

The MUSICA
MetOp/IASI H₂O and
δD products

A. Wiegele et al.

The MUSICA MetOp/IASI H₂O and δD products: characterisation and long-term comparison to NDACC/FTIR data

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Title Page

Abstract

Introduction

Conclusions

References

Tables

Figures

◀

▶

◀

▶

Back

Close

Full Screen / Esc

Printer-friendly Version

Interactive Discussion



Abstract

Within the project MUSICA (Multi-platform remote Sensing of Isotopologues for investigating the Cycle of Atmospheric water) ground- and space-based remote sensing as well as in-situ datasets of tropospheric water vapour isotopologues are provided. The space-based remote-sensing dataset is produced from spectra measured by the IASI (Infrared Atmospheric Sounding Interferometer) sensor and is potentially available on a global scale.

Here, we present the MUSICA IASI data for three different geophysical locations (subtropics, mid-latitudes, and arctic) and we provide a comprehensive characterisation of the complex nature of such space-based isotopologue remote sensing products. The quality assessment study is complemented by a comparison to MUSICA's ground-based FTIR (Fourier-Transform InfraRed) remote sensing data retrieved from the spectra recorded at three different locations within the framework of NDACC (Network for the Detection of Atmospheric Composition Change).

We confirm that IASI is able to measure tropospheric H₂O profiles with a vertical resolution of about 4 km and a random error of about 10%. In addition IASI can observe middle tropospheric δ D that adds complementary value to IASI's middle tropospheric H₂O observations. Our study is both, a theoretical and an empirical proof that IASI has the capability for a global observation of middle tropospheric water vapour isotopologues on a daily timescale and at a quality that is sufficiently high for water cycle research purposes.

1 Introduction

The water cycle is one of the most important cycles in geoscience. Its atmospheric part is affected by evaporation, transport, and condensation and strongly interacts with fundamental thermodynamic processes such as energy transport and radiation. But different effects on the energy budget are still not cleared such as rainfall evaporation (e.g.

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The MUSICA MetOp/IASI H₂O and δ D products

A. Wiegeler et al.

Title Page

Abstract

Introduction

Conclusions

References

Tables

Figures

◀

▶

◀

▶

Back

Close

Full Screen / Esc

Printer-friendly Version

Interactive Discussion



The MUSICA MetOp/IASI H₂O and δD products

A. Wiegele et al.

Title Page

Abstract

Introduction

Conclusions

References

Tables

Figures

◀

▶

◀

▶

Back

Close

Full Screen / Esc

Printer-friendly Version

Interactive Discussion



Worden et al., 2007) or radiative impacts depending on the present water phase (e.g., Trenberth et al., 2009). Thus, additional knowledge about the water cycle would allow improved weather forecasts as well as more precise climate predictions. Hereby, water vapor isotopologues may give detailed insight into the different processes since the partitioning of the different isotopologues depends on the underlying process (equilibrium condensation or Rayleigh process, ice lofting, mixing of dry and humid air masses, rain evaporation, plant transpiration, etc.). In this paper combined measurements of H₂¹⁶O and HD¹⁶O are used (in the following referred to as H₂O and HDO). The enrichment of the heavier isotopologue HDO compared to the main isotopologue H₂O is called δD and calculated as deviation of the ratio of both isotopologues compared to the Vienna standard mean ratio in ocean water (VSMOW).

$$\delta D = 1000\text{‰} \times \left(\frac{\text{HDO}/\text{H}_2\text{O}}{\text{VSMOW}} - 1 \right) \quad (1)$$

More than 50 years ago Craig (1961) reported about the measurements of water isotopologues by mass spectrometry in collected liquid water samples from all around the globe. First atmospheric in-situ profiling of water isotopologues in the gas phase has been performed by Ehhalt et al. in the 1970s (a review is given in Ehhalt et al., 2005). Afterwards a few dedicated aircraft campaigns have taken place (e.g., Zahn, 2001; Webster and Heymsfield, 2003) using different in situ instruments. In recent years there has been large progress in remote sensing observations of water vapor isotopologues. In the meanwhile ground-based FTIR instruments (Schneider et al., 2006, 2012) are used for measuring δD in the lower and middle troposphere. Furthermore, there are space-borne scientific sensors that measure middle tropospheric δD (Worden et al., 2007) and δD at and above the upper troposphere and lower stratosphere (e.g. Steinwagner et al., 2007; Payne et al., 2007; Lossow et al., 2011). Most recently, middle tropospheric δD products applying the operational meteorological satellite sensor IASI (Infrared Atmospheric Sounding Interferometer) have been presented by Schneider and Hase (2011), Lacour et al. (2012), and Pommier et al. (2013).

The MUSICA MetOp/IASI H₂O and δ D products

A. Wiegele et al.

Title Page

Abstract

Introduction

Conclusions

References

Tables

Figures

◀

▶

◀

▶

Back

Close

Full Screen / Esc

Printer-friendly Version

Interactive Discussion



These remote sensing observations are very interesting since they can give a global view on the atmospheric water vapour isotopologues thus promising unprecedented opportunities for water cycle research on a global scale. However, the remote sensing of trace gas ratios like δ D, is no trivial task. The trace gas ratio product has rather complex characteristics and it is important to be aware of these complexities, to understand, and to comprehensively describe them, otherwise its scientific value will be limited.

Such quality assessment is a main objective of the project MUSICA (MULTi-platform remote Sensing of Isotopologues for investigating the Cycle of Atmospheric water, www.imk-asf.kit.edu/english/musica). Schneider et al. (2012) presents an extensive theoretical characterisation of the MUSICA ground-based FTIR remote sensing dataset.

In this paper we give a brief overview of MUSICA's NDACC/FTIR and METOP/IASI products and the applied retrieval strategies (Sect. 2). In Sect. 3 we use the formalism as presented for the NDACC/FTIR dataset by Schneider et al. (2012) for characterising MUSICA's METOP/IASI products. Then, the IASI and the FTIR products are compared in Sect. 4. This is done for three rather different locations: for a subtropical, a mid-latitude, and a polar site. Section 5 resumes the study.

2 Remote sensing of water isotopologues

In the real atmosphere H₂O and HDO vary mostly in parallel: compared to the large variability of tropospheric H₂O and HDO concentrations, the ratio between the HDO and H₂O concentrations remains relatively stable. This is the dominating characteristics of atmospheric water vapour isotopologues and it has to be accounted for when setting up a remote sensing retrieval.

We use the same code (PROFFIT, Hase et al., 2004) for MUSICA's NDACC/FTIR and METOP/IASI remote sensing retrievals. Thereby we want to ensure that the respective ground- and space-based data products are as consistent as possible. The

code has been developed and successfully used for the inversion of ground-based absorption spectra as well as thermal nadir spectra (e.g., Schneider and Hase, 2011). The retrievals are performed in logarithmic scale and with an interconstraint between both water vapor isotopologues. This strategy enables us to account for the dominating characteristics of the atmospheric water vapour isotopologue state.

