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Accuracy of retrieving temperature and humidity profiles by ground-based microwave radiometry in truly complex terrain

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Abstract

Within the Innsbruck Box project, a ground-based microwave radiometer (RPG-HATPRO) was operated in the Inn Valley (Austria), in very complex terrain, between September 2012 and May 2013 to obtain temperature and humidity vertical profiles of the full troposphere with a specific focus on the valley boundary layer. The profiles obtained by the radiometer with different retrieval algorithms based on different climatologies, are compared to local radiosonde data. A retrieval that is improved with respect to the one provided by the manufacturer, based on better resolved data, shows a significantly smaller root mean square error (RMSE), both for the temperature and humidity profiles. The improvement is particularly substantial at the heights close to the mountaintop level and in the upper troposphere. Lower level inversions, common in an alpine valley, are resolved to a satisfactory degree. On the other hand, upper level inversions (above 1200 m) still pose a significant challenge for retrieval. For this purpose, specialized retrieval algorithms were developed by classifying the radiosonde 15 climatologies into specialized categories according to different criteria (seasons, day-time, nighttime) and using additional regressors (e.g., measurements from mountain stations). The training and testing on the radiosonde data for these specialized categories suggests that a classification of profiles that reproduces meaningful physical characteristics can yield improved targeted specialized retrievals. A really new and very promising method of improving the profile retrieval in a mountain region is adding further information in the retrieval, such as the surface temperature at fixed levels along a topographic slope or from nearby mountain tops.

1 Introduction

Precise knowledge of the temperature and humidity structure of the atmosphere is not only essential for numerical weather prediction, but also for the study of small-scale phenomena within the atmospheric boundary layer. Especially in complex terrain

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the boundary layers are still a topic of intense research, and the information about the vertical profiles, such as temperature and humidity, as well as their temporal evolution is particularly valuable (Rotach and Zardi, 2007). For this later topic the temporal scales of minutes and spatial scales on the order of few tens to hundreds of metres are required.

One of the most accurate methods for measuring atmospheric vertical profiles of temperature and humidity are radio-soundings, but given their cost as well as finite space/time resolution, (routinely once or twice per day) they are inadequate for a detailed study of the diurnal evolution of the near surface atmosphere. An alternative to obtaining such profiles is the use of remote sensing. Passive remote sensing from satellites, exploiting infrared or microwave radiation naturally emitted by atmospheric constituents, has the advantage to cover areas with sparse data (e.g., oceans). The vertical resolution is fairly good in the upper troposphere; however the information deteriorates towards the ground, due to the satellite's viewing geometry and the opacity of thick clouds (Zhou et al., 2007); in addition, the surface contribution to the signal has to be disentangled from the atmospheric signal which is more difficult close to the ground. For example, Divakarla et al. (2006) compared temperature profiles from an atmospheric infrared sounder (AIRS) with global radiosonde data for two years, finding a root mean square error (RMSE) larger than 1.5 K at ground level. Thus, the accuracy of passive remote sensing from satellites is too poor to be useful for studying boundary layer evolution.

On the other hand, ground-based remote sensing can provide valuable information on the temperature and humidity structure of the lower troposphere. Methods using passive microwave radiometry have rapidly developed within the last decade when radiometers became commercially available. The measurement principle of a ground-based passive radiometer is measuring the radiation emitted by the atmospheric constituents (oxygen, water vapour, cloud droplets). Unlike infrared radiometers that are able to produce vertical profiles only under clear sky conditions due to strong liquid water absorption, a microwave radiometer operates under almost all conditions (Löhner et al., 2009) and is therefore more appropriate for long-term monitoring of a valley at-

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mosphere. One of commercially available radiometers is the RPG-HATPRO (Humidity and Temperature Profiler) manufactured by Radiometer Physics GmbH (Rose et al., 2005). Statistical algorithms are used to retrieve humidity and temperature vertical profiles from the observed brightness temperatures. These retrieval algorithms exploit

5 a local history of pressure-temperature-humidity profiles by using a multiple regression approach following Löhnert and Crewell (2003) and Crewell and Löhnert (2007). The advantages of profiles derived from passive microwave observations over radiosonde data, beyond the economic convenience, are their high temporal resolution (on the order of 1 min or less), their vertical resolution comparable to current operational numerical weather prediction models and their ability to operate under all weather conditions, because clouds are semi-transparent for the microwave frequency range, with the exception of precipitation (Löhnert et al., 2009). Crewell and Löhnert (2007) compared RPG-HATPRO observations at Lindenberg (Germany) with data from 80 nearby radiosondes over flat terrain. Löhnert and Maier (2012) did a 3.5 year statistical comparison between 2107 radiosoundings and RPG-HATPRO temperature profiles at the lowland station of Payerne (Switzerland). They found accuracies between 0.4 and 0.8 K in the lowest 500 m, gradually deteriorating with height (1.2 K at 1200 m and 1.7 K at 4000 m above ground).

In complex terrain, Sanchez et al. (2013) operated a MP-3000A microwave radiometer in Sierra Guadarrama (Spain). Comparison with radiosondes launched at a distance of 50 km provided accuracies of about 2 K in the lower troposphere. A MTP-5HE (by ATTEX) was used in the Bergen Valley (Wolf et al., 2014) in order to obtain temperature profiles and compare them with one-year measurements from two automatic meteorological stations, located at the ground and on a mountain about 550 m above the valley floor; they obtained a RMSE of 0.2 and 0.8 K for the two stations, respectively.

Regarding the performance of retrieving absolute humidity profiles, Löhnert et al. (2009) compared the absolute humidity profiles obtained from simulated measurements by such a radiometer with radiosonde data at the aerological station of Payerne. They found an RMSE on the order of 0.8 g m^{-3} in the lowest 500 m, around

0.7 g m^{-3} at 1200 m and about 0.4 g m^{-3} at 4000 m above ground. Sanchez et al. (2013) found comparable accuracies for more complex terrain.

Within the Innsbruck Box project (Rotach et al., 2015), a RPG-HATPRO has been operated since 2012 in Innsbruck (Austria), located in the Inn Valley, an approximately East–West oriented 1700 m deep *U* shaped alpine valley (Fig. 1). As far as the authors know, this type of a radiometer has never been used for a prolonged period of time in so truly complex setting where inversions (near surface and especially near mountain top) pose a significant challenge to the radiometer measurements and where regular radiosoundings are available. The questions that we specifically want to address are whether a radiometer can provide useful profiles in complex terrain and how accurate the retrieved profiles are in comparison to radiosonde data. In particular, we are interested in the performance of the radiometer within the valley boundary layer. The employment of ground-based radiometry in an alpine valley is especially challenging because the topography strongly affects the boundary layer dynamics and temperature structure through formation of strong inversions, differential solar heating (Matzinger et al., 2003), anabatic/katabatic winds (Zardi and Whiteman, 2012), secondary cross-valley circulation (Weigel and Rotach, 2004), etc. Since all retrieval methods assume horizontal homogeneity of the atmosphere, which is not satisfied in an alpine valley, it is necessary to assess its performance and accuracy in complex terrain. With this in mind we wish to examine the possibility of improving the retrieval algorithm by including additional regressors, such as temperature observations along the slopes or on mountain tops.

