed in reverse chronological order based on
1305 their start date with the project. JL, JC, and EW provided LIDAR data for development of the cirrus curvature
1306 methodology. SK and AL provided gaseous and water vapor absorption coefficients based on radiative transfer
1307 models.

1308

1309 *Competing interests:* The authors declare that they have no conflict of interest.

1310

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1331 **References**

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1665 **Table 1.** Nominal AERONET wavelengths for ion assisted deposition filters used for aerosol remote sensing and spectral
 1666 corrections or components for each channel.

Nominal Central Wavelengths (nm)	Filter Bandpass (nm)	Spectral Corrections/ Components
340	2	Rayleigh, NO ₂ , O ₃
380	2	Rayleigh, NO ₂
440	10	Rayleigh, NO ₂
500	10	Rayleigh, NO ₂ , O ₃
675	10	Rayleigh, O ₃
870	10	Rayleigh
935	10	Rayleigh, Aerosol
1020	10	Rayleigh, H ₂ O
1640	25	Rayleigh, H ₂ O, CO ₂ , CH ₄

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Table 2. Summary of Cloud Screening Related Quality Control Changes from Version 2 to Version 3.

Algorithm/Parameter	Version 2	Version 3
Very High AOD Restoration	N/A	$\tau_{870} > 0.5$; $\alpha_{675-1020} > 1.2$ or $\alpha_{870-1020} > 1.3$, restore if eliminated by cloud screening
Optical Air Mass Range	Maximum of 5.0	Maximum of 7.0
Number of Potential Measurements	$N_{\text{remain}} < 3$, reject all measurements in the day	After all checks applied, reject all measurements in the day if $N_{\text{remain}} < \text{MAX}\{3 \text{ or } 10\% \text{ of } N\}$
Triplet Criterion	All wavelengths checked; AOD Triplet Variability $> \text{MAX}\{0.02 \text{ or } 0.03 * \tau_{\text{aerosol}}\}$	AOD Triplet Variability $> \text{MAX}\{0.01 \text{ or } 0.015 * \tau_{\text{aerosol}}\}$ for 675nm, 870nm, and 1020nm wavelengths simultaneously
Ångstrom Exponent (AE) Limitation	N/A	If $\text{AE}_{440-870\text{nm}} < -1.0$ or $\text{AE}_{440-870\text{nm}} > 3.0$, then eliminate triplet measurement.
Smoothness Check	$D < 16$	For AOD _{500nm} (or 440nm) $\Delta\tau_{\text{aerosol}} > 0.01$ per minute, then remove larger τ_{aerosol} in pair. Repeat condition for each pair until points are not removed.
Solar Aureole radiance Curvature Check (Sect. 3.2.2)	N/A	Using 1020nm solar aureole radiances, compute the curvature (k) between 3.2° and 6.0° scattering angle (φ) at the smallest scattering angle. If $k < 2.0E-5 \varphi$ and if slope of curvature (M) is greater than 4.3 (empirically determined), then radiances are cloud contaminated. For sky scan measurements, all τ_{aerosol} measurements are removed within 30 minutes of the sky measurement. For Model T, special aureole scan measurements will remove all τ_{aerosol} within a two minute period superseding any sky scan aureole measurements.
Standalone Measurements	N/A	If no data exists within 1 hour of a measurement, then reject it unless $\text{AE}_{440-870\text{nm}} > 1.0$.
AOD Stability Check	Same as Version 3	Daily averaged AOD 500nm (or 440nm) has σ less than 0.015, then do not perform 3- σ check.
3- σ Check	Same as Version 3	AOD 500nm and $\text{AE}_{440-870\text{nm}}$ should be within the $\text{MEAN} \pm 3\sigma$; otherwise, the points are rejected.

1672 **Table 3.** AERONET and MPLNET sites and date ranges used for assessing cirrus and non-cirrus cloud presence

Site	Latitude	Longitude	Elevation (meters)	Date Range
GSFC	38.9925° N	76.8398° W	87	May 2001–Jan 2013
COVE	36.9000° N	75.7100° W	37	May 2004–Jan 2008
Kanpur	26.5128° N	80.2316° E	123	May 2009–Jan 2013
SEDE_BOKER	30.8550° N	34.7822° E	480	Nov 2007–Apr 2013
Santa_Cruz_Tenerife	28.4725° N	16.2473° W	52	Nov 2005–Jan 2013
Singapore	1.2977° N	103.7804° E	30	Aug 2009–Jan 2013
Ragged_Point	13.1650° N	59.4320° W	40	Jun 2008–Jan 2013
Trinidad_Head	41.0539° N	124.1510° W	105	May 2005–Feb 2013

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1675 **Table 4.** Thresholds used to determine the independent and dependent AOD diurnal dependence. Satisfying both the slope and
 1676 correlation coefficient (R) conditions would constitute the possible removal of all measurements for a day.

Day Removal Type	AOD Diurnal Shape	Analyzed Period	Slope Threshold	R Threshold
Independent	Concave	AM, PM, Day	>0.25	>0.974
Dependent	Concave	AM, PM	>0.04	>0.94
Dependent	Concave	Day	>0.1	>0.94
Dependent	Convex	AM, PM, Day	<-0.02	<-0.94
Dependent – $\tau_{\text{avg}} < 0.1$	Convex	AM, PM, Day	<-0.1	<-0.94
Independent – 2 or more Silicon wavelengths (440, 675, 870, 1020nm) or 1640nm InGaAs	Concave	AM, PM, Day	>0.1 Day or AM & PM > 0.02	>0.94

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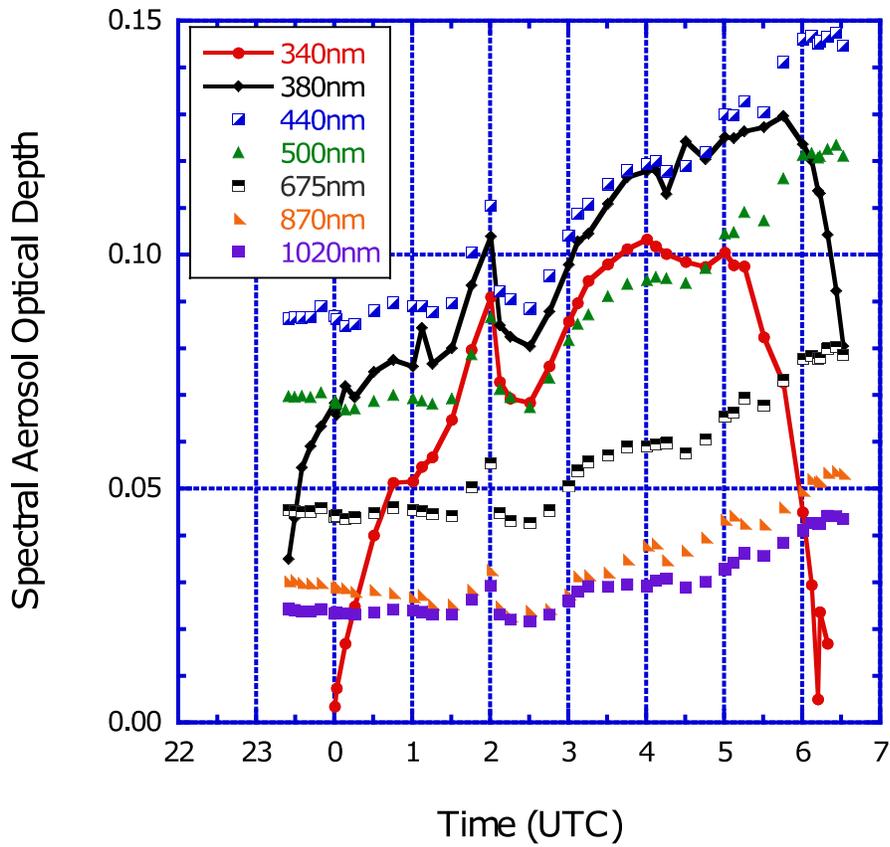
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1679 **Table 5.** Statistics corresponding to Fig. 21 and Fig. 22 for AOD interpolated to 500nm, Ångstrom exponent 440–870nm,
 1680 precipitable water (cm), and the number of days. Version 3 Level 2.0 and Version 2 Level 2.0 data are compared for the same
 1681 multi-year monthly averages when sites have a total of more than 1000 days for all months and more than 30 days in each month.
 1682 Data represented as “Matched” indicates the further condition that the exact observations were matched in Version 2 and Version
 1683 3 Level 2.0 multi-year monthly average data sets. Note that PW values for the “Matched” data set are approximately the same as
 1684 the unmatched data set.

Parameter	AOD _{500nm}	AE _{440-870nm}	PW (cm)	Days	AOD _{500nm}	AE _{440-870nm}
	(V3–V2)	(V3–V2)	(V3–V2)	(V3–V2)	(V3–V2)	(V3–V2)
	Unmatched	Unmatched	Unmatched	Unmatched	Matched	Matched
Average	0.002	–0.01	–0.02	–0.4	–0.002	–0.03
Standard Deviation	0.022	0.10	0.06	24.8	0.004	0.10
Maximum	0.247	0.29	0.34	150	0.015	0.35
Minimum	–0.166	–1.54	–0.45	–130	–0.029	–1.63
Number of Months	2953	2953	2953	2953	2514	2514

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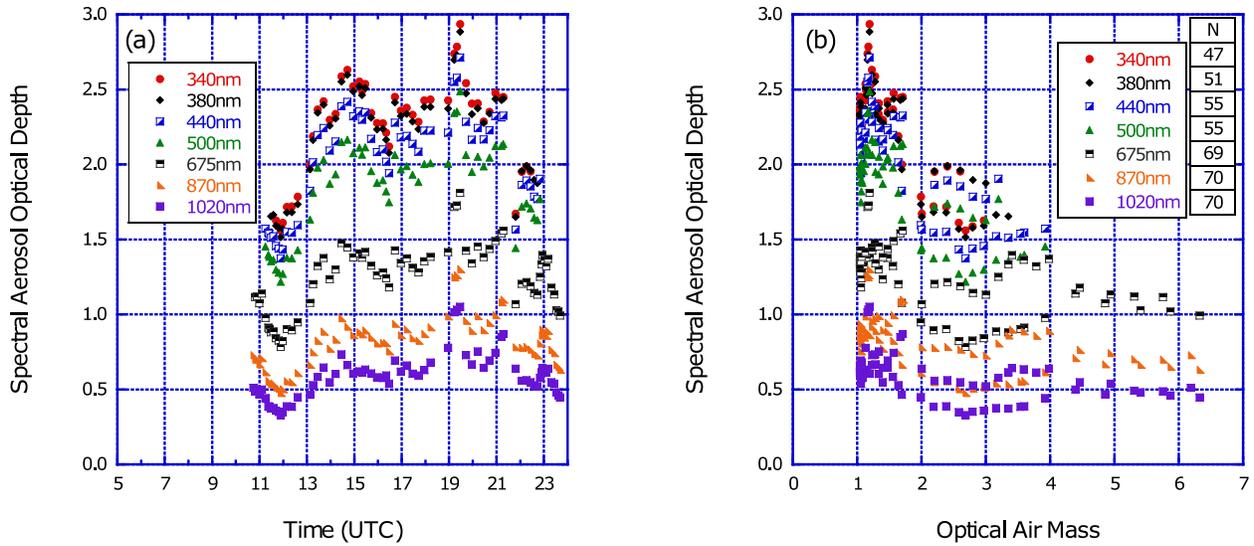
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1688 **Figure 1.** Aerosol optical depth (AOD) data from AERONET Ussuriysk site (43.70° N, 132.16° E) on 30 November 2005 shows
 1689 electronic instability. For the Cimel Model 4 instruments, the electronic sensitivity of the UV AOD data (340nm and 380nm) can
 1690 be high due to a bad amplifier. The resulting AOD data for the UV channels are out of spectral dependence the entire day with a
 1691 maximum error for large optical air mass due to large dark current values. The UV channels (identified by line plots) are
 1692 removed by the quality control while preserving other wavelengths that are not affected by this condition.