2.1 The {humidity, δD }-proxy state and water vapour isotopologue covariances

The state $\{(\ln[H_2O] + \ln[HDO])/2\}$ captures the large variations that are common to H_2O and HDO, it is a good proxy for H_2O variations, and we refer to it in the following as the {humidity}-proxy state. The state $\{\ln[HDO] - \ln[H_2O]\}$ describes the relatively small variations in the HDO/ H_2O ratio, it is a good proxy for δD variations, and we refer to it in the following as the $\{\delta D\}$ -proxy state. The transformation between the $\{\ln[H_2O], \ln[HDO]\}$ -state (x) and the {humidity, δD }-proxy state (x') can be realised by a transformation matrix \mathbf{P} :

$$x' = \mathbf{P}x = \begin{pmatrix} 1 & 1 \\ 2 & -1 \\ \parallel & \parallel \end{pmatrix} x. \quad (2)$$

Here \parallel is $n \times n$ unity matrix (n is the number of atmospheric grid levels).

This transformation is very useful for defining a correct a priori covariance matrix and thus for setting up the correct constraints for the atmospheric water vapour isotopologue retrievals. For this purpose, we define a matrix \mathbf{S}_{aH} , describing the covariances that are common to H_2O and HDO, i.e., the covariances for the {humidity}-proxy state. Similarly, we define a matrix \mathbf{S}_{aI} for the $\{\delta D\}$ -proxy state covariances. These two covariances describe the dominating characteristics of the atmospheric water vapour isotopologue variations.

However, our remote sensing retrievals works in the $\{\ln[H_2O], \ln[HDO]\}$ -state and for setting up an adequate optimal estimation constraint we need to define the a priori covariances for the $\{\ln[H_2O], \ln[HDO]\}$ -state. These covariances (represented by \mathbf{S}_a) can be easily calculated from the covariances for the {humidity, δD }-proxy state

The MUSICA MetOp/IASI H_2O and δD products

A. Wiegeler et al.

Title Page

Abstract

Introduction

Conclusions

References

Tables

Figures

◀

▶

◀

▶

Back

Close

Full Screen / Esc

Printer-friendly Version

Interactive Discussion



(represented by matrix \mathbf{S}'_a) by means of the transformation matrix \mathbf{P} :

$$\mathbf{S}_a = \mathbf{P}^{-1} \mathbf{S}'_a \mathbf{P}^{-T} = \begin{pmatrix} \parallel -\frac{1}{2} \parallel \\ \parallel \frac{1}{2} \parallel \end{pmatrix} \begin{pmatrix} \mathbf{S}_{aH} & 0 \\ 0 & \mathbf{S}_{aI} \end{pmatrix} \begin{pmatrix} \parallel \parallel \\ -\frac{1}{2} \parallel \parallel \frac{1}{2} \parallel \end{pmatrix} = \begin{pmatrix} \mathbf{S}_{aH} + \frac{1}{4} \mathbf{S}_{aI} & \mathbf{S}_{aH} - \frac{1}{4} \mathbf{S}_{aI} \\ \mathbf{S}_{aH} - \frac{1}{4} \mathbf{S}_{aI} & \mathbf{S}_{aH} + \frac{1}{4} \mathbf{S}_{aI} \end{pmatrix}. \quad (3)$$

For more details please refer to Sect. 3.3 of Schneider et al. (2012), where the {humidity, δD }-proxy state is introduced.

2.2 The MUSICA NDACC/FTIR retrievals

The NDACC (Network for the Detection of Atmospheric Composition Change, <http://www.acd.ucar.edu/irwg/>, Kurylo and Zander, 2000) FTIR spectrometers measure solar absorption spectra in the mid-infrared ($750\text{--}4300\text{ cm}^{-1}$). The very high spectral resolution (typically $0.0036\text{--}0.005\text{ cm}^{-1}$) allows for observing the pressure broadening effect in the absorption signatures. As a consequence, the absorption spectra contain some information on the vertical distribution of the absorbing trace gases. E.g. in case of O_3 , four independent layers between the surface and about 35 km altitude (Barret et al., 2002; García et al., 2012) and in case of H_2O three layers between the surface and the upper troposphere (Schneider et al., 2012) can be resolved.

For the MUSICA water vapour isotopologue retrieval, we work with 11 spectral microwindows between 2650 cm^{-1} and 3020 cm^{-1} (see Fig. 2 of Schneider et al., 2012) as well as four spectral auxiliary microwindows containing CO_2 lines (in order to optimally estimate the temperature from the measured spectra, Schneider and Hase, 2008). We use HITRAN 2008 spectroscopic parameters (Rothman et al., 2009, with 2009 updates), whereby for the water vapour isotopologues we use parameters that have been adjusted for the speed-dependent Voigt line shape (Schneider et al., 2011).

We fit simultaneously the spectral signatures of H_2^{16}O , HD^{16}O , H_2^{18}O , H_2^{17}O , O_3 , N_2O , CH_4 , HCl , and C_2H_6 . For the constraint of the water vapour isotopologue state we construct a priori covariances for humidity and δD (\mathbf{S}_{aH} and \mathbf{S}_{aI} , respectively, see Eq. 3). For humidity, we assume a 1σ variability of 1.0 (on log-scale) and a correlation length

Title Page

Abstract

Introduction

Conclusions

References

Tables

Figures

◀

▶

◀

▶

Back

Close

Full Screen / Esc

Printer-friendly Version

Interactive Discussion



representing mid-latitudes, and to the right Kiruna, representing polar latitudes, respectively.

Figure 1 shows typical kernels for the $\{\ln[\text{H}_2\text{O}]\}$ - and the $\{\ln[\text{HDO}]\}$ -states obtained from the IASI retrievals. As mentioned above, there are three groups of graphs: left group for Izaña, central group for Karlsruhe, and right group for Kiruna. Each group consists of four graphs: the top left and bottom right graphs show how atmospheric $\ln[\text{H}_2\text{O}]$ variations affect the retrieved $\{\ln[\text{H}_2\text{O}]\}$ -state and how atmospheric $\ln[\text{HDO}]$ variations affect the retrieved $\{\ln[\text{HDO}]\}$ -state, respectively. Furthermore, there are large cross dependencies (top right and bottom left graphs) that have to be considered. They show how atmospheric $\ln[\text{HDO}]$ variations affect the retrieved $\{\ln[\text{H}_2\text{O}]\}$ -state and how atmospheric $\ln[\text{H}_2\text{O}]$ variations affect the retrieved $\{\ln[\text{HDO}]\}$ -state. Due to this cross dependencies and due to the fact that H_2O and HDO vary largely in parallel, a straightforward interpretation of Fig. 1 is difficult.

Much better insight is provided by transferring the $\{\ln[\text{H}_2\text{O}], \ln[\text{HDO}]\}$ -state to the {humidity, δD }-proxy state. This proxy state concept enables us to characterise the complex MUSICA METOP/IASI water vapour isotopologue remote sensing data by means of the well-known Rodgers formalism (Rodgers, 2000). This is done in large similarity to the characterisation of the MUSICA NDACC/FTIR product as presented in Schneider et al. (2012), to which we refer to throughout this section as S12. Very recently Pommier et al. (2013) used the S12 formalism for assessing uncertainties in the IASI water isotopologue product as provided by the Université libre de Bruxelles.