Section 2 describes the basics of microwave radiometry, radiative transfer, as well as the retrieval algorithms. In Sect. 3 the experimental set-up is explained. The comparison between the profiles obtained from the microwave radiometer by applying different retrieval algorithms with radiosonde data for 84 days between September 2012 and May 2013 are presented in Sect. 4. A final discussion and open challenges are given in Sect. 5.

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2 Microwave radiometry and retrieval development

2.1 Radiative transfer

In the microwave region of the electromagnetic spectrum (about 3–300 GHz, 1 mm to 10 cm wavelength), a ground-based receiver measures the thermal radiation emitted by

- 5 the atmospheric constituents, especially O₂ and H₂O (the latter in both gaseous and liquid form), and the cosmic background radiation. With the assumptions of a plane-parallel atmosphere, thermodynamic equilibrium and negligible scattering (valid for frequencies below 90 GHz in the absence of rain) the brightness temperature T_b at the ground for each frequency ν is given by:

$$10 \quad T_b(\nu) = T_{b0}e^{-\tau(s_t)} + \int_0^{s_t} \alpha(s)T(s)e^{-\tau(s)}ds \quad (1)$$

with s being the path length, α the absorption coefficient and τ the optical depth. The first term in Eq. (1) originates from the cosmic background radiation attenuated over the path of propagation. The second term represents the integral from the top of the atmosphere to the ground of the emission by atmospheric gases and hydrometeors in a particular atmospheric layer that is attenuated by the underlying atmospheric layers (Pospichal, 2009).

2.2 Retrieval algorithms for atmospheric quantities

In order to obtain atmospheric quantities from observed brightness temperatures, the radiative transfer equation (Eq. 1) has to be inverted. However, since this is an ill-posed problem, it cannot be solved analytically. Therefore, statistical methods have to be applied, such as multiple regression or neuronal networks. The algorithms we use for this work are based on a set of training data from historical profiles (climatology) and allow

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retrieval of vertical profiles of temperature and humidity (Löhnert and Crewell, 2003). In our case, this set of training data are profiles of pressure, temperature and relative humidity (p – T –RH) obtained by radiosonde measurements. Under the assumption of a horizontally homogeneous atmosphere, a profile consists of several layers characterized by their proper temperature, thus the integral in Eq. (1) can be converted into a sum. Theoretical T_b from the training set of radiosonde data are computed with a non-scattering radiative transfer model using gas absorption following Rosenkranz (1998) and the liquid cloud absorption according to Stogryn et al. (1995). Liquid clouds are assumed to exist above a 95 % relative humidity threshold with a temperature warmer than 243.15 K. In this case the liquid water content is calculated following the modified adiabatic model by Karstens et al. (1994).

A linear regression between these modelled T_b and temperatures at some pre-defined atmospheric layers can then be performed. These regression coefficients and T_b measured by the radiometer are then used to retrieve the atmospheric profiles also in the absence of radiosoundings. The Output (Out^i) of the retrieval algorithm, which is the temperature or the absolute humidity of the i th atmospheric layer, is related to the measured T_b at the j frequencies in a linear and a quadratic term, respectively, and to a number of additional regressors (such as surface pressure or temperature sensors) that are introduced to potentially improve the statistical performance. The regression equation is given by Eq. (2):

$$\text{Out}^i = C_{\text{Os}}^i + \sum_{\text{freq},j} C_{\text{Tb},1}^{ij} \text{Tb}_j + \sum_{\text{freq},j} C_{\text{Tb},2}^{ij} \text{Tb}_j^2 + \sum_{\text{sens},j} C_{\text{Sr},1}^{ij} \text{Sr}_j + \sum_{\text{sens},j} C_{\text{Sr},2}^{ij} \text{Sr}_j^2 \quad (2)$$

where C_{Os}^i is an offset, $C_{\text{Tb},1}^{ij}$ and $C_{\text{Tb},2}^{ij}$ are the coefficients for the linear and quadratic terms, respectively, of the brightness temperatures Tb_j , $C_{\text{Sr},1}^{ij}$ and $C_{\text{Sr},2}^{ij}$ are the coefficients (linear and quadratic, respectively) for the sensors at the ground level Sr_j and the index i runs over several layers of the atmosphere. The vertical grid (Table 1) for which the profiles are retrieved depends on vertical resolution of the radiometer, and is grad-

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ually getting coarser with height. In our case, the elevation angles used for scanning are: 90.0, 30.0, 19.2, 14.4, 11.4, 8.4, 6.6, 5.4, 4.8, 4.2°.

The retrieval provided by the manufacturer that we refer to as “RPG algorithm”, uses radiosonde profiles at Innsbruck airport from 1999 to 2005 and from 2009 to 2012, with a low vertical resolution (i.e., standard and significant levels only) as a training dataset. The radiosonde measurements are only available during nighttime (02:00 UTC). Although this significantly limits the climatology, still the more challenging nighttime near surface atmosphere with frequent inversions is well represented. The algorithm also takes into account measurement errors of the T_b introducing a randomly distributed noise with a SD of 0.35 K (i.e., noise level). Only the surface pressure is used as an additional regressor. Table 2 summarizes the main characteristics of the RPG algorithm.

2.3 Improving the retrieval algorithm

The first step in enhancing the retrieval performance is to use a more statistically robust set of radiosonde data. The latter are now used at their full temporal resolution: 10 s for the soundings before 2009 and 2 s for the later ones, corresponding to a height resolution of 40–50 and 8–10 m, respectively. Additionally about 130 daytime soundings from the MAP (Bougeault et al., 2001) and ALPNAP (Harnisch et al., 2009) international projects, launched between 1999 and 2005 from the airport of Innsbruck, are used to include information on the diurnal variation. A total amount of 3157 radiosonde profiles passed the quality check (cf. Sect. 3.2.1) and are used in the radiative transfer model. In addition, the best choice of regression (linear vs. quadratic) is tested, and the performance of the retrieval algorithm for different noise levels is investigated in order to determine the optimal value. The resulting retrieval will be denoted “IMGI algorithm” in the following (see Table 3).

The historic sounding data-set is split into two subsets: the training set is used to obtain the regression coefficients, and the testing set to test the performance of the new retrieval. The subsets are chosen randomly: 70 % of the total soundings for training and 30 % for testing. Since several retrievals are obtained (see the following sub-section),

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the algorithm is considered to have an improvement over the other algorithms only if the RMSE between radiosonde and retrieved profile decreases by 0.1 K and more. After the validation, the best retrieval is applied to the actual radiometer data.