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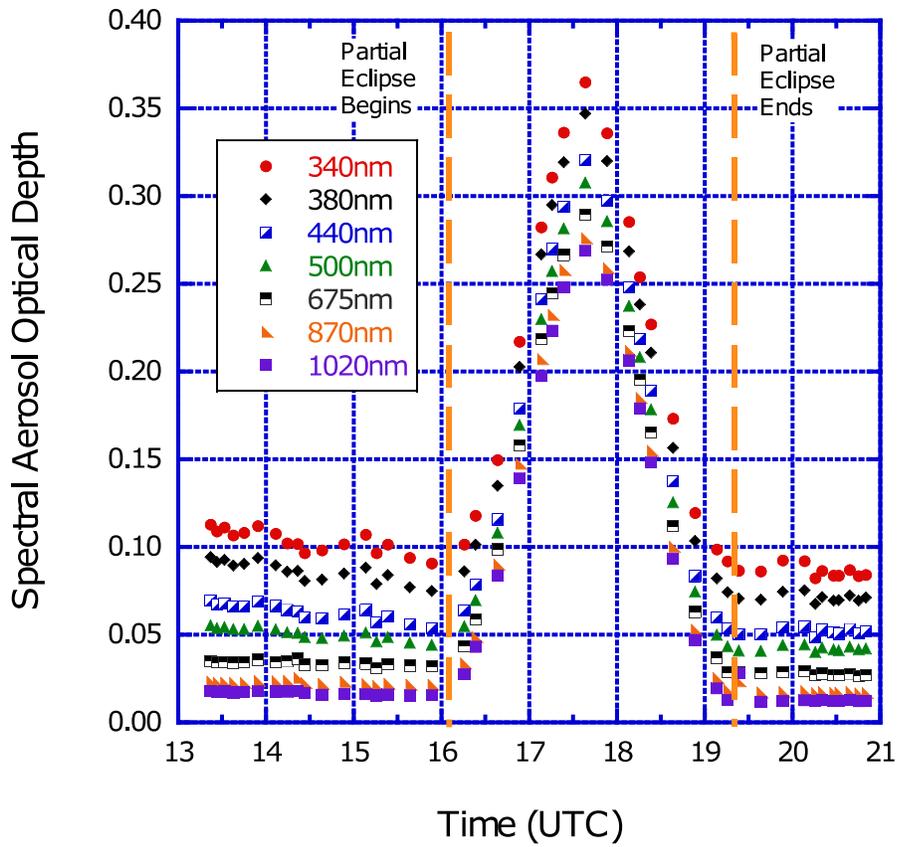
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Figure 2. Spectral dependent low digital number removal at NASA Goddard Space Flight Center (GSFC; 38.99°N, 76.84°W). (a) Level 1.0 AOD data from GSFC on 8 July 2002 are plotted for the Quebec forest fire smoke event. Significantly fewer Level 1.0 AOD data are available for the shorter wavelengths near local sunrise (~11 UTC) and sunset (~23:30 UTC). (b) The distribution of the AOD measurements with respect to optical air mass clearly shows the removal of short wavelengths for large air mass in this fine mode aerosol event. The high aerosol loading due to smoke and haze results in significant extinction at UV and visible wavelengths, which corresponds to low digital counts. The low digital count quality control removes AOD measurements impacted by diffuse radiation scattered into the instrument field of view (Sinyuk et al., 2012).

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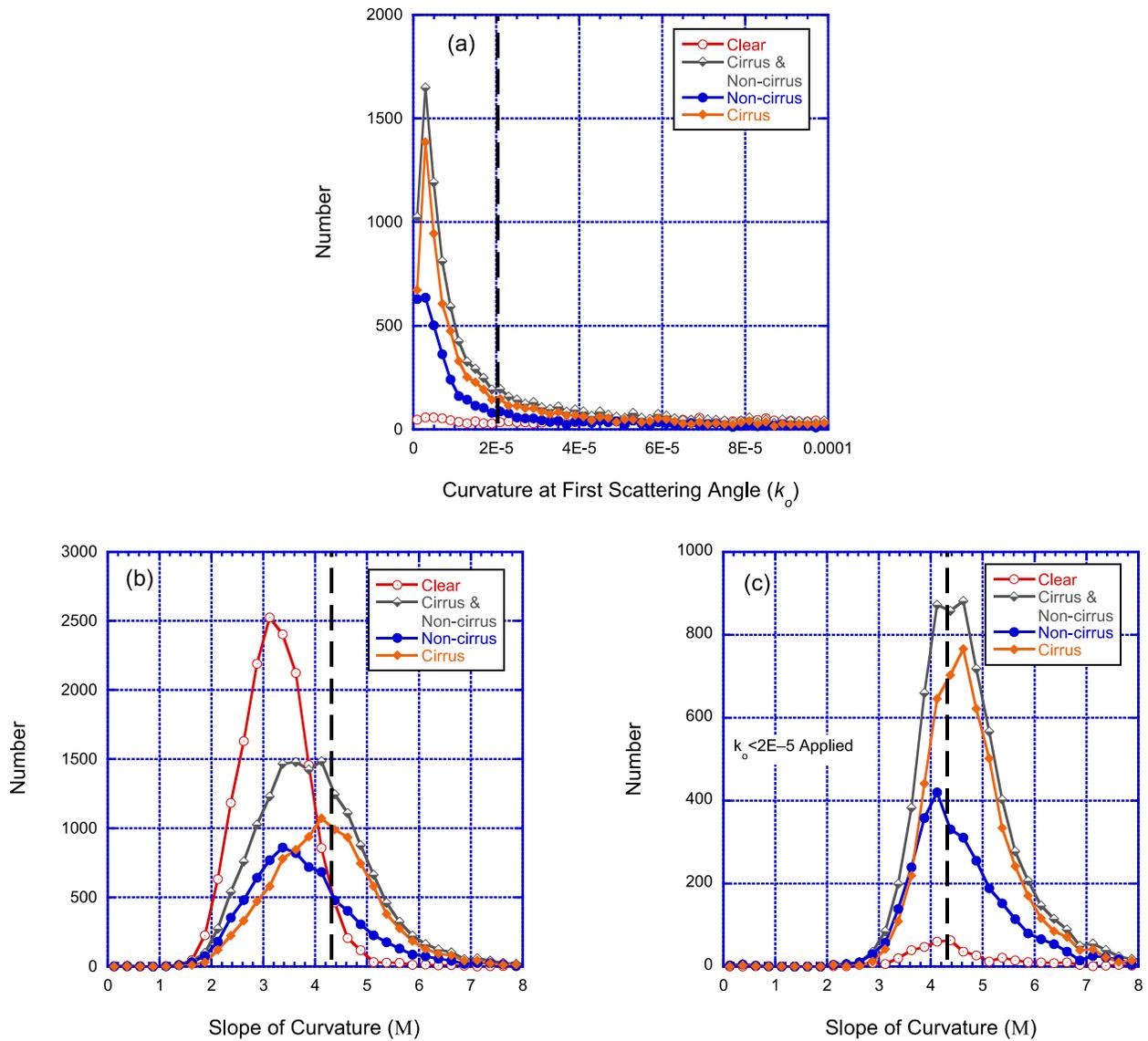


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1704 **Figure 3.** Eclipse circumstance at the NASA Goddard Space Flight Center (GSFC; 38.99° N, 76.84° W) on 25 December 2000
 1705 between 16:04:13 UTC and 19:16:25 UTC. The maximum AOD during the eclipse occurs at the maximum obscuration of 0.42,
 1706 which results in a change of ~0.28 for AOD 500nm compared to data before and after the solar eclipse. Utilizing the NASA
 1707 Solar Eclipse database, the AOD measurements are removed between the partial eclipse first contact and partial eclipse last
 1708 contact as denoted by the vertical dashed lines.

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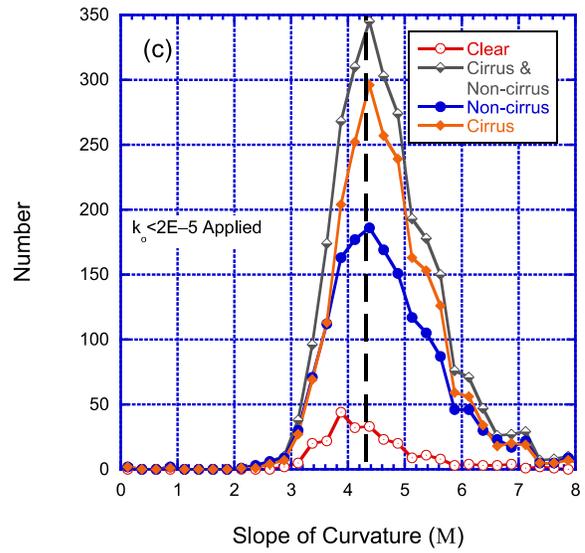
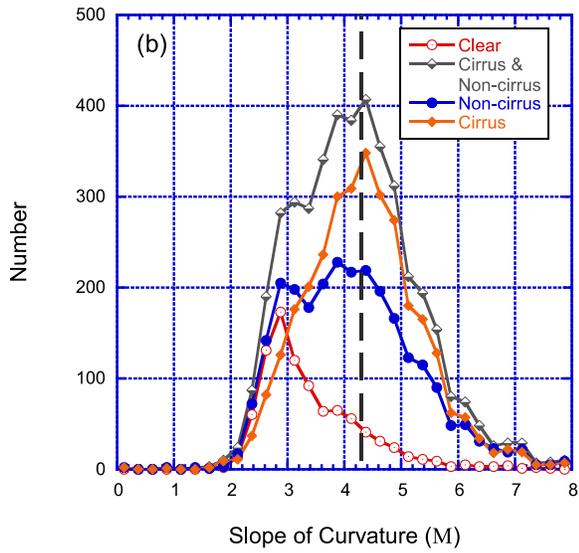
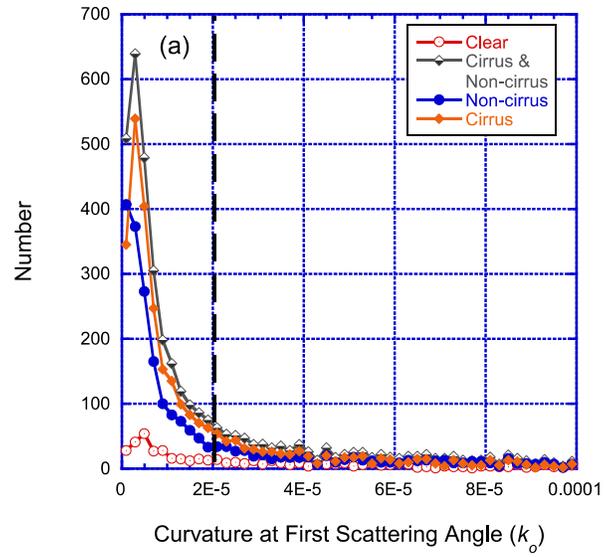
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1712 **Figure 4.** NASA Goddard Space Flight Center (GSFC; 38.99° N, 76.84° W) AERONET data coincident with MPLNET LIDAR
 1713 derived sky condition categories (Clear, both Cirrus and Non-cirrus clouds, Non-cirrus clouds, and Cirrus clouds) from 2001–
 1714 2013. The AERONET solar aureole 1020nm radiances are used to calculate the curvature at the first scattering angle (k_o) and the
 1715 slope of curvature (M) between 3.2° and 6.0° scattering angles. **(a)** The number distribution of k_o is shown and the dashed
 1716 vertical line at k_o equals $2E-5$ indicates the threshold where values less than $2E-5$ are considered possibly cirrus cloud
 1717 contaminated (the x-axis is truncated at $1E-4$ for viewing purposes). **(b)** The number distribution of M is shown and M greater
 1718 than 4.3 are considered to be possibly cirrus cloud contaminated (the dashed vertical line indicates the threshold of 4.3). **(c)**
 1719 Similar to panel (b) except that the k_o threshold ($k_o < 2E-5$) is applied first and, as a result, data greater than 4.3 in this panel are
 1720 considered to be cirrus cloud contaminated.