In the following we will characterise the two types of the IASI water vapour isotopologue products.

The MUSICA MetOp/IASI H_2O and δD products

A. Wiegeler et al.

Title Page

Abstract

Introduction

Conclusions

References

Tables

Figures

⏪

⏩

◀

▶

Back

Close

Full Screen / Esc

Printer-friendly Version

Interactive Discussion



3.1.2 Propagation of uncertainties

The propagation of uncertainties to the humidity and δD states can be calculated as (see Eq. 13 of S12):

$$\mathbf{S}'_e = \mathbf{PGK}_p \epsilon_p \epsilon_p^T \mathbf{K}_p^T \mathbf{G}^T \mathbf{P}^T, \quad (5)$$

whereby \mathbf{G} is the gain matrix, \mathbf{K}_p the error Jacobian matrix for parameter p and ϵ_p the parameter uncertainty. We calculate the error Jacobians \mathbf{K}_p as follows: we calculate two simulated spectra using a different parameter p . Then we calculate the difference of the simulated spectra and divide it by the difference applied in parameter p .

The assumed uncertainties ϵ_p are listed in Table 2. As measurement noise we assume 5‰ (noise-to-signal ratio), which is in agreement with an IASI radiometric noise value of $2 \times 10^{-2} \mu\text{W}(\text{cm}^2 \text{srcm}^{-1})$ established from a set of representative spectra (Clerbaux et al., 2009, Fig. 2). As further instrumental error we assume a small uncertainty in the observation geometry (0.01° uncertainty in the swath angle).

For the line intensity parameters of the water vapour isotopologues (H_2O and HDO) as well as of the major interfering absorbers CH_4 and N_2O , we assume an uncertainty of 2%. In addition, we consider an uncertainty of the pressure broadening parameters of H_2O and HDO of 1%. These assumptions are in good agreement with the uncertainty values given in the HITRAN line lists (e.g. Rothman et al., 2009).

For emissivity we assume an uncertainty value of 5% (land emissivities are taken from measurements and ocean emissivities from the model of Masuda et al., 1988). In agreement to August et al. (2012), we assume a temperature uncertainty of 2 K for surface temperature and the temperature in the lowermost tropopause (0–2 km) and of 1 K above, whereby we suppose that the uncertainties at ground and at different atmospheric layers are uncorrelated.

For complex terrain, IASI's ground pixel might cover an area with varying ground altitude. This is considered in our error assessment by assuming an uncertainty in ground altitude of 20 m. In addition, the IASI pixels can be affected by unidentified

The MUSICA MetOp/IASI H_2O and δD products

A. Wiegeler et al.

Title Page

Abstract

Introduction

Conclusions

References

Tables

Figures

◀

▶

◀

▶

Back

Close

Full Screen / Esc

Printer-friendly Version

Interactive Discussion



clouds. This might be low optically thick clouds that only partly cover the IASI pixel (we assume a 5 % coverage) or elevated but optically thin clouds that cover the whole IASI pixel (we assume a cloud with 98 % transmittance).

Figure 3 shows how these uncertainties propagate into the product type 1 humidity profiles. Depicted are the square root values of the diagonal of the error covariance matrix S'_e . The calculations are performed for the three different sites individually (from the left to the right: for pixels measured over the subtropical ocean around Izaña, for land pixels measured around Karlsruhe, and Kiruna). For each site a single and representative typical situation is chosen. All of this situations are measurements during morning overpasses in springtime and have an identical satellite zenith angle of about 25.3°.

Above the lower troposphere (above 2–3 km altitude), the propagation of the uncertainties is very similar at the different sites. Atmospheric temperature, thin elevated clouds, and measurement noise (in the upper troposphere) are the dominating uncertainty sources. Atmospheric temperature and measurement noise are mainly random uncertainty sources and we can estimate the random error for the middle/upper tropospheric humidity type 1 product to be about 10 %. The thin elevated clouds occur randomly but also introduce a systematic bias.

In the lower troposphere we predict larger errors for the subtropical ocean scene around Izaña than for the continental scenes around Karlsruhe and Kiruna. This is due to the relatively lower thermal contrast encountered over the ocean as compared to the continent. The surface and boundary layer temperatures for the subtropical ocean around Izaña are about 290 K and 291 K, respectively, i.e. there is no thermal contrast between surface and atmosphere. At the continental sites there is significant thermal contrast: at Karlsruhe the temperatures are 290 K and 276 K for the surface and the boundary layer temperature, respectively, and at Kiruna it is 279 K and 270 K, respectively.

The most important systematic uncertainty source as listed in Table 3 are the spectroscopic parameters. For our assumptions of a 2 % uncertainty in the line intensity and

The MUSICA MetOp/IASI H₂O and δD products

A. Wiegeler et al.

Title Page

Abstract

Introduction

Conclusions

References

Tables

Figures

⏪

⏩

◀

▶

Back

Close

Full Screen / Esc

Printer-friendly Version

Interactive Discussion



a 1 % uncertainty in the line pressure broadening parameters, we estimate a systematic error in the product type 1 H₂O profile of 2 %.

3.2 Characterisation of product type 2: consistent H₂O and δD data

As outlined in Sect. 4.2 of S12, we have to perform an a posteriori processing in order to ensure that the product can be used for water vapour isotopologue research. This a posteriori processing takes care that the humidity and δD product become sensitive to very similar altitude ranges and it reduces the dependency of the retrieved δD values on atmospheric humidity variations. The a posteriori processing is realised by a simple matrix multiplication (see Eq. 20 of S12):

$$\hat{\mathbf{x}}^* = \mathbf{P}^{-1} \mathbf{C} \mathbf{P} (\hat{\mathbf{x}} - \mathbf{x}_a) + \mathbf{x}_a. \quad (6)$$

Here $\hat{\mathbf{x}}$ is the retrieved {ln[H₂O], ln[HDO]}-state, $\hat{\mathbf{x}}_a$ the a priori state, and $\hat{\mathbf{x}}^*$ the a posteriori corrected {ln[H₂O], ln[HDO]}-state. The matrix \mathbf{P} is the transformation matrix of Eq. (2) and \mathbf{C} the correction operator (for the definition of \mathbf{C} please refer to Eq. 14 of S12).