2.3.1 Specialized retrieval algorithms

- 5 The entire radiosonde data-set is, naturally, very heterogeneous, spanning different seasons, times of day, atmospheric stability, etc. Löhnert and Maier (2012) tested their retrieval for different meteorological conditions such as inversions, front passages, cold or warm extremes cases and they found different results depending on the weather conditions: in particular, their retrieval showed less skill for inversion cases. How-
10 ever, they made no distinction in their training radiosonde data pool. Constraining the training-testing statistics to certain more homogeneous subsets (i.e., sub-sets containing profiles of similar characteristics) may be expected to provide better statistics and to be beneficial to the performance of the retrieval algorithm. We will test the specialized retrievals for (1) seasons, (2) daytime and nighttime. December, January, February and
15 March are thereby considered “winter months” and June, July, August and September “summer months”. October through March are considered “cold months” and the remaining ones “warm months”. All the radiosonde launches performed between sunrise and sunset are considered daytime launches and vice-versa.

3 Instrumentation

20 3.1 The profiling radiometer RPG-HATPRO

The RPG-HATPRO is a ground-based passive microwave radiometer, which operates in two frequency bands (Rose et al., 2005). It has 7 channels on the upper wing of the 22 GHz water vapour absorption line and 7 channels at the 60 GHz oxygen absorption complex: the line around 22 GHz is used to retrieve humidity information; the second one, allows retrieving temperature profiles. HATPRO measures brightness tem-

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peratures with a resolution of up to 1 s. It has two operation modes: zenith pointing (Z mode) and elevation scanning mode (S mode). In the Z mode the radiometer points vertically, while in the S mode it scans the atmosphere under elevation angles between about 4 and 90°. By the assumption of horizontal homogeneity of the atmosphere, the received radiation for optically thick channels originates from lower atmospheric layers if the elevation angle is reduced. The scanning mode is used only for temperature retrieval, because in the water vapour band the optical thickness of the atmosphere is too low.

Since the detected intensities have to be transferred to brightness temperatures, the radiometer needs to be well calibrated. The absolute calibration consists in scanning blackbody targets whose radiometric temperature is considered to be equal to the physical one. Automatic calibration includes the calibration of the receiver gain. The overall brightness temperature accuracy reported by the manufacturer for the RPG-HATPRO, accounting for the receiver noise, receiver drifts and accuracy of calibrations, is 0.5 K. A complete description of the calibration is given in Rose et al. (2005).

3.2 Experimental set-up

The RPG-HATPRO radiometer is installed on the roof of the Institute for Meteorology and Geophysics (IMGI), University of Innsbruck, at an altitude of 612 m.a.s.l. and has been operational since 1 September 2012. It is programmed to operate in both zenith (Z) and scanning (S) modes. Therefore it is oriented to scan along the Inn Valley axis towards Northeast (60° N). The radiometer performs a scanning in both Z and S modes every 5 min. The time repetition between the measurement modes (TP-BL repetition) and the integration times are shown in Table 4.

Austro Control, the Austrian Air Navigation Service, performs a radio-sounding at Innsbruck airport every night at about 02:00 UTC. The launch site is located at a distance of about 3 km from the IMGI at an altitude of 577 m.a.s.l. The comparison between current sounding and retrieved profiles is performed after a quality check of both HATPRO and radiosonde data and after deleting the days with rain flag switched on

(cf. following subsection). Radiosonde measurements have an accuracy (2-sigma confidence level) of 0.5 °C for the temperature and 5 % for the relative humidity (Vaisala, 2013).

As the radiosonde launches are performed each night at about 02:00 UTC, the HAT-

5 PRO profile closest in time is taken for comparison. The radiosonde data are available at a temporal resolution of 2 s, corresponding to a mean height of 8–10 m. These data are interpolated to the HATPRO grid (Table 1) for further analysis. The different heights of the airport and the roof of IMGI (+35 m) are taken into account, as the temperature may change significantly over this height range.

10 3.2.1 Data quality check

For the radiosonde data the following checks (physical consistency) are performed:

- pressure within the 1 Pa–1050 hPa range and decreasing with height;
- temperature within the 210–330 K range;
- surface pressure larger than 500 hPa.

15 For the brightness temperatures from the radiometer the following conditions are checked:

- rain flag (any amount of rain measured) not activated;
- brightness temperature in the 2.7–330 K range;
- visual inspection to exclude spikes, caused by radio frequency interferences or other disturbances (e.g. aircraft, birds, . . .).

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4 Results

4.1 Scanning vs. zenith

In order to give a first impression of the performance we present a temperature profile comparison between radiosonde and microwave radiometer profiles using the original RPG-algorithm with both scanning and zenith modes (Fig. 2). This is a case with a deep near surface temperature inversion throughout the first 1000 m above ground. The scanning mode gives a better shape of the temperature profile than the zenith mode. This is in agreement with the fact that the scanning mode yields more information about the lower atmospheric layers. For the upper atmosphere the accuracy of the temperature profiles with the two modes is generally similar (not shown), also in agreement with the findings by Crewell and Löhner (2007).

4.2 Evaluation of improved retrieval algorithms

As explained in Sect. 2.3, the IMGI algorithm (cf. Table 3) is obtained using more robust statistics by using more and better resolved radiosonde data. Both IMGI and RPG algorithms are now applied to the full microwave radiometer dataset (September 2012–May 2013). During this time, 84 radiosondes were launched and passed quality control. Figure 3 shows the mean RMSE computed between retrieved temperature and humidity profiles and radiosondes for this dataset. The profiles retrieved by the newly developed IMGI algorithm show an overall improvement at all levels with respect to the RPG algorithm. The error of temperature profiles retrieved with the IMGI algorithm (Fig. 3), are considerably reduced compared to RPG algorithm in nearly all atmospheric layers. The largest improvement can be found in the upper troposphere, but also within the lowest 1000 m the errors are smaller, thus advantageous for studying the boundary layer structure.

More specifically, the RMSE for temperature with the IMGI algorithm is between 0.3 and 0.7 K below 500 m above ground, within 0.9 K in the layer between 500 and 1200 m,

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it increases to 1.5 K at 4000 m and stays within 3.5 K at 10 000 m. Our results compare well and are even slightly better than those of previously published studies. One of the most recent and statistically most robust results of temperature profiles retrieved by ground-based radiometry is from Löhner and Maier (2012). They used observations from the same type of radiometer at the aerological station of Payerne at 456 m a.s.l. (MeteoSwiss) and compared their profiles with collocated radiosonde data. They found a RMSE between retrieved profiles and radiosonde data, between 0.4 and 0.8 K in the lowest 500 m, within 1.2 K at 1200 m and around 1.7 K at 4000 m above ground.

This improved performance is very encouraging given that our radiometer is operated in much more complex terrain and the fact that Löhner and Maier (2012) used a significantly larger radiosonde dataset (of about 12 000 high resolution radiosondes during both daytime and nighttime) for their retrieval, providing a more robust diurnal cycle but also more robust statistics in general than we have at our disposal. Therefore, the use of HATPRO for continuous monitoring of the valley atmosphere is very promising.