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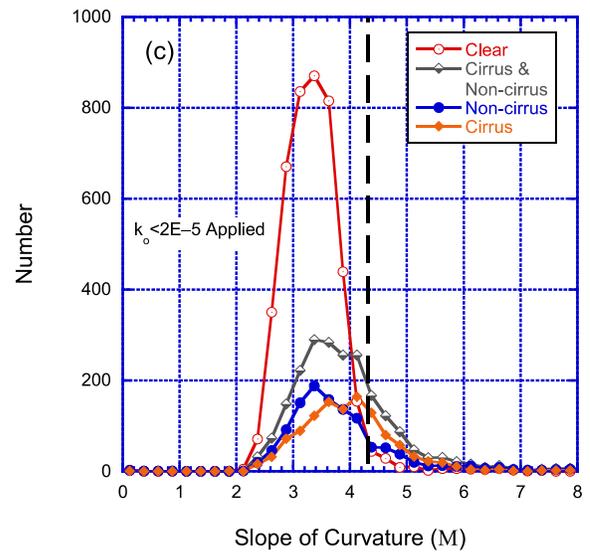
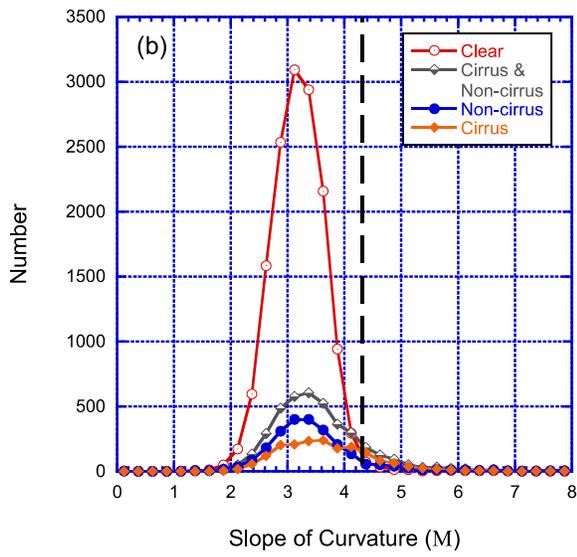
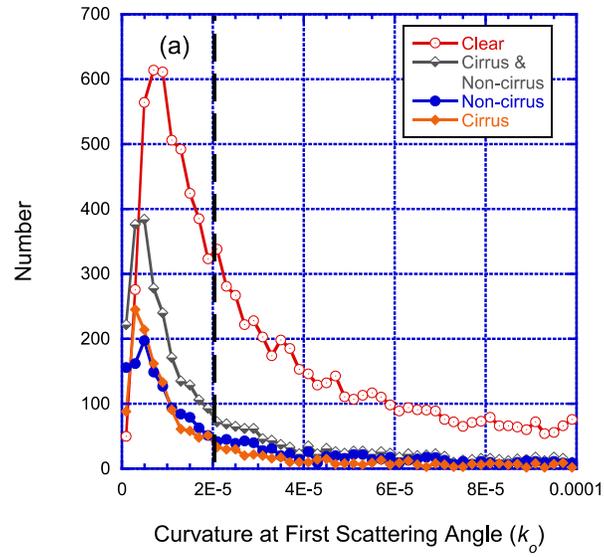


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Figure 5. Similar to Fig. 4, except for Singapore (1.29° N, 103.78° E) from 2009–2013.

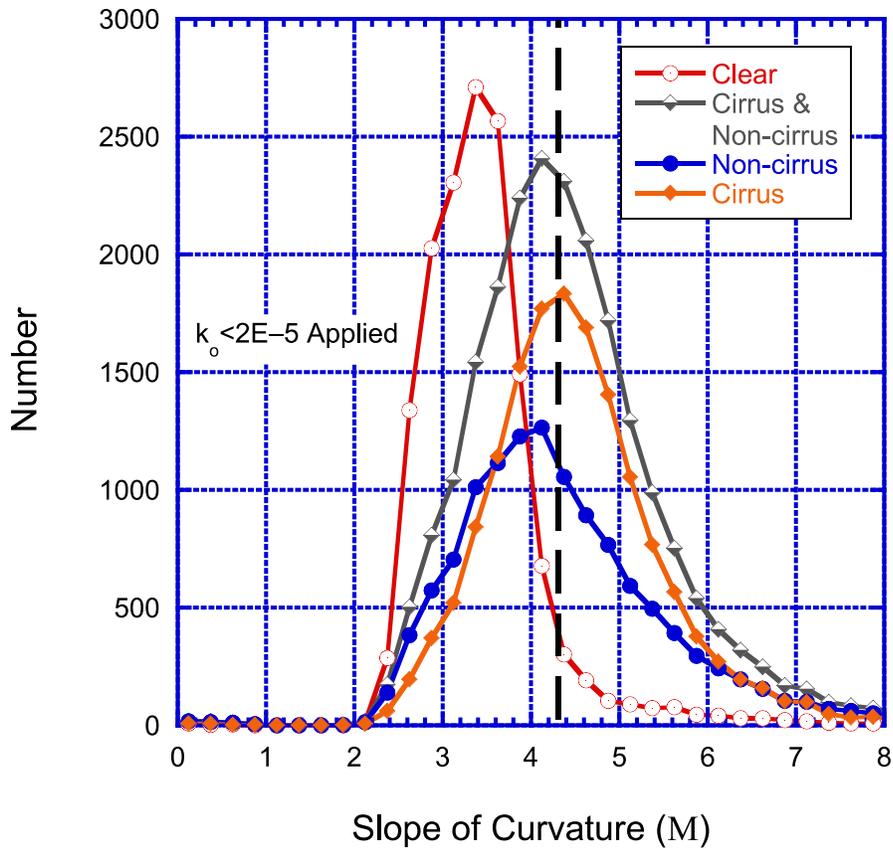
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1726 **Figure 6.** Similar to Fig. 4, except for SEDE BOKER (30.85° N, 34.78° E) from 2007–2013.

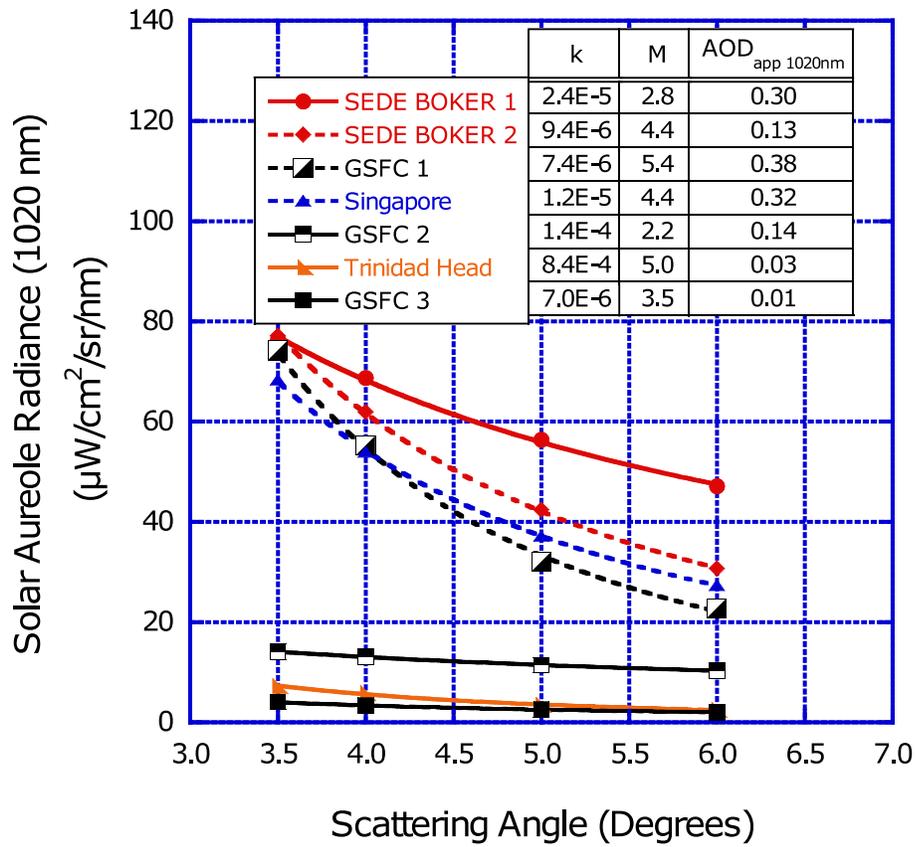
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1729 **Figure 7.** Similar to Fig. 4c including all analyzed sites in Table 3.

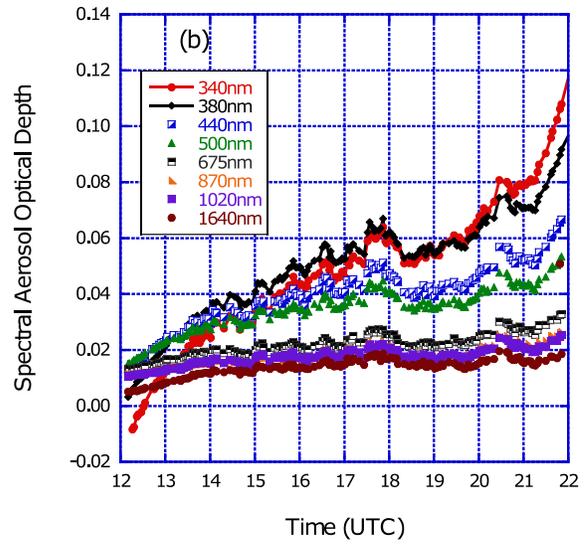
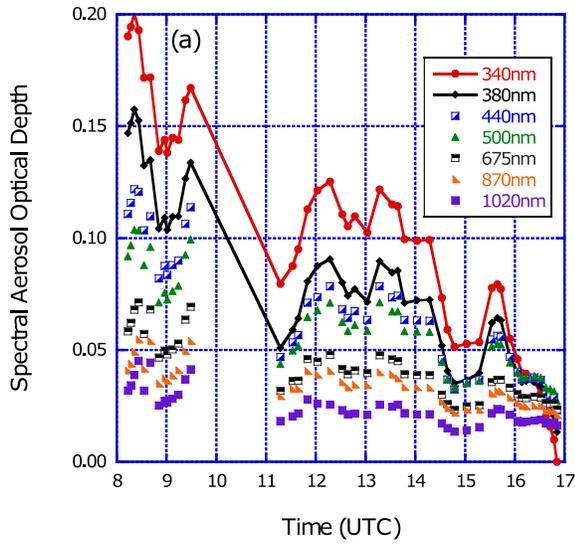
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1732 **Figure 8.** The solar aureole 1020nm radiance versus the scattering angle in degrees for selected sites. Data plots with the dashed
 1733 lines (i.e., SEDE BOKER 2, GSFC 1, and Singapore) all qualify for the removal of data due to optically thin homogeneous cloud
 1734 contamination.