3.2.1 Sensitivity and vertical resolution

The a posteriori corrected kernel for the {humidity, δD}-proxy state is (Eq. 15 of S12):

$$\mathbf{A}'' = \mathbf{C} \mathbf{P} \mathbf{A} \mathbf{P}^{-1}. \quad (7)$$

The rows of \mathbf{A}'' are depicted in Fig. 4. The correction has the desired effects. First, it reduces the cross dependency of humidity on δD (compare bottom left graphs of each group in Figs. 2 and 4), thereby minimizing the dependency of the δD product on atmospheric humidity. Second, it assures that the humidity (or H₂O) product and the δD product represent very similar altitude regions (compare upper left and bottom right kernels of each group in Figs. 2 and 4). This is important, since the added value

The MUSICA MetOp/IASI H₂O and δD products

A. Wiegeler et al.

Title Page

Abstract

Introduction

Conclusions

References

Tables

Figures

◀

▶

◀

▶

Back

Close

Full Screen / Esc

Printer-friendly Version

Interactive Discussion



of δD has to be investigated together with H_2O in form of H_2O -vs.- δD plots, meaning that both products have to be used and have to be representative for the same altitude regions.

This product type 2 is well-suited for atmospheric water isotopologue research. It has a sensitivity that is limited to the middle troposphere (between 2–8 km altitude) and offers typically about 0.7 degrees of freedom for signal (DOFs, see right column of Table 1).

3.2.2 Propagation of uncertainties

The propagation of the uncertainties can be calculated by (Eq. 19 of S12):

$$\mathbf{S}_e'' = \mathbf{CPGK}_p \mathbf{e}_p \mathbf{e}_p^T \mathbf{K}_p^T \mathbf{G}^T \mathbf{P}^T \mathbf{C}^T. \quad (8)$$

Figure 5 shows how the uncertainties propagate into the type 2 products of H_2O (upper panels) and δD (bottom panels). The typical random error for H_2O is 3–10 % and is dominated by the atmospheric temperature uncertainties and by not well identified thin elevated clouds. The H_2O errors are a bit larger for Izaña than for the other two locations. This is due to the fact that over the subtropical ocean there is a better sensitivity with respect to δD than for the mid-latitudinal or polar land scenes. Reducing the H_2O sensitivity to the low δD sensitivity also reduces the sensitivity with respect to uncertainties (at Karlsruhe and Kiruna more than at Izaña, compare the groups of kernels in Fig. 4).

The δD error is clearly dominated by the dependency on atmospheric humidity. One and the same atmospheric δD value is observed by IASI with an uncertainty of more than 40%, in case the observations are made for different atmospheric humidity scenarios (dry vs. humid conditions). If there are independent H_2O measurements available, we can simulate this error by means of the averaging kernel (bottom left graphs of each group in Fig. 4) and eventually correct it. Please note that this error is even larger, if we do not apply the a posteriori correction. Furthermore, measurement noise and thin elevated clouds are important and can sum up to a random error of 15–25%.

The MUSICA MetOp/IASI H_2O and δD products

A. Wiegeler et al.

Title Page

Abstract

Introduction

Conclusions

References

Tables

Figures

◀

▶

◀

▶

Back

Close

Full Screen / Esc

Printer-friendly Version

Interactive Discussion



ground pixel is within a box of approximately 110 km × 110 km bounding the location of the corresponding FTIR instrument to the south. The shift to the south is performed since the FTIR measurements are pointing to the sun in southern directions.

We tried to qualitatively assess the validity of these coincidence criteria. For this purpose we use the variation as seen in the FTIR data for estimating the temporal inhomogeneity, and the variations as seen in the IASI data for estimating the spatial inhomogeneity. The scatter ($1 - \sigma$ standard deviation) in the FTIR data observed during the two hours around local noon are due to FTIR random errors and temporal variations in the atmosphere. We can use it as an upper limit of the temporal inhomogeneity. Similarly we use the scatter between the IASI data corresponding to all morning overpass pixels that fall in our validation box as an upper limit of the spatial inhomogeneity (the scatter is due to IASI random errors and inhomogeneity in the atmospheric fields). These inhomogeneity values are resumed in Table 3 and are calculated from all available FTIR and IASI data (not only the coincidence data). They document how a temporal and/or spatial mismatch between the FTIR and the IASI observations can affect our comparison study.

4.2 Comparing two remote sensing products

The averaging kernels and thus the altitude resolution and sensitivity for the FTIR and IASI products are different. For product type 1 (vertically resolved H₂O profiles) the IASI retrieval yields degrees of freedom for signal (DOFs) of about 4 and best altitude resolutions in the middle troposphere. The FTIR products for the Izaña, Karlsruhe, and Kiruna sites have DOFs of about 2.5–3 and show best vertical resolution close to the surface and reasonable sensitivity up to the middle/upper troposphere. For product type 2 (consistent H₂O and δD data) the situation is vice versa. There, the FTIR products offer better sensitivity (DOFs of 1.5–1.7) than the IASI product (DOFs of about 0.7).

The MUSICA MetOp/IASI H₂O and δD products

A. Wiegeler et al.

Title Page

Abstract

Introduction

Conclusions

References

Tables

Figures



Back

Close

Full Screen / Esc

Printer-friendly Version

Interactive Discussion



These differences limit the comparability of the IASI and FTIR remote sensing products. We can estimate the effect of the different averaging kernels on the comparability:

$$\mathbf{S}_c = (\mathbf{A}_I - \mathbf{A}_F)\mathbf{S}_a(\mathbf{A}_I - \mathbf{A}_F)^T \quad (9)$$

where \mathbf{S}_a is the atmospheric covariance matrix and \mathbf{A}_I and \mathbf{A}_F the averaging kernels for the IASI and FTIR products, respectively. As metric for the comparability of the two instruments we work with the square root values of the diagonal elements of \mathbf{S}_c and calculate the ratio with respect to the square root of the diagonal elements of atmospheric covariance matrix \mathbf{S}_a . The obtained value, $\sqrt{\text{diag}(\mathbf{S}_c)}/\sqrt{\text{diag}(\mathbf{S}_a)}$, informs about the portion of the atmospheric variability that cannot be compared, i.e., it appears as scatter between the FTIR and IASI products although both instruments and retrievals work perfectly and detect the same air mass. If it is 100 %, we cannot compare the products (the kernels are very different), if it is very low, the kernels of both instruments are quite similar.

4.3 H₂O profiles (product type 1)

The comparability values $\sqrt{\text{diag}(\mathbf{S}_c)}/\sqrt{\text{diag}(\mathbf{S}_a)}$ for product type 1 are plotted in the left graph of Fig. 6. We find that the IASI and FTIR products are well comparable between 2.5 and 8 km, for the subtropical ocean scene around Izaña, and between 0.5 and 5 km, for the continental scenes at Karlsruhe and Kiruna, respectively. For these altitudes we estimate $\sqrt{\text{diag}(\mathbf{S}_c)}/\sqrt{\text{diag}(\mathbf{S}_a)} < 40\%$. A comparison for altitudes above 13 km makes few sense, since there both IASI and FTIR sensitivities are rather low and both sensors report mainly the apriori assumptions.