The IMGI algorithm also outperforms RPG algorithm for humidity profiles (Fig. 4). The improvement is observed throughout the full troposphere and it is especially pronounced in the lower atmospheric layers. In particular, the RMSE of absolute humidity with the IMGI algorithm is between 0.9 and 0.8 gm^{-3} below 500 m, within 0.7 gm^{-3} at 1200 m, it decreases to 0.4 gm^{-3} at 4000 m and to 0.01 gm^{-3} at the top of the troposphere. Löhner et al. (2009), found a RMSE of absolute humidity around 0.8 gm^{-3} in the lowest 500 m, within 0.7 gm^{-3} at 1200 m and within 0.4 gm^{-3} at 4000 m above ground retrieving the absolute humidity profiles from brightness temperatures that were measured by a HATPRO in Payerne and comparing them with radiosonde data. Taking into account that the results by Löhner et al. (2009) were retrieved using a more sophisticated optimum estimation technique, the obtained results for humidity profiles can be considered very satisfying.

With the knowledge of improved statistical performance, we now evaluate our new IMGI retrieval for a couple of inversion cases. Figure 5 shows the same case of a deep

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nighttime inversion as in Fig. 2, but for the retrieved temperature profiles with the RPG and IMGI algorithms. Both algorithms capture the inversion, but the IMGI reproduces the temperature gradient slightly better; in the medium to high troposphere the better performance of the IMGI algorithm is evident. Figure 6 shows a night with a very strong elevated temperature inversion around 1500 m above ground. Both the RPG and the IMGI algorithms reproduce it only roughly. This type of inversion case is nearly impossible to be retrieved by radiometers when only ground-based measurements are available. Similar underperformance has already been shown by Löhner and Maier (2012) using the same instrument and by Knupp et al. (2009), operating a similar profiling radiometer (manufactured by Radiometrics Corporation). This is likely due to the low occurrence of these kind of situations in the radiosonde climatology as well as the height of the inversion, which is higher than the atmospheric layers that benefit from the scanning mode, hence the radiometer information is not sufficient to resolve it.

An example of a retrieved nighttime humidity profiles is shown in Fig. 7. Only the mean shape of the actual humidity profile is reproduced by both retrievals, but for the present example the IMGI algorithm yields a slightly better overall accuracy. This is related to the transparency of the atmosphere in the K-band and in accordance with the findings by Liljegren et al. (2001) and Ware et al. (2003), using similar passive microwave radiometers. The lower information on the vertical humidity distribution is caused by the lower information content for water vapour than for temperature observations; for humidity profiles there are 1–2 independent degrees of freedom, whereas for temperature profiles the scanning measurement contains 4 independent pieces of information (Löhner et al., 2009).

4.3 Impact of targeted training data sets

Further improvement to the retrieved profiles was expected by performing separate retrieval development for targeted data sets, for example seasonal or time-of-day subsets (see Sect. 2.3.1). Unfortunately, the number of available daytime radiosonde launches is very small (only 134) hence the statistical analysis is biased towards the nighttime

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cases. In order to develop robust statistics for daytime cases, ten different independent random choices were performed for this subset. The results are displayed in Fig. 8. The nighttime retrieval (N) roughly follows the behaviour of the general IMGI retrieval (All), according to the fact that the number of nighttime radiosonde measurements is predominant. Daytime (D), winter (W) and winter nighttime (WN) retrievals have worse RMSE than IMGI retrieval (difference larger than 0.1 K). On the other hand, retrieval algorithms based on the summer (S) or summer nighttime (SN) appear to give better results (difference in RMSE larger than 0.1 K). The results for cold and warm months' retrievals are equivalent to those of winter and summer respectively and are therefore not shown in Fig. 8. The results for the daytime retrieval are not very conclusive due to the small number of samples.

The statistics for summer and winter retrievals are quite robust (more than 1000 profiles). However, in winter (or in the cold months) it seems to be more difficult to retrieve the temperature profile. The differences between summer and winter can be partly explained by more frequent elevated and multiple inversions in winter. Moreover, in mid-tropospheric levels, the natural atmospheric variability is lower in summer, resulting in a smaller climatic RMSE.

Concerning the diurnal cycle the daytime boundary layer is often characterised by an elevated inversion (entrainment layer during thermally dominated situations); on the other hand for dynamically dominated situations often no inversions are present. Therefore, apparently “daytime” is a criterion that is not sufficiently unique to benefit from a specialized retrieval.

The results show that with careful selection of climatic subsets, the resulting profile algorithms can yield better results. However, for transition periods between different seasons or day/night a combined algorithm would be required in order to continuously monitor atmospheric profiles.

Apparently, summer profiles are overall more similar among themselves than the winter profiles. Likely due to the abundance of night-time profiles in the present data set, the summer profiles have no or only surface inversions, whereas the group of winter

profiles possesses many cases of elevated or even multiple inversions. The fact that there are largely improved results for the S and SN specialized retrievals, in principle suggests that a better selection of the training profiles can yield better results. However, only if physically meaningful specialisations are chosen – and if these groups have a sufficiently large database – the targeted specialized retrievals can be beneficial.

4.4 Additional regressors

Another potential method for improving the accuracy of the retrieval is including additional regressors into the algorithm development (Eq. 2), like the pressure or temperature at the height of the radiometer. These data have been shown to improve the 10 temperature and humidity retrievals in the lower atmosphere (Del Frate and Schiavon, 1998). Alternatively, in mountainous regions, such as the Inn Valley, it is possible to include pressure and temperature measurements from meteorological stations on the surrounding mountains. One such example is a weather station at Patscherkofel Mountain in the vicinity of Innsbruck, at about 1600 m above the valley floor, and at only 8 km 15 horizontal distance from the microwave radiometer location. More generally, in such a terrain the temperature at specific altitudes can be routinely available.

As a proof of concept, we test two new retrievals. The first one uses the temperature at 1600 m above ground as the additional information and the second retrieval uses “a slope profile”, i.e. temperatures at 400, 800, 1200, 1600 m (above ground) as 20 additional regressors. Note that these temperatures (regressors) are here obtained from the soundings and not from actual surface measurements at these altitudes. Figure 9 shows the RMSE comparison between the retrievals with additional regressors and the IMGI retrieval without them. It is apparent that the accuracy of temperatures at the heights close to those of additional regressors is significantly improved (the RMSE is about 0.1 K). The beneficial effect of these additional regressors is most pronounced 25 within a zone of several hundred meters around the height of the additional temperatures themselves. Still, the overall RMSE is improved also until the mid-troposphere, especially for 4 additional regressors constraining the retrieved profile. Therefore, the

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disadvantage of operating the radiometer in mountainous terrain, with frequent higher-level inversions that are challenging for standard radiometer retrievals, can potentially be turned into a benefit and the resolution of the radiometer profile in the lower troposphere might be improved in a mountainous region where additional surface measurements from different altitudes (e.g., along a nearby slope or from mountain peaks) are available.

The potential of such an approach becomes clear when considering an example with a pronounced elevated inversion, which both the RPG and IMGI retrievals were unable to resolve properly. Figure 10 shows the same case as Fig. 6 but for the IMGI retrieval and the new retrieval with 4 additional regressors. The retrieval algorithm with the information from elevated levels included provides a significantly better representation of the inversion than the non-specialized (IMGI) algorithm, both in terms of inversion height and temperature gradient. Naturally, the improvement is largest at levels where the additional information comes from. It remains to be tested to what degree actual surface data from stations at different altitudes, i.e. independent data, can reproduce this result. It will also be interesting to find out up to which horizontal distance from a profiler location, a mountaintop measurement site would have a beneficial impact on the retrieval algorithm.