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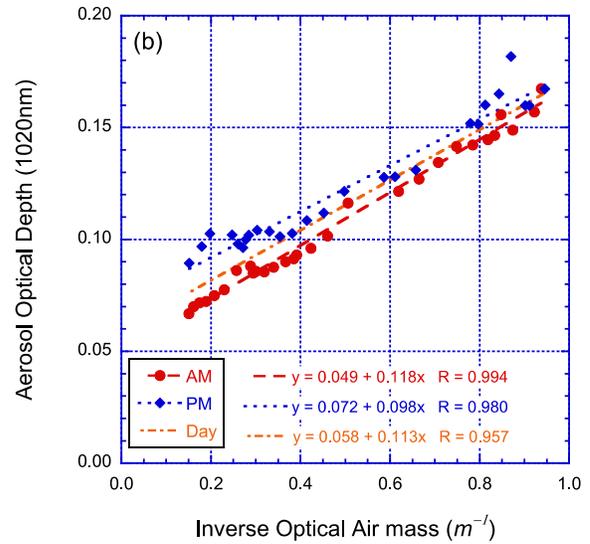
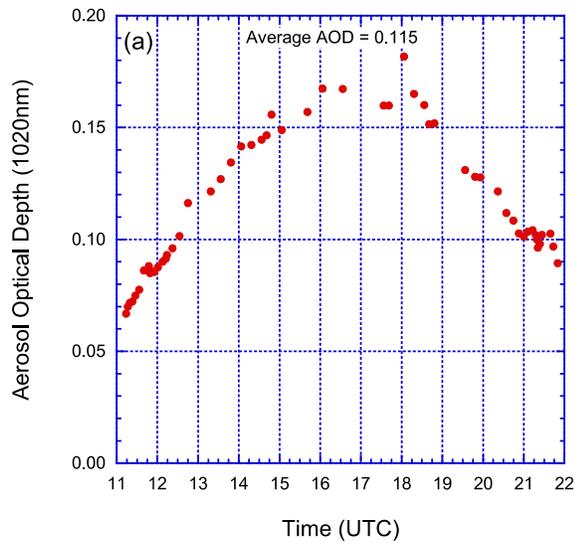
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Figure 9. Time shifted aerosol optical depth (AOD) data examples at Malaga (36.72° N, 4.48° W) and Toronto (43.79° N, 79.47° W). Note the line plot is used to emphasize the 340nm and 380nm AOD impact for the time shift. **(a)** The Level 1.5 AOD cloud screened only data measured at the Malaga site on 30 January 2014. These data show the time shifted AOD especially at short wavelengths represent the instrument clock is too fast. **(b)** The Level 1.5 AOD cloud screened only data measured at the Toronto site on 24 September 2013. The time shifted aerosol optical depth especially at short wavelengths represent when the instrument clock was too slow. Panel (a) also shows the algorithm can be used with data gaps and lower temporal resolution measurement interval compared to panel (b).

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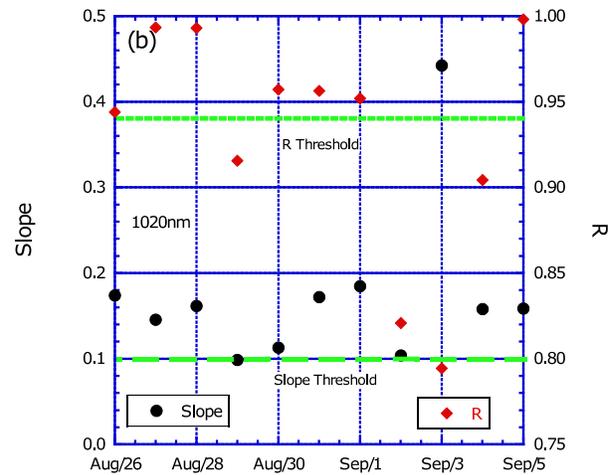
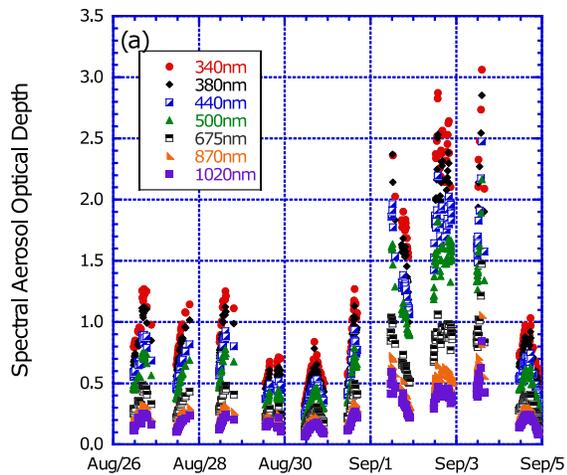
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Figure 10. AERONET data collected at Rio Branco (9.96 °S, 67.87° W) on 30 August 2011. The AOD 1020nm Level 1.5 with only the cloud screening algorithm applied to the data. **(a)** The AOD diurnal dependence presents a concave shape during the solar day. **(b)** The AOD 1020nm and the inverse optical air mass show a highly correlated linear fit and the slope is significant for the full day (day) and morning (AM), and afternoon (PM). Data separation for AM and PM is defined by the local solar noon, which is 16:31:28 UTC at Rio Branco.

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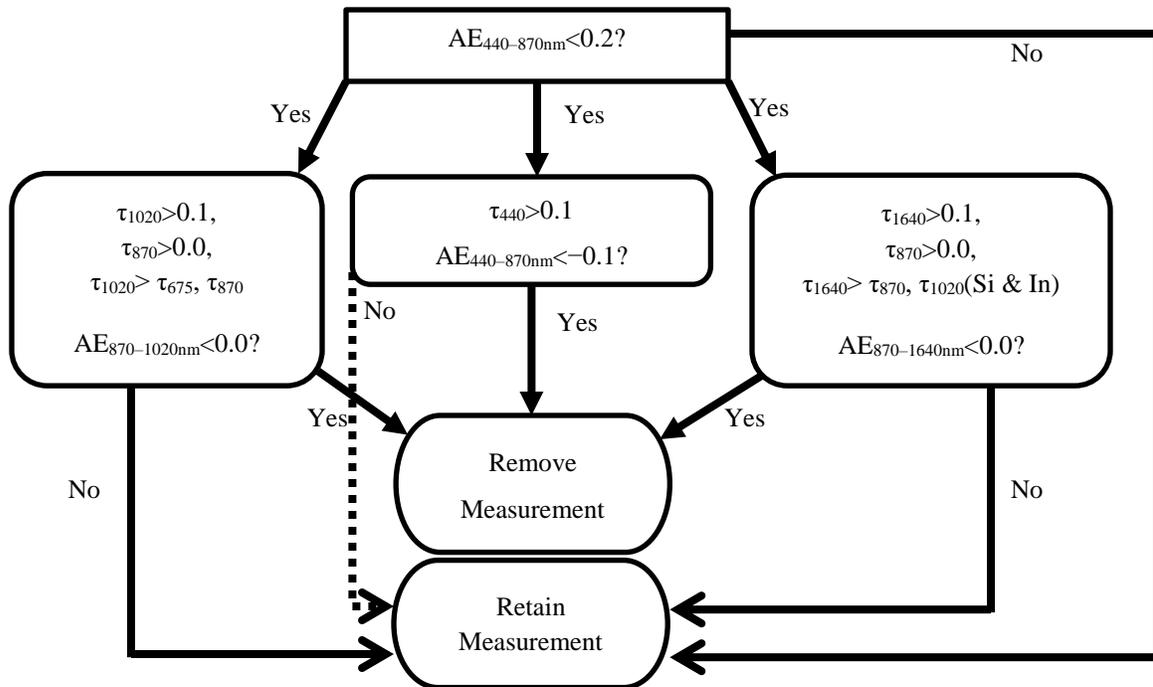


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Figure 11. AERONET data collected at Rio Branco (9.96° S, 67.87° W) from 15 August to 30 September 2011. **(a)** The time series of Level 1.5 spectral AOD (cloud screened only) data is plotted from 26 August to 5 September 2011 and shows repeated diurnal dependence for varying magnitudes of AOD. **(b)** The robust linear fit slope and correlation coefficient (R) is calculated from the AOD 1020nm versus the inverse of the optical air mass (m^{-1}). For the full day evaluation, the green dashed line indicates the threshold for the slope parameter at 0.1 and the solid green line indicates the threshold for the correlation coefficient ($R = 0.94$). Both the slope and R must exceed these thresholds for at least three days scanning from the current day to the last occurrence within the 20-day period to remove the spectral AOD, and in this circumstance, all of the data are removed for the period for Levels 1.5 and 2.0.

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Figure 12. Flowchart of the reverse spectral dependence algorithm used to remove cloud contamination artifacts and instrument anomalies. The 1640nm wavelength is available on some Cimel Model 5 instruments and all Model T instruments.