For the coincidences between IASI and FTIR, direct correlations of water vapour are plotted in Fig. 7 for all three FTIR measurement sites and three different altitudes. The altitudes are selected according to the comparability estimations as presented in Fig. 6. The apriori values are figured as red stars and the numbers of coincidences (N) and correlation coefficients (R^2) are given in each graph. At Izaña and Kiruna we compare IASI data measured between 2007 and 2012 and at Karlsruhe between 2010 and

The MUSICA MetOp/IASI H₂O and δD products

A. Wiegele et al.

Title Page

Abstract

Introduction

Conclusions

References

Tables

Figures

◀

▶

◀

▶

Back

Close

Full Screen / Esc

Printer-friendly Version

Interactive Discussion



2012 (the Karlsruhe FTIR instrument started its operation in 2010). There are several thousand numbers of coincidences, except for Kiruna where the number is smaller due to the lack of FTIR measurements during polar winter.

We find a very good agreement between the two datasets. Both instruments see very consistent deviations from the apriori values. This is especially true for the middle and upper troposphere. At lower altitudes the correlations tend to be slightly weaker. In addition, we find no significant systematic difference between both instruments. The common apriori values (red stars) fit well into the correlated data points.

The here observed good agreement is in consistency with previous studies that compared IASI H₂O profile products to meteorological radiosonde data (Pougatchev et al., 2009; Schneider and Hase, 2011; August et al., 2012).

4.4 Consistent H₂O and δD (product type 2)

The right side of Fig. 6 depicts the comparability values $\sqrt{\text{diag}(\mathbf{S}_c)} / \sqrt{\text{diag}(\mathbf{S}_a)}$ as calculated by Eq. (9) as solid lines. For Izaña these values are smaller than 50 % above 4 km altitude, whereby the respective IASI kernels show maximum sensitivity around 4–5 km altitude (see bottom right panel of Fig. 4), recommending a product comparison around 5 km. For Karlsruhe and Kiruna, the comparability values (solid line in Fig. 6) get smaller than 50 % already above 2 km altitude. In addition, in the Karlsruhe and Kiruna kernels of Fig. 4 we observe that there are IASI sensitivity maxima around 1–3 km, thus, at these two locations a comparison around 2.5 km would be most interesting.

For product type 2 the differences between the IASI and FTIR kernels are larger than for product type 1, whereby the FTIR data offer significantly more DOFs than the IASI data. Under these circumstances we can convolve the FTIR data with the IASI averaging kernels, which modifies Eq. (9):

$$\mathbf{S}_c^{\text{sm}} = (\mathbf{A}_I - \mathbf{A}_I \mathbf{A}_F) \mathbf{S}_a (\mathbf{A}_I - \mathbf{A}_I \mathbf{A}_F)^T. \quad (10)$$

**The MUSICA
MetOp/IASI H₂O and
δD products**

A. Wiegele et al.

Title Page	
Abstract	Introduction
Conclusions	References
Tables	Figures
◀	▶
◀	▶
Back	Close
Full Screen / Esc	
Printer-friendly Version	
Interactive Discussion	



The respective comparability values $\sqrt{\text{diag}(\mathbf{S}_c^{\text{sm}})}/\sqrt{\text{diag}(\mathbf{S}_a)}$ are plotted as dotted line in the right panel of Fig. 6. The smoothing of the FTIR data with the IASI kernels improves the comparability. Now we get values of about 15 % for the altitudes that are interesting at Karlsruhe and Kiruna (altitudes around 2.5 km) and of about 10 % for 5 km altitude at Izaña.

4.4.1 δD correlations

Figure 8 shows the correlations of the IASI and FTIR type 2 δD products for the three different sites and for the aforementioned interesting altitudes. Here we work with the FTIR product that has been smoothed with the IASI kernels. We find a reasonable agreement and correlation coefficients R^2 of about 0.75–0.90. The graphs demonstrate that IASI and FTIR see very similar atmospheric δD variations. Furthermore, we observe no significant systematic difference between both datasets (the common a priori values fit well to the correlated data points, see black stars). We observe a scatter between the FTIR and IASI data of less than 15–25 %. A part of this scatter is expected to be due to the differences between the IASI and FTIR averaging kernels (calculations according to Eq. 10) and most of this scatter is due to errors in the IASI and FTIR data. Assuming negligible errors in the FTIR data no mismatch in the airmass as detected by the FTIR and IASI, we can use this scatter as a conservative estimate of the IASI δD random error. Indeed, the observed scatter of 15–25 % is in excellent agreement with our estimations as depicted in the bottom panels of Fig. 5. Please note that the error due to cross dependence on humidity is an issue of the averaging kernels and its remaining effect on the comparability is accounted for in Eq. (10).

There are several studies that have shown similar correlation plots between δD measurements obtained by two different instruments (e.g., Schneider and Hase, 2011; Boesch et al., 2013) or between δD measurements and model simulations (e.g., Schneider et al., 2010; Lacour et al., 2012). Such correlations can document that the investigated instrument is able to observe atmospheric δD signals. However, in the

The MUSICA MetOp/IASI H₂O and δD products

A. Wiegele et al.

Title Page

Abstract

Introduction

Conclusions

References

Tables

Figures

◀

▶

◀

▶

Back

Close

Full Screen / Esc

Printer-friendly Version

Interactive Discussion



FTIR δD -vs.- H_2O plots agree even better with the respective IASI plots (second row of graphs) than the unsmoothed FTIR curves (upper row).

5 Conclusions

We perform a theoretical and empirical quality assessment study of the MUSICA MetOp/IASI water vapour isotopologue data. We identify two types of products. Type 1 are vertically resolved tropospheric H_2O profiles. Type 2 are consistent middle tropospheric H_2O and δD data and can be used for water vapour isotopologue research.

Our theoretical assessments reveal that the IASI H_2O profiles (product type 1) can resolve tropospheric vertical structures of about 4 km, i.e., the full-width-half-maximum, FWHM, of the averaging kernels is typically 4 km. The random error of these profile data is generally smaller than 10 %. Only in the lower troposphere it can be a bit larger, in particular for observational scenes with weak thermal contrast (small difference between the surface temperature and the temperature in the lowermost atmospheric layers). The systematic errors due to the assumed uncertainties in the spectroscopic parameters are estimated to be 2 %.

In the middle troposphere IASI can also consistently detect H_2O and δD data (product type 2). We estimate that despite the a posteriori correction method there remains a cross dependency on humidity, which can cause δD errors as large as 40 %. Beyond this cross dependency we estimate δD random errors of about 15–25 %. For the H_2O product type 2 product we estimate a random error of 3–10 %.

For our empirical quality study, we use the MUSICA NDACC/FTIR data that correspond to observations that are made in coincidence to IASI overpasses at three different sites. We find that the H_2O profiles (product type 1) as observed by FTIR and IASI are in good agreement. This confirms previous studies of IASI H_2O profile products.

Good agreement is also found for the H_2O and δD product type 2 data. We can prove that IASI detects almost the same middle tropospheric δD variations as the FTIR.

The MUSICA MetOp/IASI H_2O and δD products

A. Wiegele et al.

Title Page

Abstract

Introduction

Conclusions

References

Tables

Figures

◀

▶

◀

▶

Back

Close

Full Screen / Esc

Printer-friendly Version

Interactive Discussion



Furthermore, the scatter we observe between the two datasets excellently confirms our error estimations.