5 Conclusions and outlook

Within the i-Box Project a RPG-HATPRO microwave radiometer was operated for one of the first times during a prolonged period in an alpine valley, i.e. in truly complex terrain. Although the atmospheric boundary layer is not homogeneous in this terrain, the radiometer allows obtaining continuous temperature and humidity profiles with acceptable accuracy. These profiles can be used for studying boundary layer processes in complex mountainous terrain. Observations show that by using the elevation scanning mode more accurate temperature profiles can be retrieved in the lowest 1200 m above

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ground, as already reported by Crewell and Löhnert (2007). Furthermore, we could show that we were able to improve the retrieval algorithm still further.

First, temperature and humidity profiles retrieved by the algorithm provided by the manufacturer (RPG algorithm) and an improved retrieval (IMGI algorithm), based on more robust statistics, have been compared for simultaneous nighttime radiosondes. The more robust statistics consists of a larger radiosonde dataset, using their full vertical resolution, finding the best noise level and determining for the best regression type (linear or quadratic). Considering 84 nights between September 2012 and May 2013 where radiosonde data are available, both for temperature and absolute humidity the IMGI algorithm gives improved results. It can be concluded that the set of training data, i.e., the local climatology, is essential for obtaining accurate profiles. Specifically, the accuracy of the retrieved temperature profile with the IMGI retrieval is comparable to those obtained from other radiometers operated in less complex terrain (Löhnert and Maier, 2012; Löhnert et al., 2007) and at certain height ranges even better. It is thus shown that with the availability of a local, long term, high-resolution training data-set a microwave radiometer can be operated even in truly complex terrain.

On the other hand, neither the RPG nor the improved retrieval algorithms are able to accurately capture elevated temperature inversions at the level of the valley crest (typically above 1200 m in the present environment). It is known that these cases pose significant challenge to radiometry (Crewell and Löhnert, 2007). The most promising approach in complex mountainous terrain would be to include additional regressors from mountain stations into the retrieval. Our results show that the accuracy of the retrieved temperatures improves considerably at heights around those of additional regressors (despite the fact that the information on the height of those regressors is not included in the retrieval). Also and perhaps more importantly, the retrieval algorithm with these additional regressors is able to resolve an elevated inversion to an unprecedented degree.

Where information from higher levels (e.g. mountain stations) are not available, a better accuracy for temperature profiles can be obtained by training based on subsets of

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data with similar characteristics thus allowing for a specialized retrieval for specific conditions. Our results for different seasons, nighttime – daytime show some improvements. However, the fact that there are better results for some classification subsets and worse for others, suggests that targeted specialized retrievals based on classification of profiles according to their similar physical characteristics could give improved

- 5 results. For this purpose, a more in-depth study of the typical profiles in the environment where the profiler is used would be required, as well as an appropriate method for classifying them. These however are out of the scope of this paper. Other types of training, such as artificial neural network might be tested as well for this purpose.
- 10 A powerful method of classification of the profiles could be in terms of their atmospheric stability.

Finally, when considering humidity profiles, details within the boundary layer cannot be resolved precisely, due to the limited information content of HATPRO observations. In order to obtain a better accuracy of retrieved humidity, it is likely necessary to use 15 additional frequencies (e.g. 183 GHz) where the water vapour absorption is higher or to operate the radiometer in synergy with other remote sensing instruments (Raman LIDAR etc.). Also, humidity observations on slopes or mountaintops could act as additional regressors like we presented for temperature profiles.

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Table 1. Heights grid of the temperature/humidity profile retrieval, expressed in meters over the instrument.

Heights grid of profiles retrieved from RPG-HATPRO [m – over the instrument]

0, 10, 30, 50, 75, 100, 125, 150, 200, 250, 325, 400, 475, 550, 625, 700, 800, 900, 1000, 1150, 1300, 1450, 1600, 1800, 2000, 2200, 2500, 2800, 3100, 3500, 3900, 4400, 5000, 5600, 6200, 7000, 8000, 9000, 10000

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Table 2. Main characteristics of the built-in retrieval (RPG algorithm). “Ibk” stands for the operational radiosonde at the airport of Innsbruck. “Degree” refers to the order of the employed regression (see Eq. 2).

RPG retrieval algorithm	Training data	Degree	Surface sensor	Noise level [K]
	Radiosonde Ibk (~ 3000) 1999–2005, 2009–2012 low vertical resolution nighttime	2	pressure	0.35

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Table 3. Main characteristics of the improved retrieval (IMGI algorithm) for temperature (T) and absolute humidity (a). “Ibk” stands for the operational radiosonde at the airport of Innsbruck. “Degree” refers to the order of the employed regression (see Eq. 2).

IMGI retrieval algorithm	Training data	Degree	Surface sensor	Noise level [K]
	Radiosonde Ibk (3157)	T : 2	T : –	T : 0.20
	1999–2005, 2009–2012	a : 2	a : pressure	a : 0.35
	resolution 2 s/10 s			
	night and daytime			

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Table 4. Set-up for the time repetition and time integration of our RPG-HATPRO. TP-BL repetition indicates the time between two successive scanning measurements. The measured brightness temperature is integrated over a certain time interval (level 1) and the retrieved profiles are then averaged (level 2).

TP-BL repetition	300 s
Level 1: Time integration brightness temperature	Z mode: 1 s S mode: 150 s
Level 2: Time integration retrieved profiles	Z mode: 60 s S mode: 150 s

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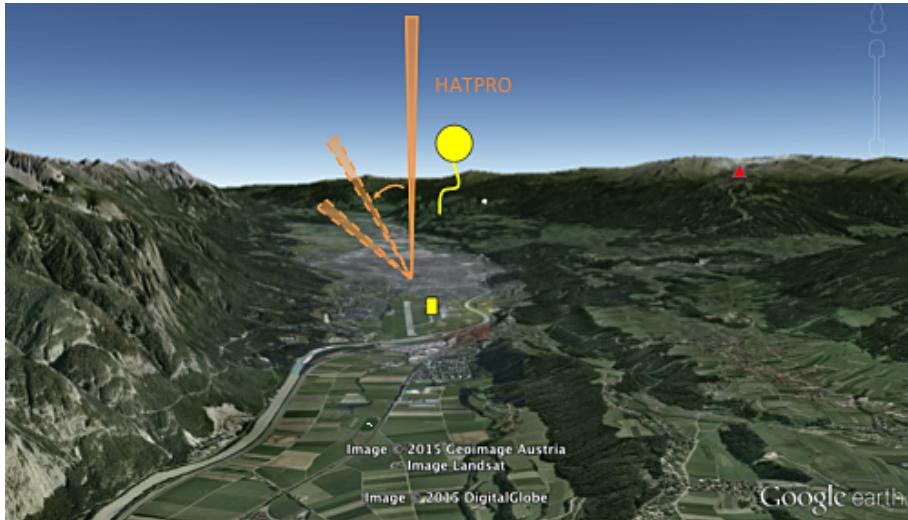


Figure 1. View from the west to the city of Innsbruck. In the foreground the airport is visible where the radio soundings are launched and the approximate position of the HATPRO on the roof of the University building with the scanning direction towards the east is indicated. The red triangle denotes the Patscherkofl mountain-top station.