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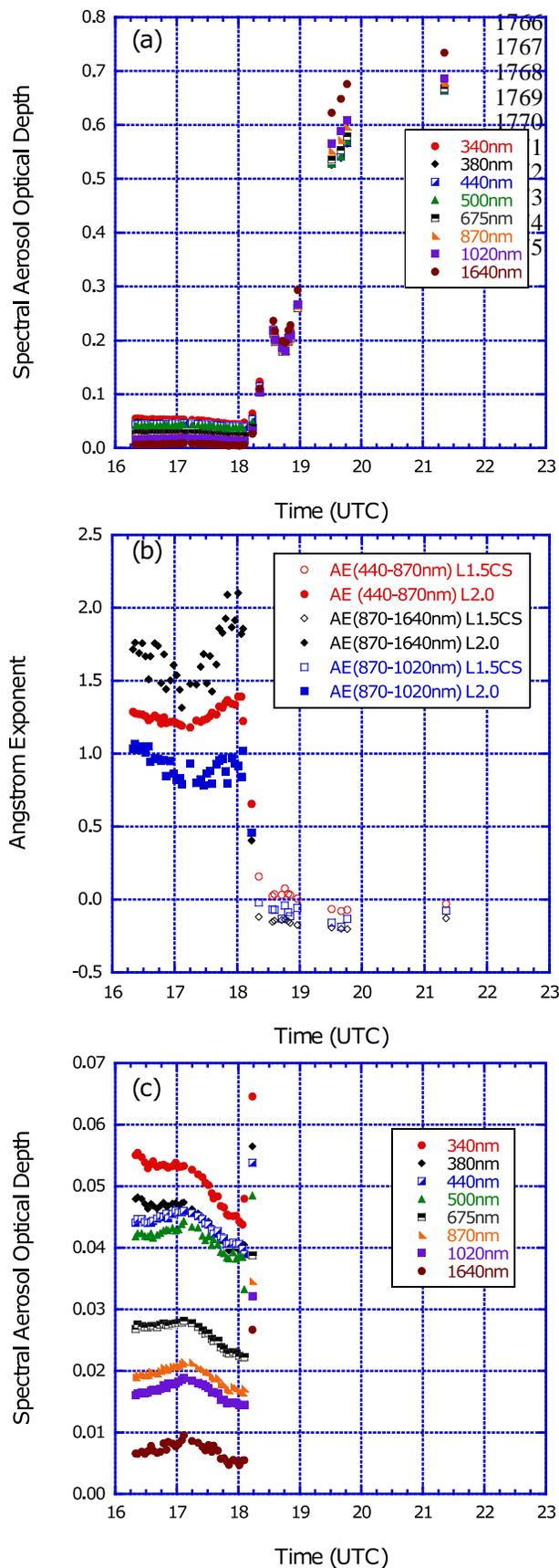
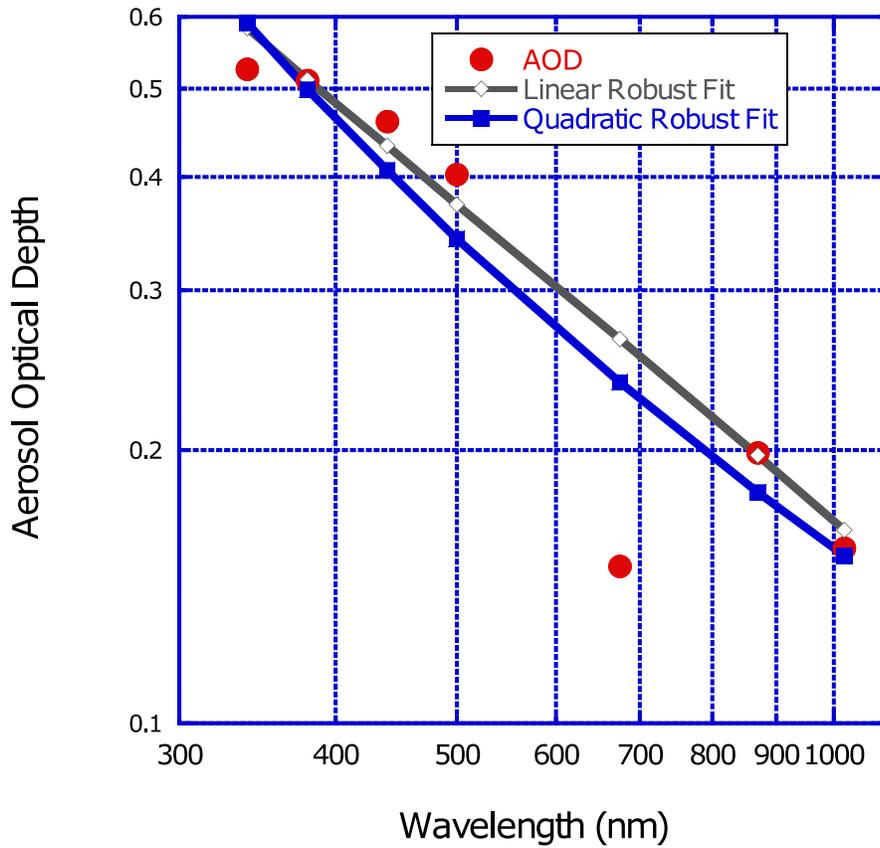
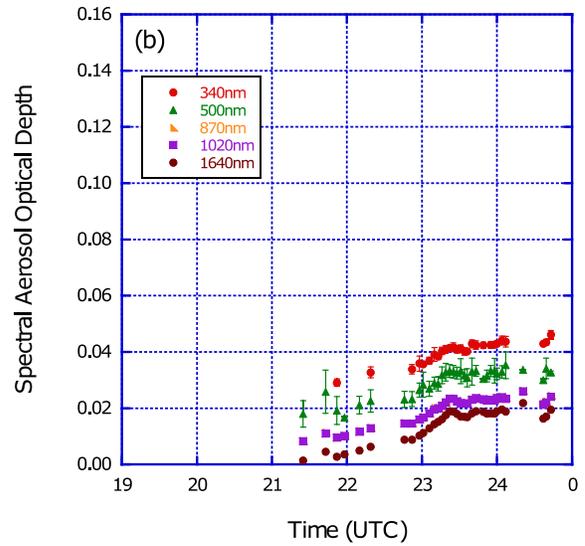
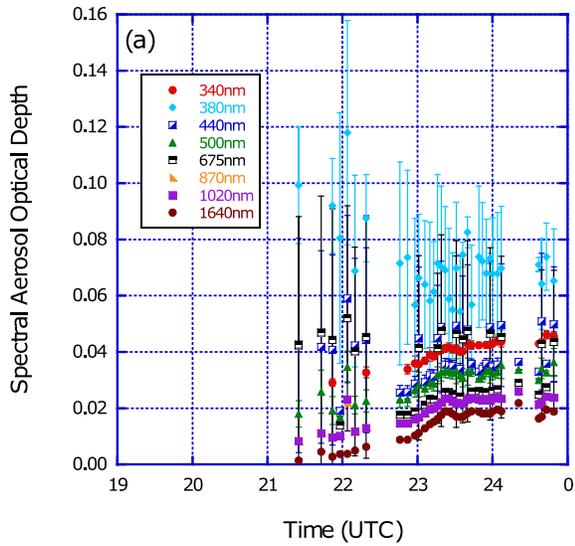


Figure 13. Data from Bratts Lake (50.20° N, 104.71° W) on 7 January 2007. **(a)** The Level 1.5 data with only the cloud screening (CS) algorithm applied shows cloud contaminated data remain after 18:10 UTC. **(b)** For the same period as (a), the Ångström exponent values decreased significantly to a level where coarse mode aerosol particles are not expected. **(c)** The final Level 1.5 and Level 2.0 data series after the reverse spectral dependence quality control or additional cloud screening method has been applied to the standalone Level 1.5 CS data.



1777 **Figure 14.** AERONET data from the Osaka (34.65° N, 135.59° E) site on 16 October 2006 at 22:02:11 UTC. The plot shows
 1778 AOD versus the wavelength with lines identifying the linear and quadratic robust regression fits on logarithmic scale used by the
 1779 AOD spectral dependence algorithm. The 675nm channel is clearly anomalous with fits differing by 0.12 for linear and 0.09 for
 1780 quadratic. In addition, the AOD 340nm appears anomalous with deviations of 0.06 from linear fit and 0.07 from quadratic fit.
 1781 While both wavelengths exceed their respective AOD thresholds (0.023 for 675nm and 0.051 for 340nm), the algorithm
 1782 determines the maximum deviation for linear and quadratic fits and removes the AOD 675nm measurement. A subsequent scan
 1783 by the algorithm determined that the remaining AOD measurements from 340nm to 1020nm were within the established fit
 1784 deviation thresholds.

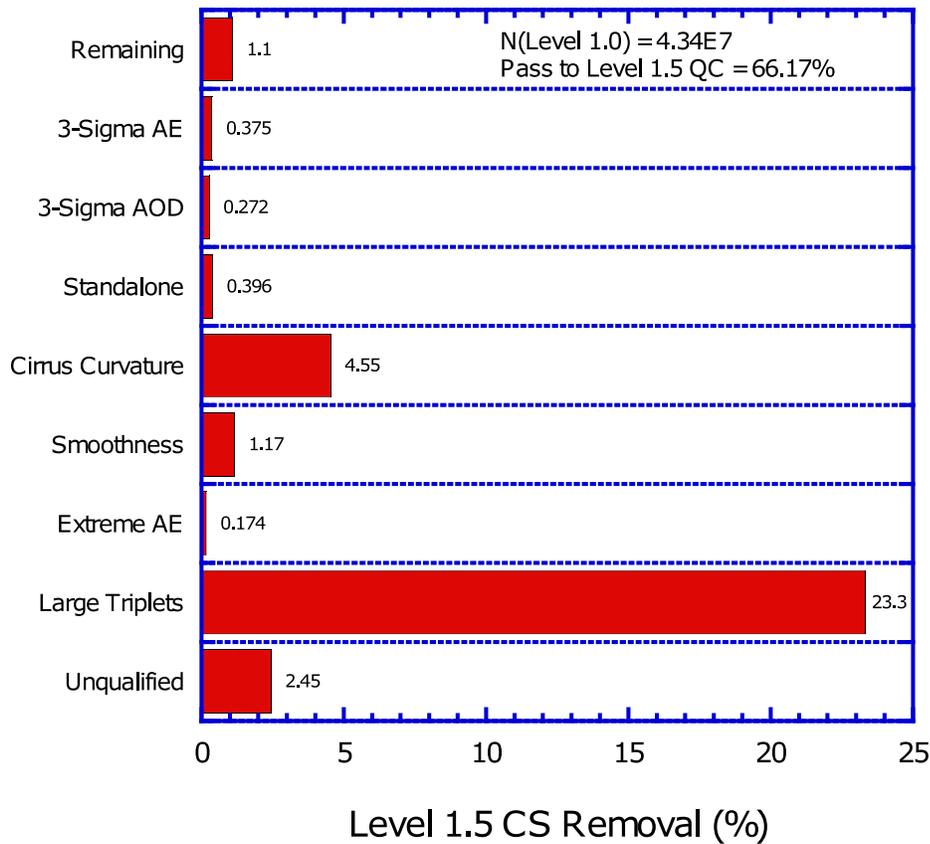


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Figure 15. Spectral AOD exhibiting large triplet variability at PEARL (80.05° N, 86.42° W) on 25 August 2013. **(a)** Version 3 Level 1.5 cloud screened only data is plotted with large triplet variability and these data were not removed by the cloud screening. The error bars represent the triplet variability (AOD Max – AOD Min) divided by 2 so the full range represents the AOD triplet variability. The large triplet variability occurs mainly at shorter wavelengths than 675nm. **(b)** Data affected by large triplet variability (i.e., AOD 380nm, AOD 440nm, and AOD 675nm) are removed by using the Level 1.5 large triplet variability quality controls.