In order to demonstrate that the IASI and the FTIR δD observations provide consistent scientifically useful information we compare δD -vs.- H_2O plots. We show that the IASI δD data add information to the IASI H_2O measurements and that this added information is in agreement with the information that the FTIR δD data add to the FTIR H_2O measurements. This kind of comparison proves that the water vapour isotopologue data produced within MUSICA from METOP/IASI and NDACC/FTIR observations contain consistent scientifically relevant information.

Our study is made for three rather different geophysical locations: the subtropics, the mid-latitudes, and the polar regions. Therefore, we conclude that the results are globally valid and provide a first clear theoretical and empirical proof of IASI's capability for a global observation of middle tropospheric water vapour isotopologues on a daily timescale and with a quality that is sufficiently high for water cycle research purposes.

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The MUSICA MetOp/IASI H_2O and δD products

A. Wiegele et al.

Title Page

Abstract

Introduction

Conclusions

References

Tables

Figures



Back

Close

Full Screen / Esc

Printer-friendly Version

Interactive Discussion



References

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The MUSICA MetOp/IASI H₂O and δD products

A. Wiegele et al.

Title Page

Abstract

Introduction

Conclusions

References

Tables

Figures

◀

▶

◀

▶

Back

Close

Full Screen / Esc

Printer-friendly Version

Interactive Discussion



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The MUSICA
MetOp/IASI H₂O and
 δ D products

A. Wiegele et al.

Title Page

Abstract

Introduction

Conclusions

References

Tables

Figures

◀

▶

◀

▶

Back

Close

Full Screen / Esc

Printer-friendly Version

Interactive Discussion



**The MUSICA
MetOp/IASI H₂O and
δD products**

A. Wiegele et al.

Title Page

Abstract

Introduction

Conclusions

References

Tables

Figures

◀

▶

◀

▶

Back

Close

Full Screen / Esc

Printer-friendly Version

Interactive Discussion



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AMTD

7, 3915–3952, 2014

The MUSICA MetOp/IASI H_2O and δD products

A. Wiegele et al.

Title Page

Abstract

Introduction

Conclusions

References

Tables

Figures

◀

▶

◀

▶

Back

Close

Full Screen / Esc

Printer-friendly Version

Interactive Discussion



**The MUSICA
MetOp/IASI H₂O and
 δ D products**

A. Wiegele et al.

Title Page

Abstract

Introduction

Conclusions

References

Tables

Figures

◀

▶

◀

▶

Back

Close

Full Screen / Esc

Printer-friendly Version

Interactive Discussion

**Table 1.** Mean and standard deviation of degree of freedom of signal (DOFs) for the two product types and the three locations.

location	product type 1	product type 2
Izaña	4.15 ± 0.10	0.74 ± 0.10
Karlsruhe	3.78 ± 0.30	0.74 ± 0.20
Kiruna	3.31 ± 0.22	0.57 ± 0.18

The MUSICA MetOp/IASI H₂O and δ D products

A. Wiegeler et al.

[Title Page](#)
[Abstract](#)
[Introduction](#)
[Conclusions](#)
[References](#)
[Tables](#)
[Figures](#)
[Back](#)
[Close](#)
[Full Screen / Esc](#)
[Printer-friendly Version](#)
[Interactive Discussion](#)


Table 2. Uncertainty sources and expected magnitudes used for error estimation of the IASI retrieval.

uncertainty source	expected magnitude
noise	5 %
swath angle	0.01 rad
line intensity H ₂ O	2 %
line intensity HDO	2 %
line intensity CH ₄	2 %
line intensity N ₂ O	2 %
pressure broadening H ₂ O	1 %
pressure broadening HDO	1 %
emissivity	5 %
surface temperature	2 K
atmospheric temperature (< 2 km)	2 K
atmospheric temperature (2–5 km)	1 K
atmospheric temperature (5–10 km)	1 K
atmospheric temperature (> 10 km)	1 K
ground altitude	20 m
cloud at 1 km (optically thick)	5 % cloud coverage
thin cloud at 10 km	transmittance 98 %

**The MUSICA
MetOp/IASI H₂O and
 δ D products**

A. Wiegele et al.

Title Page

Abstract

Introduction

Conclusions

References

Tables

Figures



Back

Close

Full Screen / Esc

Printer-friendly Version

Interactive Discussion

**Table 3.** Estimated potential temporal and spatial mismatch.

	H ₂ O [%]	δ D [%]
temporal	4.1	7.5
spatial	19.3	17.5

The MUSICA MetOp/IASI H₂O and δD products

A. Wiegele et al.

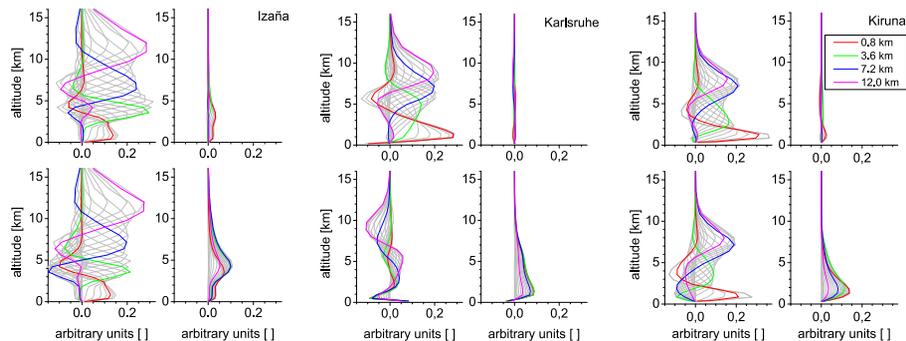


Fig. 1. Example of row kernels in the $\{\ln[\text{H}_2\text{O}], \ln[\text{HDO}]\}$ -basis. There are three groups of graphs: left group for Izaña, central group for Karlsruhe, and right group for Kiruna. The upper panels display how the retrieved $\ln[\text{H}_2\text{O}]$ is affected by actual $\ln[\text{H}_2\text{O}]$ variations (left panel of each group) and by actual $\ln[\text{HDO}]$ variations (right panel of each group). The lower panels display the same for the retrieved $\ln[\text{HDO}]$.

[Title Page](#)[Abstract](#)[Introduction](#)[Conclusions](#)[References](#)[Tables](#)[Figures](#)[◀](#)[▶](#)[◀](#)[▶](#)[Back](#)[Close](#)[Full Screen / Esc](#)[Printer-friendly Version](#)[Interactive Discussion](#)

The MUSICA MetOp/IASI H₂O and δD products

A. Wiegeler et al.

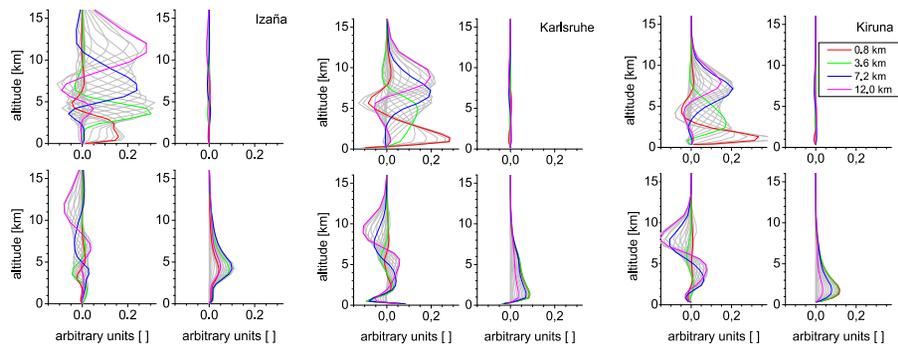


Fig. 2. Same as Fig. 1 but for the kernels in the {humidity, δD }-proxy state basis.