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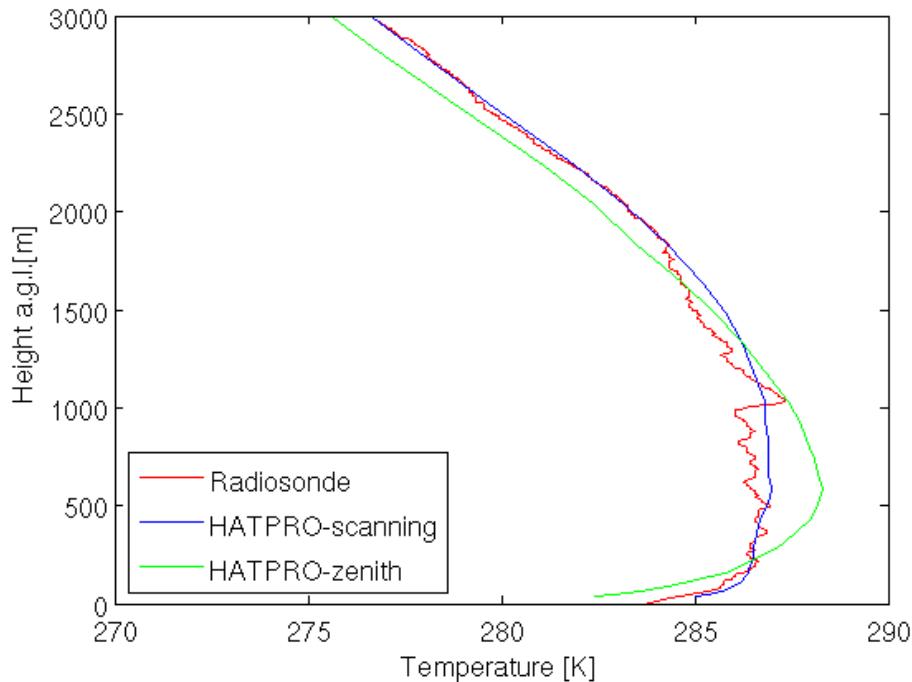


Figure 2. Temperature vertical profile for the lower part of the troposphere. The comparison is between (differently coloured lines, see inlet) radiosonde and measurements of the radiometer by the RPG-algorithm with the scanning and zenith mode. Data from 9 September 2012, at 01:58 UTC (launch time of the radiosonde). The height is expressed in meters above ground.

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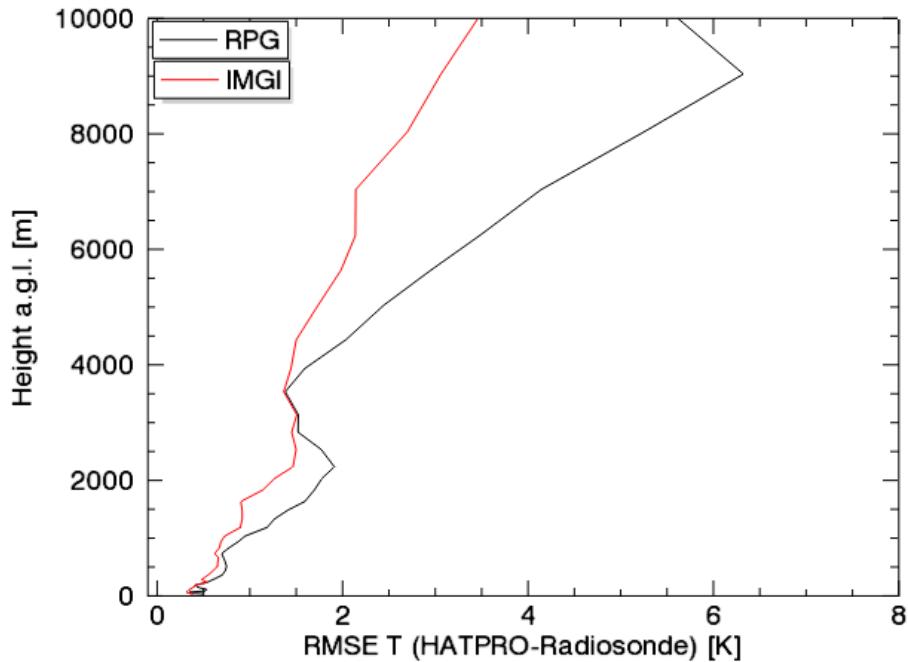


Figure 3. Comparison between RPG and IMGI algorithms for temperature profiles within the full troposphere. The RMSE is between temperature retrieved from the two algorithms and radiosonde in function of height (above ground). The 84 days refer to the time period from September 2012 to May 2013 and are all during the night. The radiosonde measurements are from the airport of Innsbruck and the profiler is located on the roof of IMGI.

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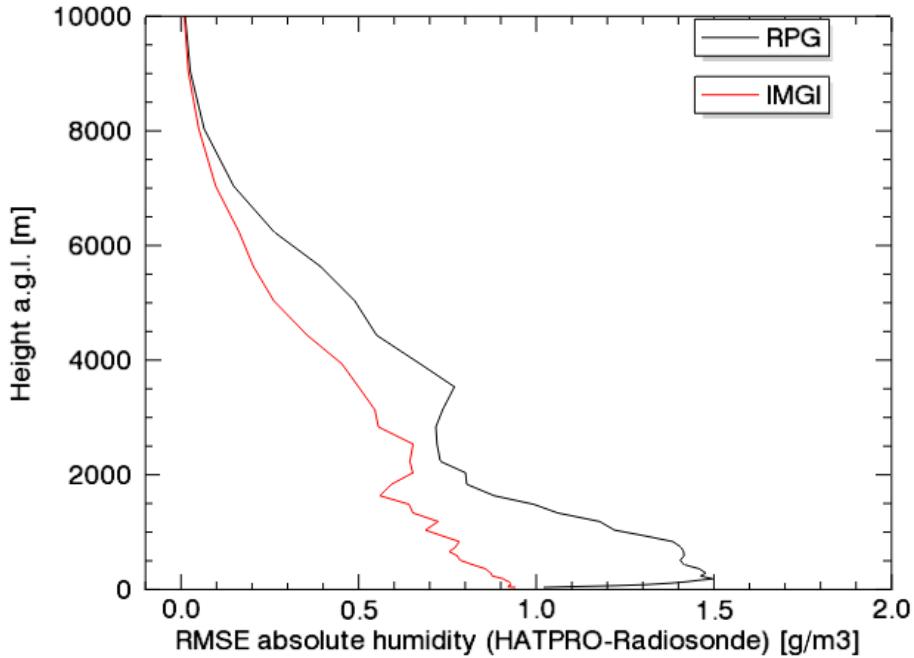


Figure 4. Same as Fig. 3, but for absolute humidity.