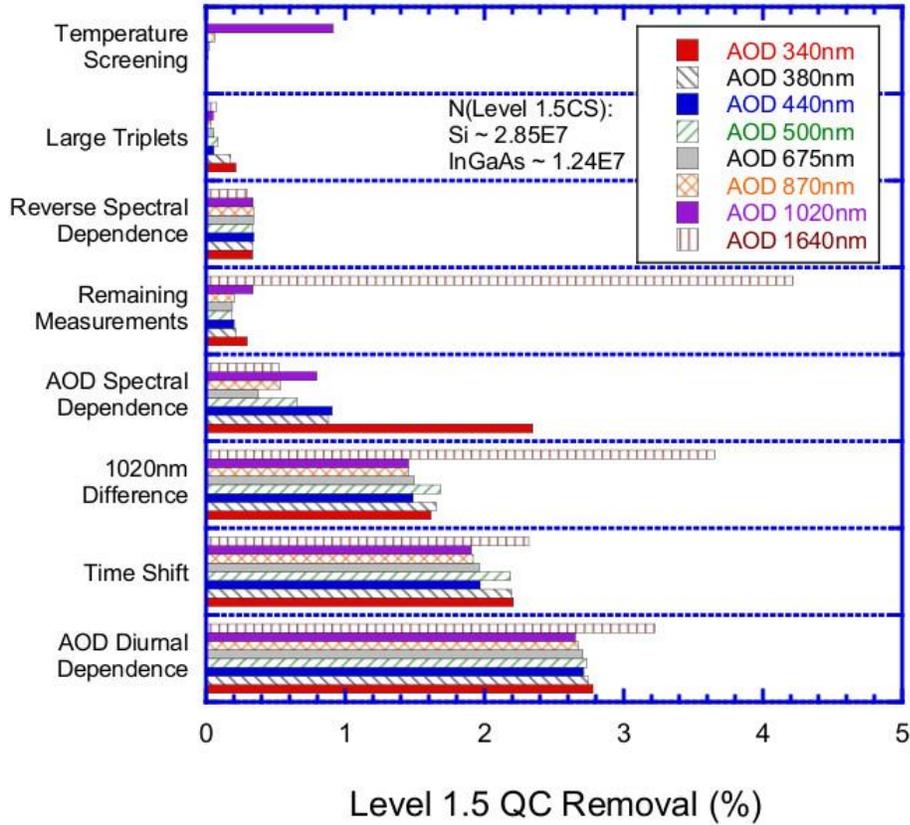
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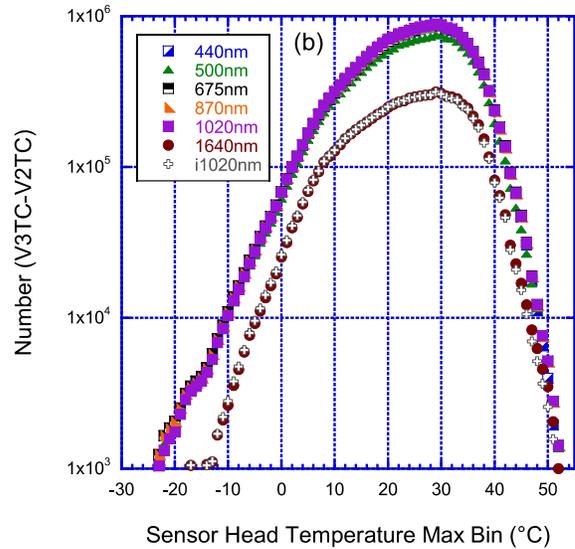
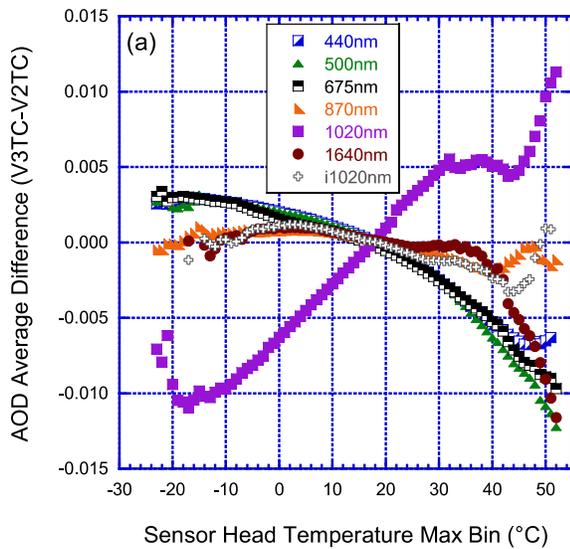
1795 **Figure 16.** The Level 1.0 AOD measurement removal by the Level 1.5 cloud screening algorithm from 1993 to 2018. The plot
1796 shows the impact of the major cloud screening steps in the Level 1.5 cloud screening algorithm and removal of these data applies
1797 to all wavelengths. The triplet criterion removes more than 23% of the Level 1.0 data. Nearly 5% of the Level 1.0 data are
1798 removed due to cirrus cloud contamination. The “Remaining” category indicates the check performed after each cloud screening
1799 step to determine if enough measurements are available and do not meet the high AOD retention criteria. The “Unqualified”
1800 category indicates data that are not triplets or lack sufficient channels to participate in the cloud screening algorithm.

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1802 **Figure 17.** Level 1.5 quality control algorithm wavelength dependent impacts for each major step for the period analyzed from
 1803 1993–2018. The most significant removal for most channels is due to AOD diurnal dependence, time shift, and difference
 1804 between AOD 1020nm on the Silicon and InGaAs detectors (resulting from collimator inconsistency). The AOD 340nm has
 1805 significant removal of AOD spectral dependence. The 1640nm InGaAs channel has significant removal by “Remaining
 1806 Measurements” since this wavelength cannot be checked for quality when the Silicon channels are not available. Temperature
 1807 screening mostly applies to the 1020nm Silicon wavelength due to its strong temperature dependence near the edge of the signal
 1808 sensitivity of the Silicon photodiode detector.

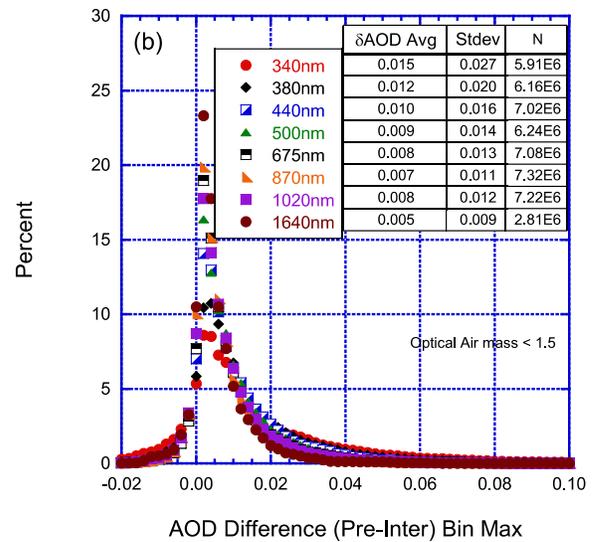
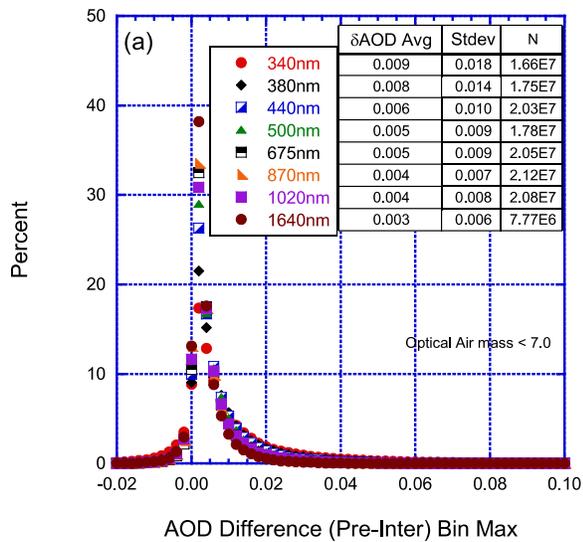
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1811 **Figure 18.** Difference in AOD response between Version 3 and Version 2 temperature correction applied to Version 3 AOD data
 1812 based on the sensor head temperature from 1993–2018. The Version 2 temperature correction assumes temperature ranges for
 1813 1020nm and no temperature correction for all other wavelengths, while Version 3 temperature correction characterizes the
 1814 temperature response for each filter or set of default filters for each instrument for wavelengths $\geq 400\text{nm}$. (a) The AOD average
 1815 difference plotted for each 1°C temperature bin from -25°C to $+55^\circ\text{C}$. The AOD 1020nm exhibits an opposite trend compared to
 1816 the other wavelengths varying from -0.01 at low temperatures and up to $+0.01$ at high temperatures. Other wavelengths have
 1817 slight differences at cold temperatures but apparent dependencies at high temperatures greater than 40°C possibly due to
 1818 extrapolation of the temperature coefficients to higher temperatures. (b) The number of measurements plotted for each 1°C
 1819 temperature bin with a minimum of 1000 observations.

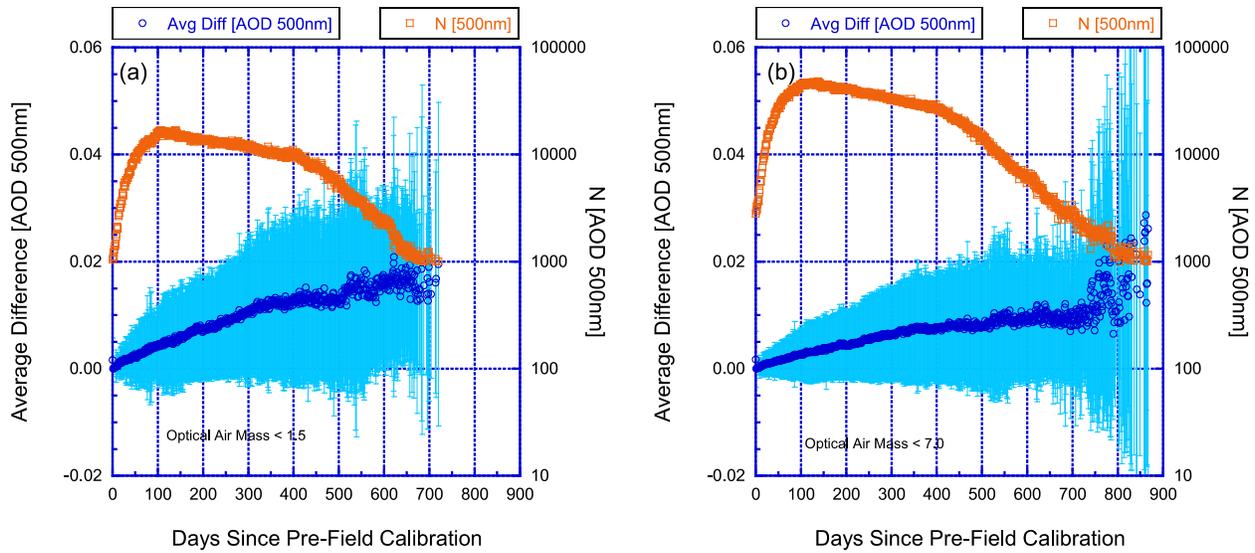
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1822 **Figure 19.** Using data qualified as Version 3, Level 2.0, aerosol optical depth (AOD) average difference comparing
 1823 measurements only with the pre-field calibration applied versus instruments with both the pre-field and post-field calibrations
 1824 applied from 1993–2018. Calibration sites are excluded from the analysis. The histogram of AOD differences is provided for the
 1825 optical air mass $1.0 \leq m < 7.0$ range in panel (a) and $1.0 \leq m < 1.5$ range in panel (b). The average difference is largest for the UV
 1826 wavelengths and smallest for the longer wavelengths.