Title Page

Abstract

Introduction

Conclusions

References

Tables

Figures

◀

▶

◀

▶

Back

Close

Full Screen / Esc

Printer-friendly Version

Interactive Discussion



The MUSICA MetOp/IASI H₂O and δD products

A. Wiegeler et al.

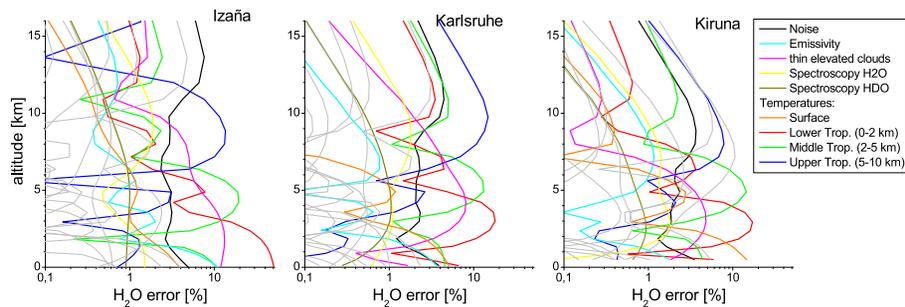


Fig. 3. Error estimation for water vapour (product type 1) at all measurement sites. The assumed uncertainty sources are detailed in Table 2. Minor error sources are figured in gray lines.

Title Page

Abstract

Introduction

Conclusions

References

Tables

Figures

◀

▶

◀

▶

Back

Close

Full Screen / Esc

Printer-friendly Version

Interactive Discussion



The MUSICA MetOp/IASI H₂O and δ D products

A. Wiegeler et al.

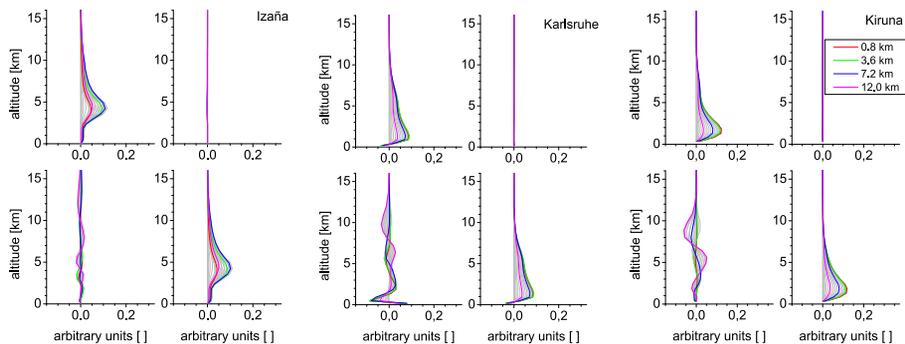


Fig. 4. Same as Fig. 2 but for the a posteriori corrected {humidity, δ D}-proxy state (a posteriori correction according to Eq. 7).

[Title Page](#)[Abstract](#)[Introduction](#)[Conclusions](#)[References](#)[Tables](#)[Figures](#)[⏪](#)[⏩](#)[◀](#)[▶](#)[Back](#)[Close](#)[Full Screen / Esc](#)[Printer-friendly Version](#)[Interactive Discussion](#)

The MUSICA MetOp/IASI H₂O and δ D products

A. Wiegeler et al.

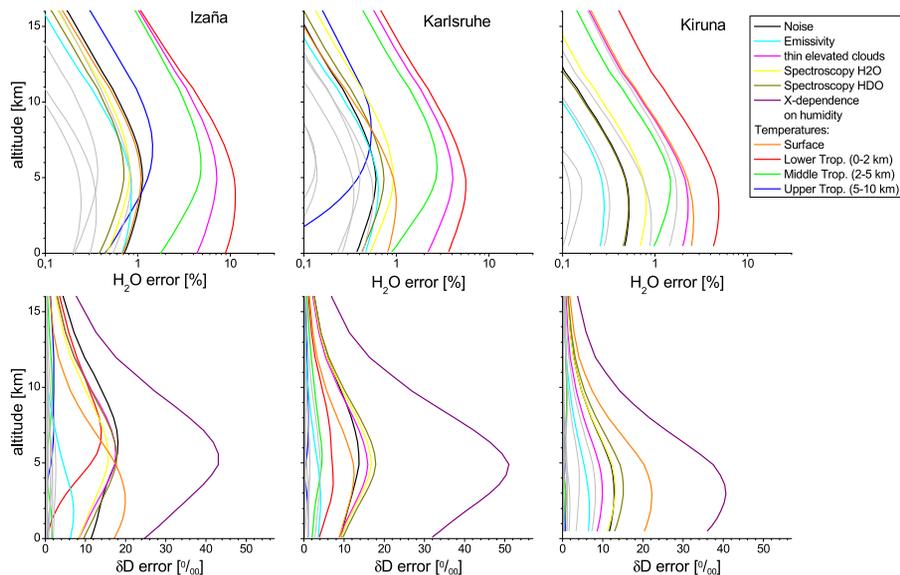


Fig. 5. Error estimation for humidity and the isotopologue at all measurement sites. The estimated and used magnitudes can be found in Table 2. Minor error sources are figured in grey lines and are included in the total error.