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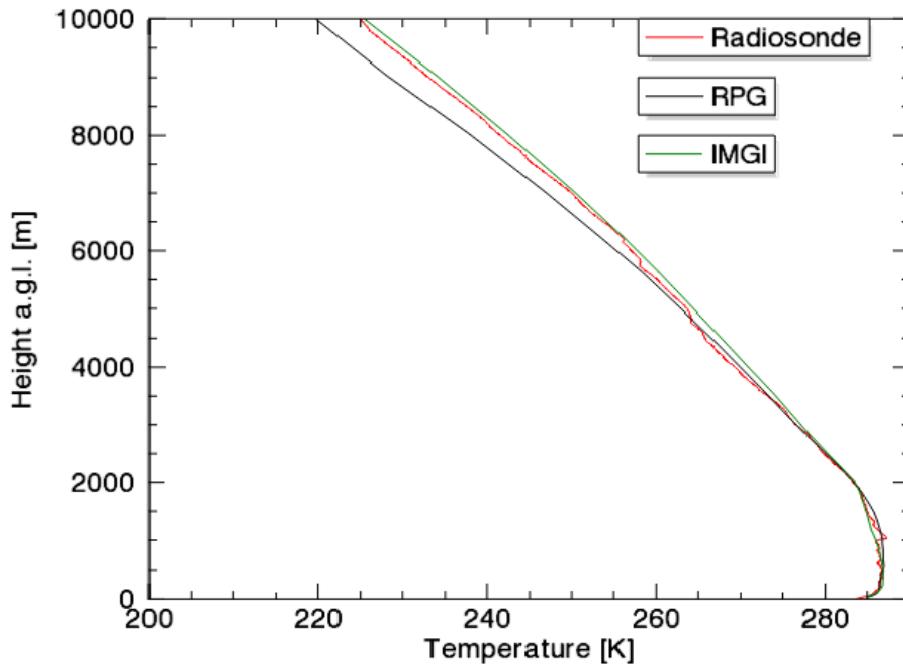


Figure 5. Temperature profile within the full troposphere. The comparison is between (differently coloured lines, see inlet) radiosonde, RPG algorithm, IMGI algorithm. They refer to 9 September 2012, at 01:58 UTC (launch time of the radiosonde). The height is expressed in meters above ground.

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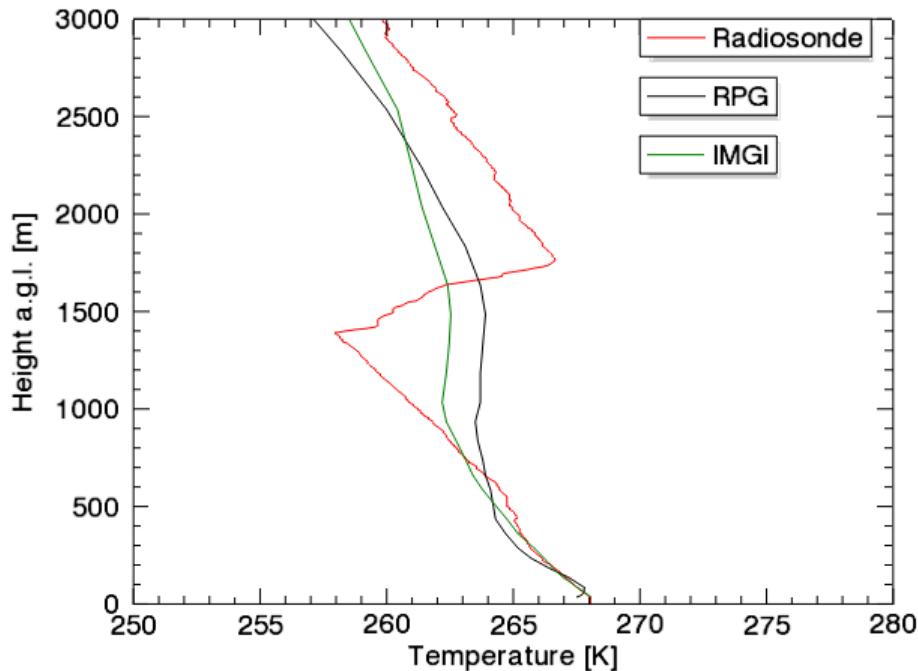


Figure 6. Temperature vertical profile for the lower part of the troposphere. The comparison is between (differently coloured lines, see inlet) radiosonde, RPG algorithm, IMGI algorithm. They refer to 14 February 2013, at 03:18 UTC (launch time of the radiosonde). The height is expressed in meters above ground.

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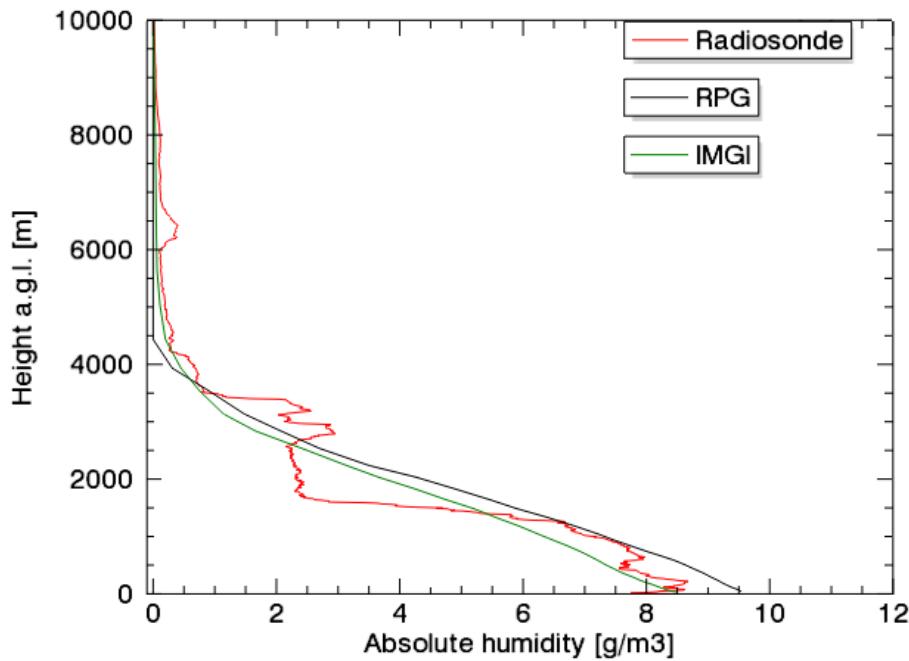


Figure 7. Humidity vertical profile within the full troposphere. The comparison is between (differently coloured lines, see inlet) radiosonde, RPG algorithm, IMGI algorithm. They refer to 3 October 2012, at 02:02 UTC (launch time of the radiosonde). The height is expressed in meters above ground.