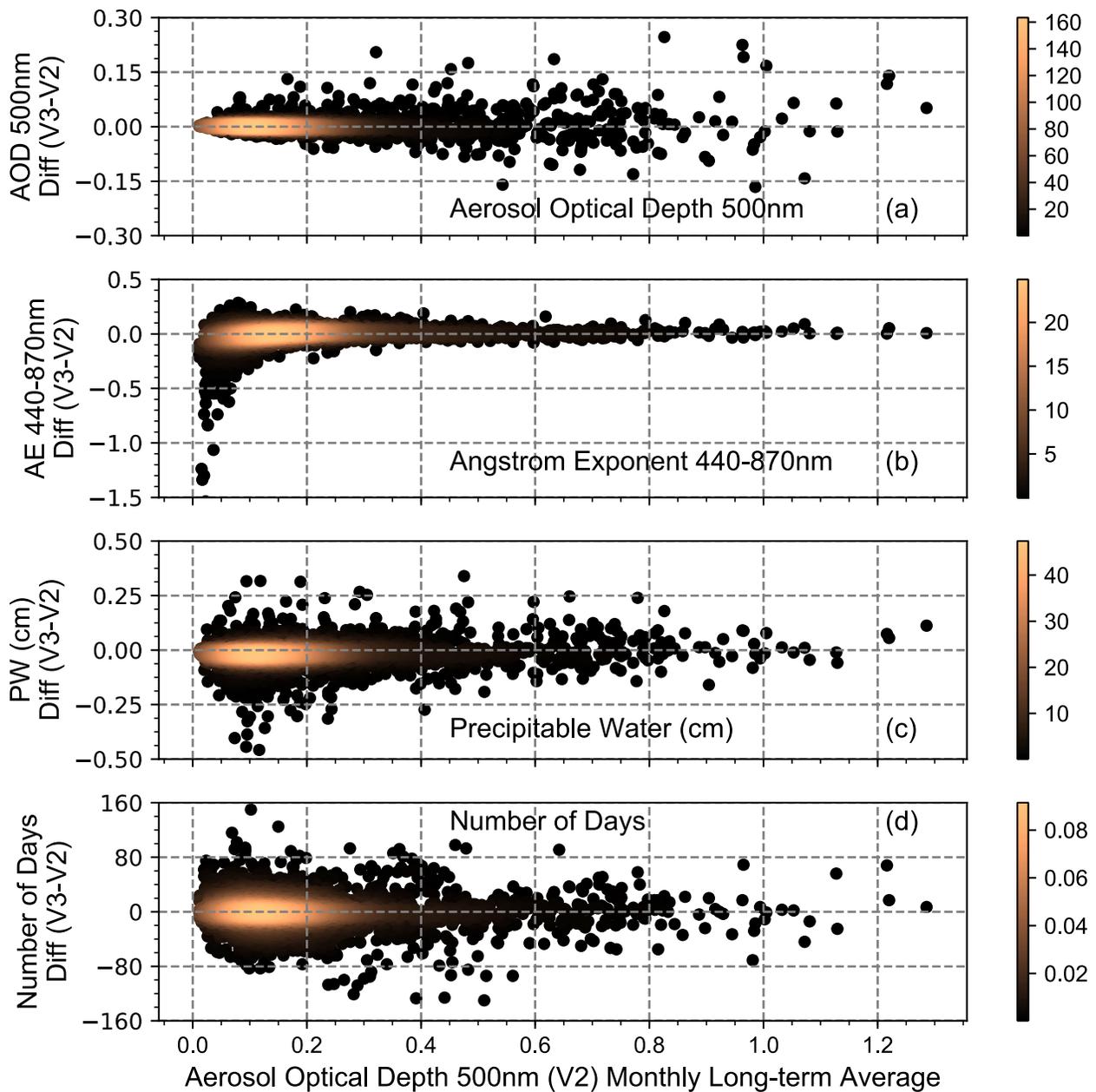
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1829 **Figure 20.** Using data qualified as Version 3 Level 2.0 aerosol optical depth (AOD) 500nm average difference comparing
 1830 measurements only with the pre-field calibration applied versus instruments with both the pre-field and post-field calibrations
 1831 applied from 1993–2018. The AOD average differences are provided for the optical air mass $1.0 \leq m < 7.0$ range in panel (a) and
 1832 $1.0 \leq m < 1.5$ range in panel (b). Vertical bars represent the standard deviation for each day bin. The secondary y-axis in
 1833 logarithmic scale represents the number of measurements of AOD 500nm for each day bin.

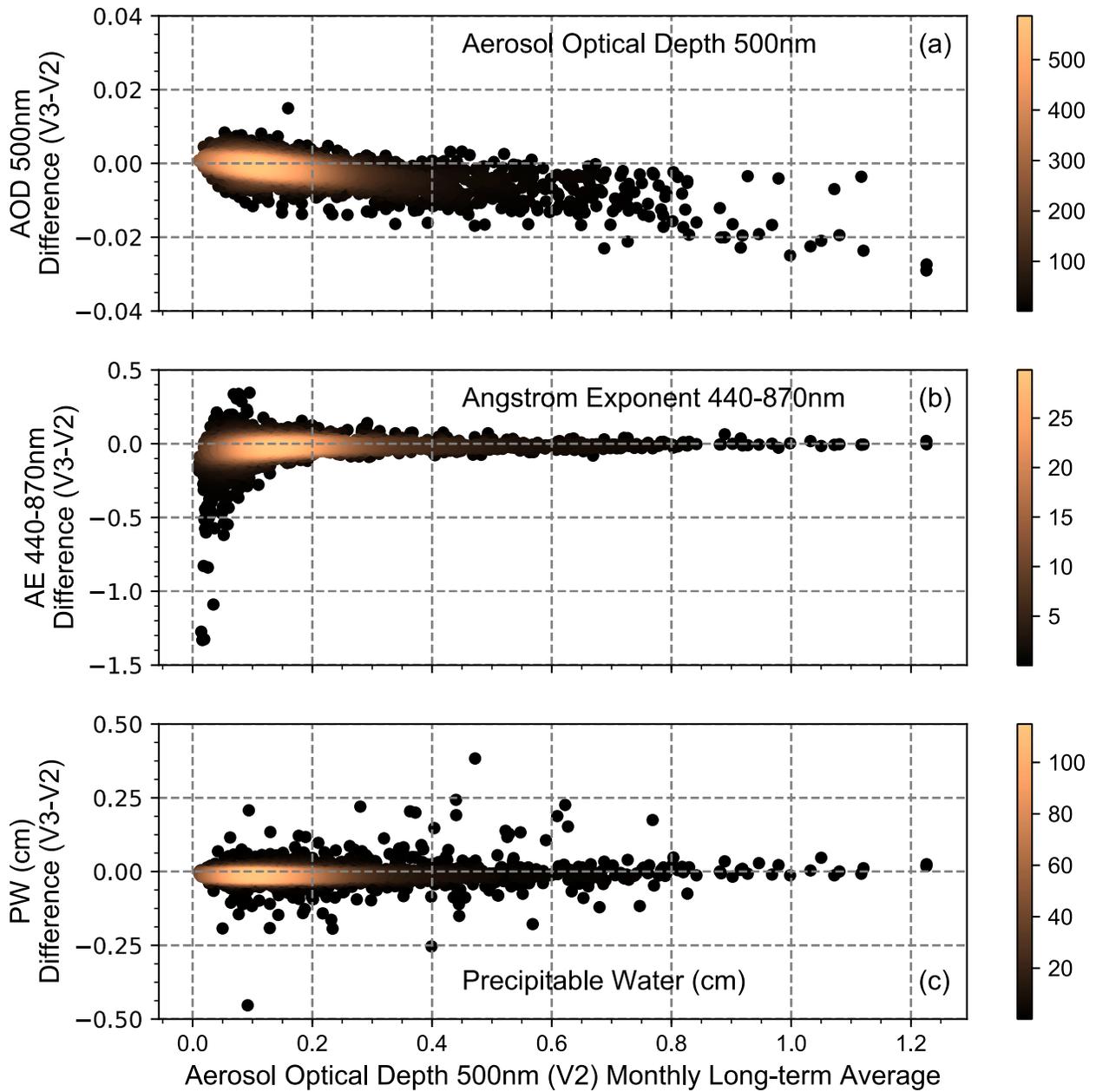
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1836 **Figure 21.** Comparison of Version 3 and Version 2 Level 2.0 multi-year monthly average data sets. (a) The aerosol optical depth
 1837 (AOD) interpolated to 500nm to include data from instruments without 500nm. (b) The Ångstrom exponent (AE) is calculated
 1838 utilizing the inclusive ordinary least squares regression fit from 440–870nm. (c) The precipitable water in cm is derived from the
 1839 935nm water vapor channel. (d) The difference in the number of days is determined for each monthly long-term average.

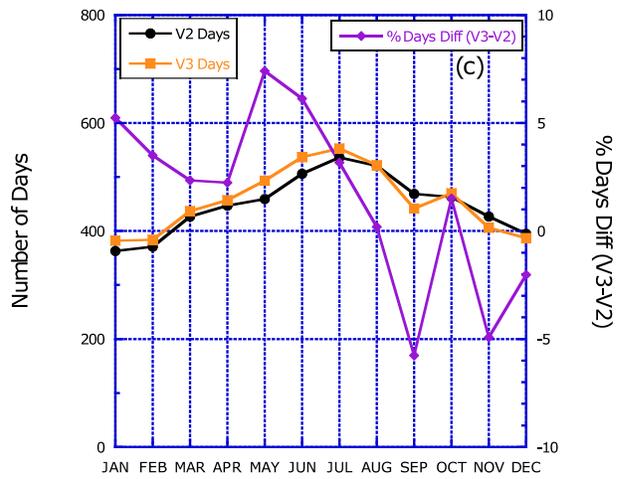
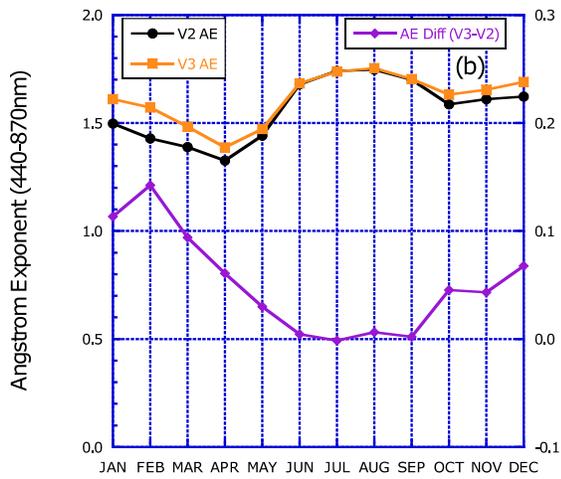
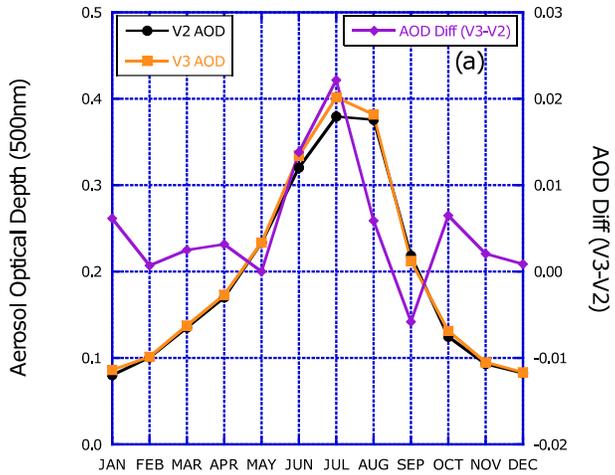
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1842 **Figure 22.** Comparison of Version 3 and Version 2 Level 2.0 multi-year monthly average data sets for time matched
 1843 instantaneous observations in both data sets. The panels are similar to those in Fig. 21.