Title Page

Abstract

Introduction

Conclusions

References

Tables

Figures

◀

▶

◀

▶

Back

Close

Full Screen / Esc

Printer-friendly Version

Interactive Discussion



The MUSICA MetOp/IASI H₂O and δ D products

A. Wiegele et al.

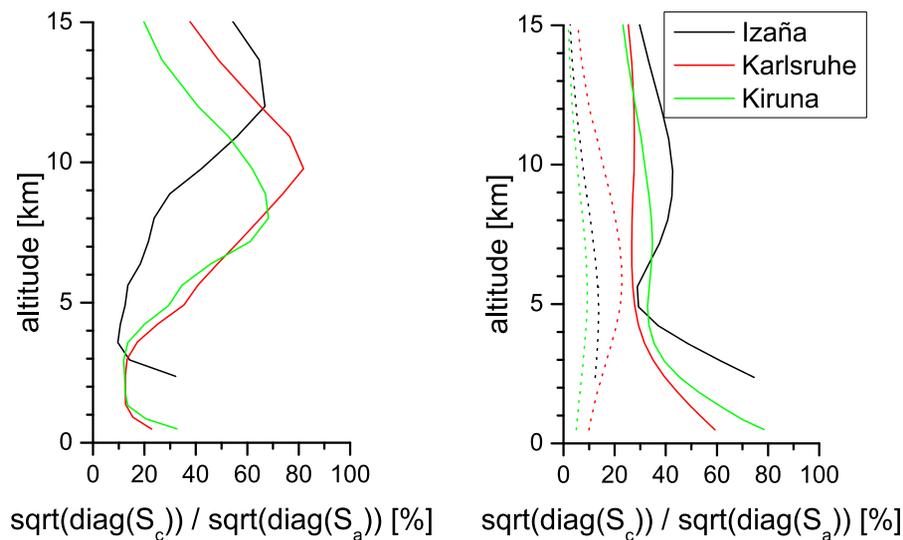


Fig. 6. Level of comparability between both remote sensing datasets at the three different locations. Left panel: H₂O profile product (product type 1), \mathbf{S}_c calculations according to Eq. (9); Right panel: consistent humidity and δ D data (product type 2), solid lines for \mathbf{S}_c calculations according to Eq. (9) and dashed lines for \mathbf{S}_c^{sm} calculations according to Eq. (10).

The MUSICA MetOp/IASI H₂O and δD products

A. Wiegele et al.

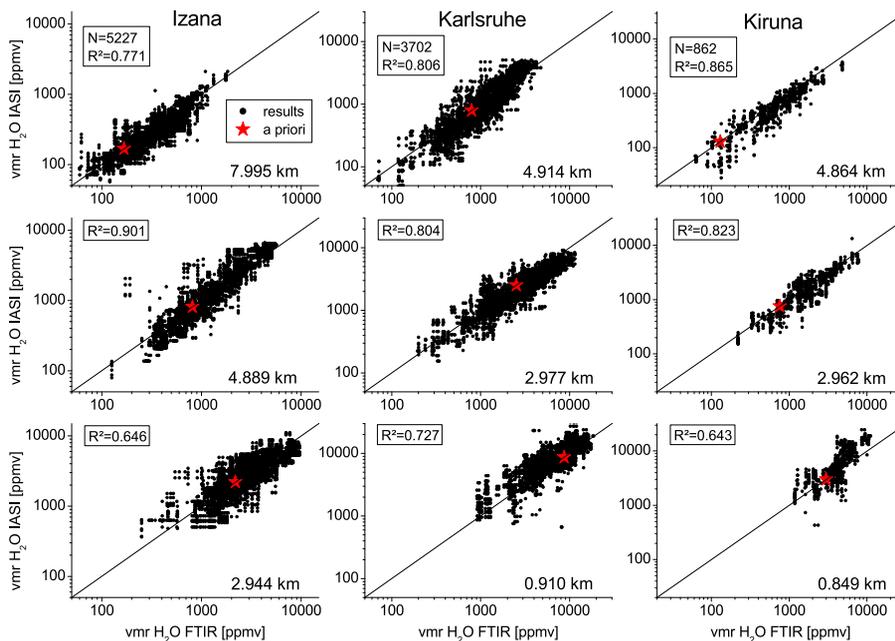


Fig. 7. Correlation between the FTIR and IASI H₂O profile data (product type 1) for three different altitudes and the three locations. The chosen levels depend on the altitude range of best comparability (Fig. 6). The a priori mixing ratios are denoted by red stars and the 1-to-1 diagonal is indicated as black line.

Title Page

Abstract

Introduction

Conclusions

References

Tables

Figures

◀

▶

◀

▶

Back

Close

Full Screen / Esc

Printer-friendly Version

Interactive Discussion



The MUSICA MetOp/IASI H₂O and δ D products

A. Wiegele et al.

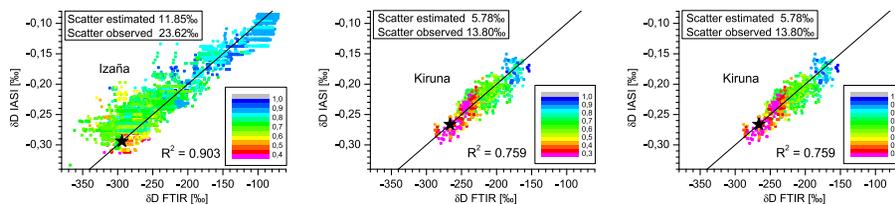


Fig. 8. Correlation between the IASI and smoothed FTIR δ D data. Colors denote the individual IASI DOFs, the black star marks the a priori, and the black line shows the 1-to-1 diagonal.

Title Page

Abstract

Introduction

Conclusions

References

Tables

Figures

◀

▶

◀

▶

Back

Close

Full Screen / Esc

Printer-friendly Version

Interactive Discussion



The MUSICA MetOp/IASI H₂O and δD products

A. Wiegeler et al.

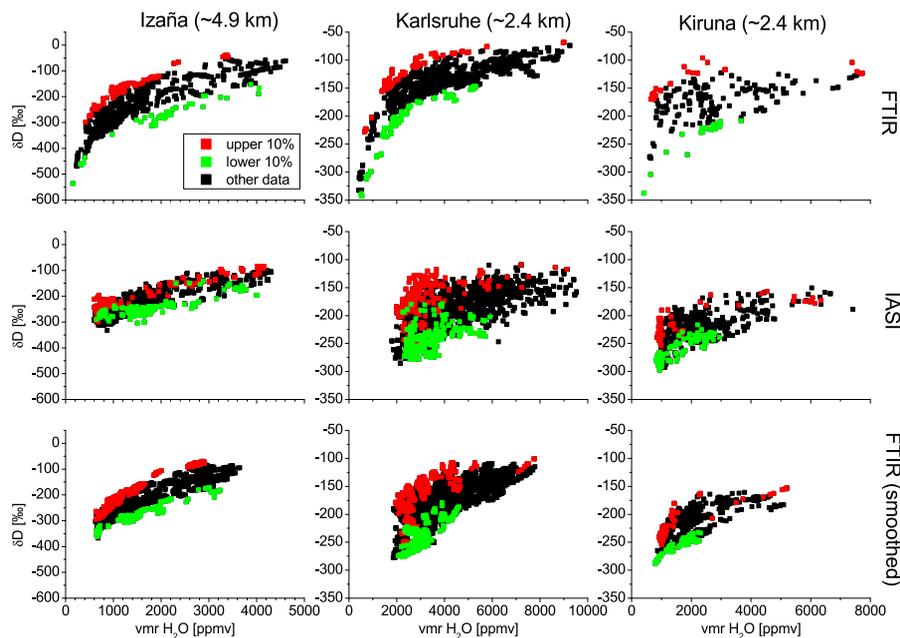


Fig. 9. H₂O-vs.- δD plots for coincident FTIR and IASI measurements for the three locations. Plotted are from the top to the bottom, the FTIR data, the IASI data, and FTIR data smoothed with the IASI averaging kernels. The color code figures the upper 10% and lower 10% of δD values as identified in the FTIR data.