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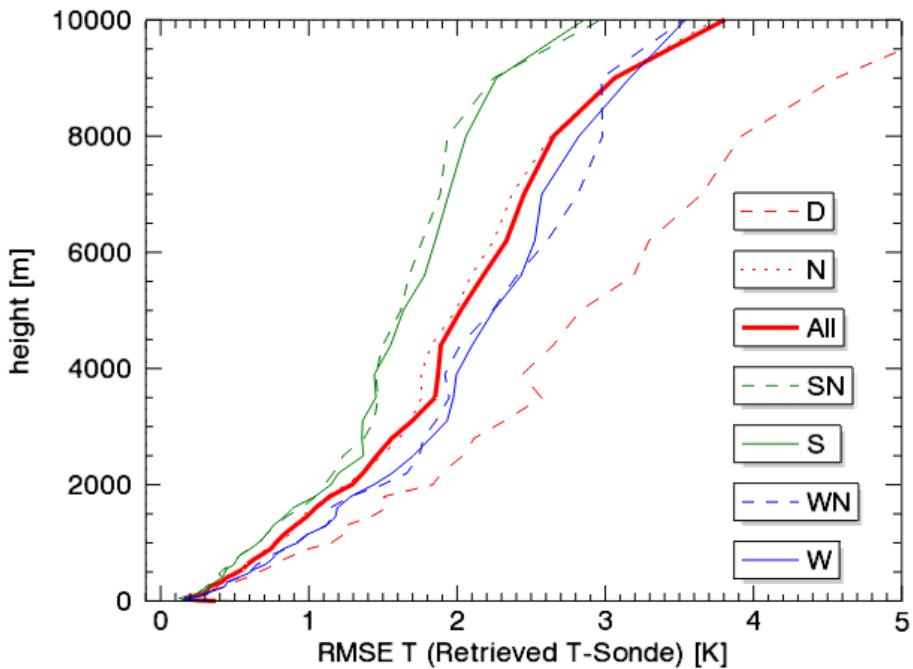


Figure 8. Effect of a specialized training considering time of year or time of day. RMSE between IMGI retrieved temperature and radiosonde in function of height (above the radiometer) for the full troposphere. D: daytime radiosonde (134); N: nighttime (3023); All: overall set of radiosonde (3157); SN: summer nighttime (984); S: summer (1028); WN: winter nighttime (990); W: winter (1026).

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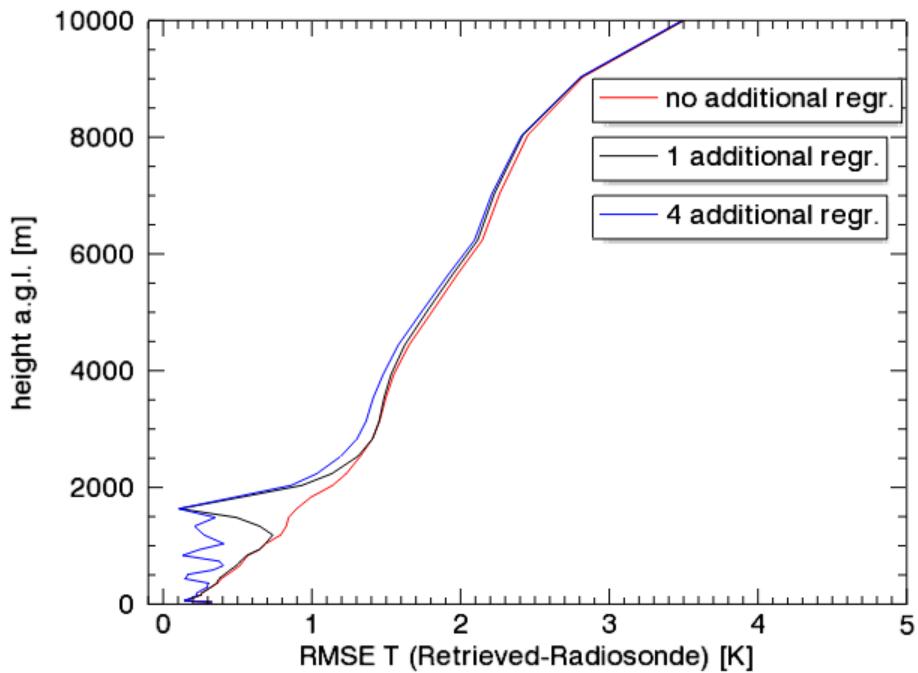


Figure 9. Comparison between a retrieval based only on the brightness temperatures (called “no additional regr.”), a retrieval with the temperature at 1600 m (called “1 additional regr.”) and a retrieval with the temperature at several heights (400, 800, 1200, 1600 m) as further regressors (called “4 additional regr.”). The RMSE is between retrieved temperature and radiosonde in function of height (above ground).

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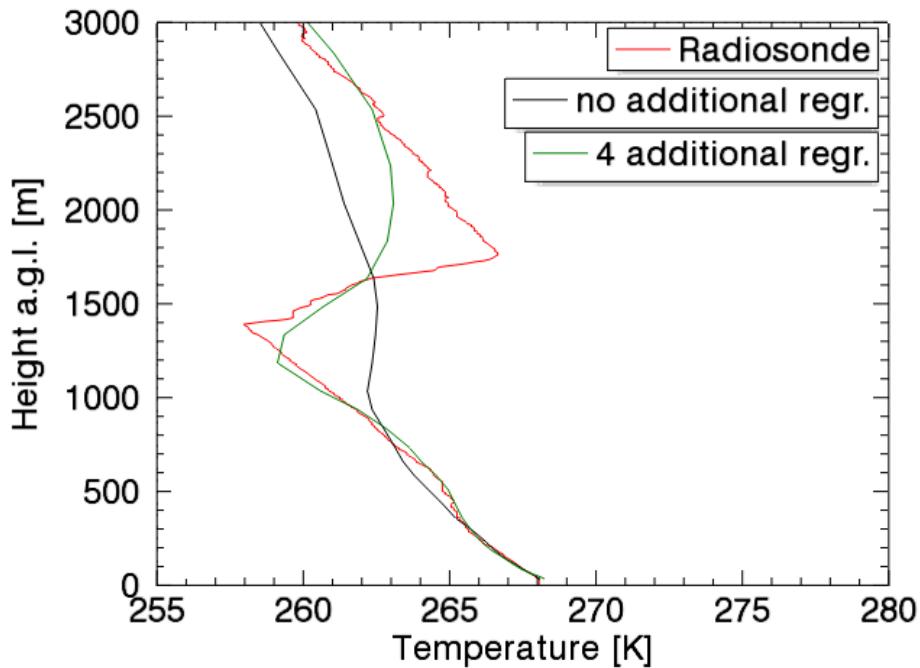


Figure 10. The effect of additional regressors for a real case, that refers to 14 February 2013, at 03:18 UTC (launch time of the radiosonde). The comparison is between the radiosonde profile, a retrieval based only on the brightness temperatures (called “no additional regr.”, corresponding to the IMGI algorithm) and a retrieval with the temperature at several heights (400, 800, 1200, 1600 m) as further regressors (called “4 additional regr.”). The height is above ground.