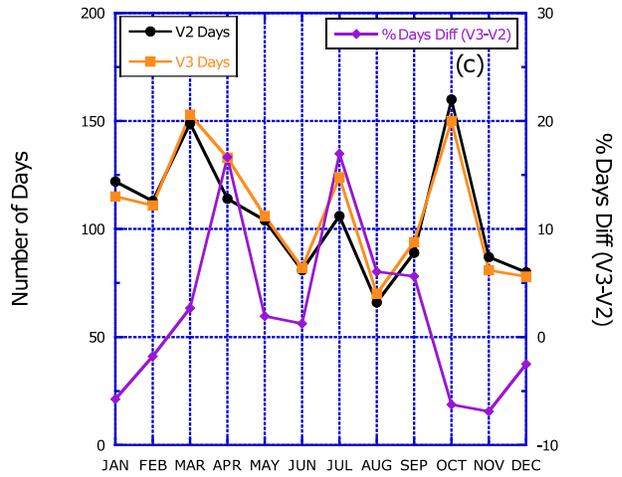
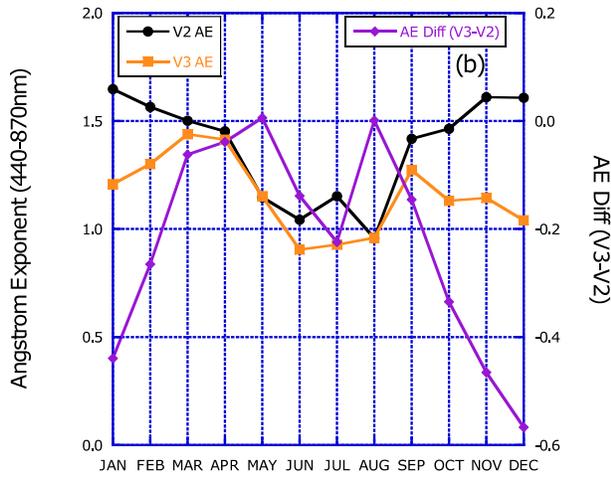
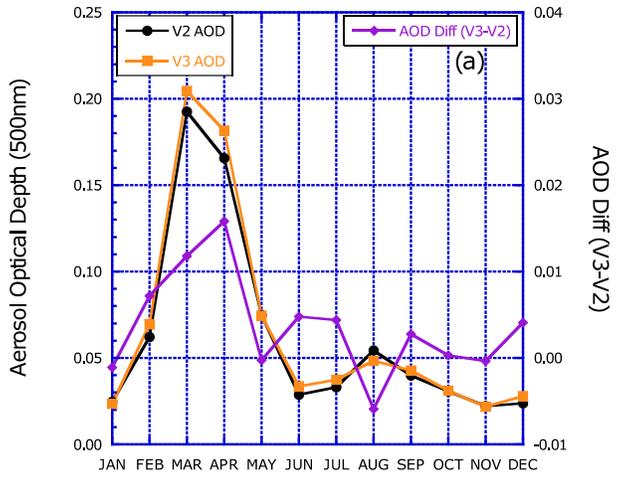
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1846 **Figure 23.** Long-term multi-year (1993–2016) monthly average comparisons of the Version 3 and Version 2 Level 2.0 data sets
 1847 at the NASA Goddard Space Flight Center (GSFC), Maryland, USA. The panel (a) provides the AOD interpolated to 500nm for
 1848 each version on the primary y-axis and differences on the secondary y-axis. The panels (b) and (c) are plotted similarly for the
 1849 AE_{440–870nm} and the number of days in the multi-year monthly average, respectively.

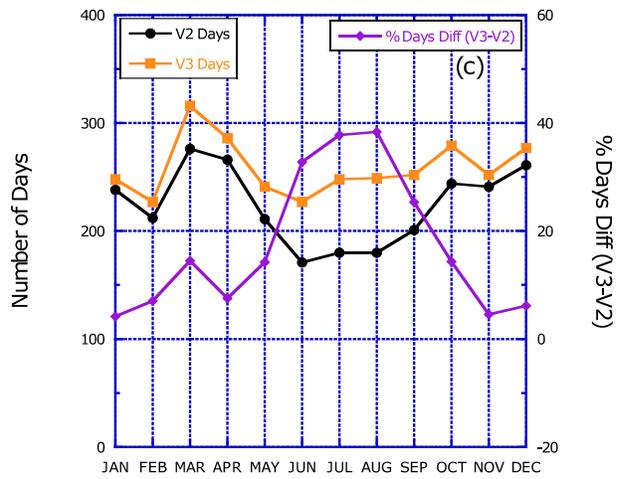
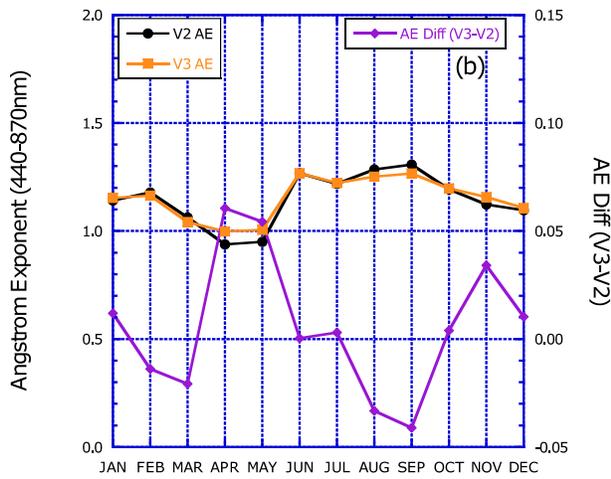
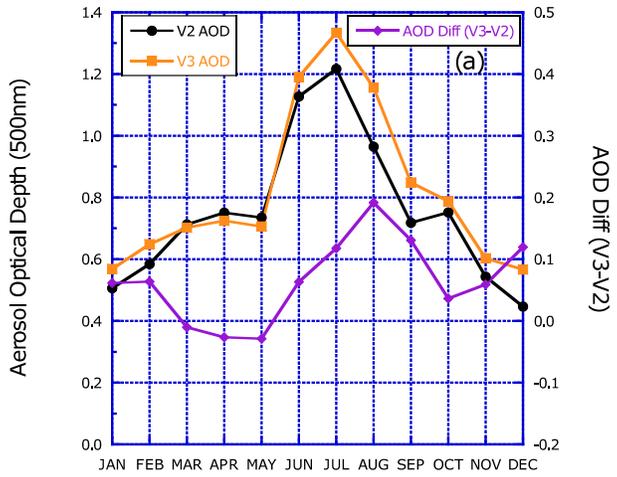
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1852 **Figure 24.** Similar to Fig. 23 except for Lulin, Taiwan (23.47° N, 120.87° E) from 2006–2017.

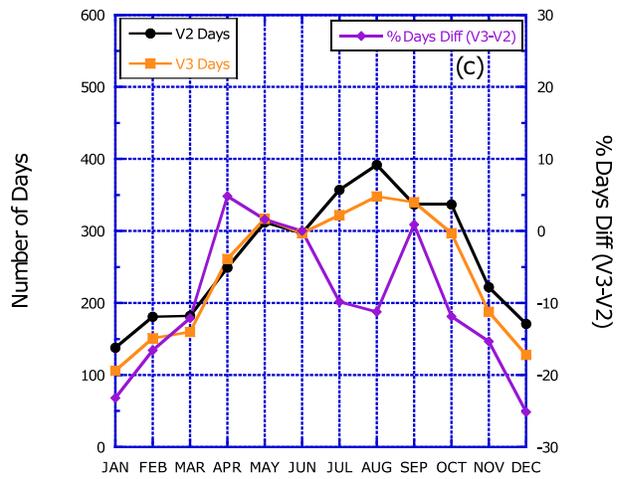
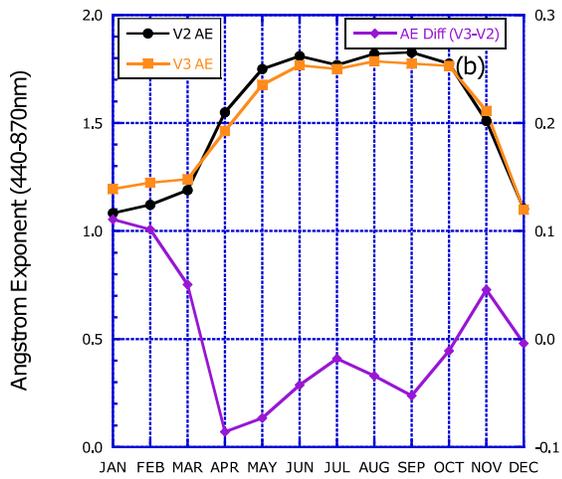
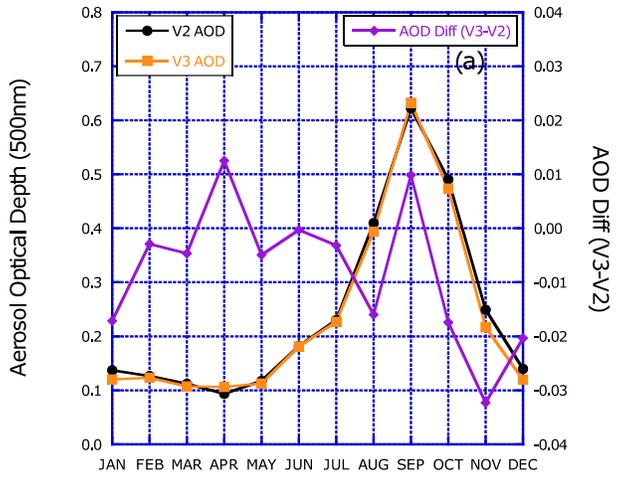
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1855 **Figure 25.** Similar to Fig. 23 except for XiangHe, China (39.75° N, 116.96° E) from 2001–2017, except 2009.

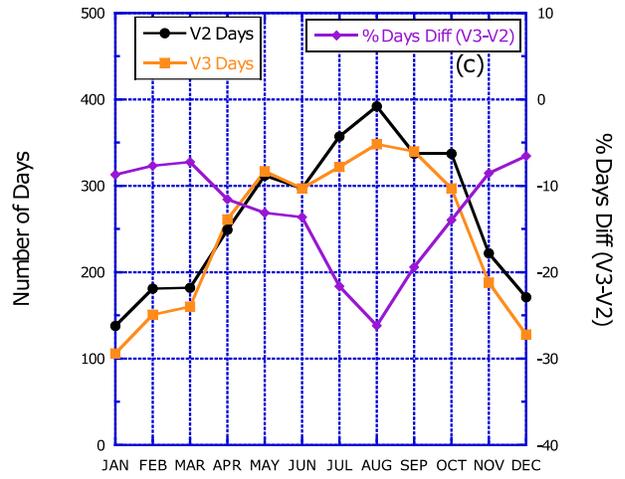
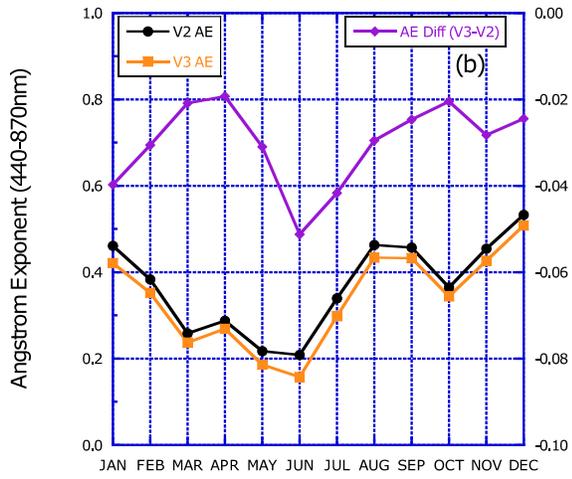
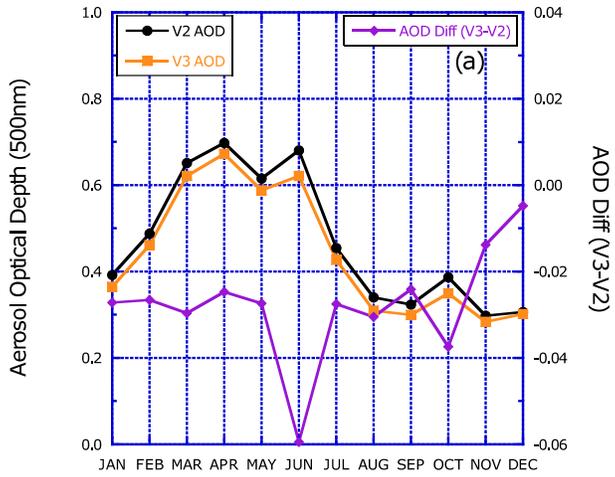
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1858 **Figure 26.** Similar to Fig. 23 except for Mongu, Zambia (15.25° S, 23.15° E) from 1997–2010.

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Figure 27. Similar to Fig. 23, except for IER-Cinzana, Mali (13.28° N, 5.93° W) from 2004-2017.